

Trustworthy Graph Neural Networks

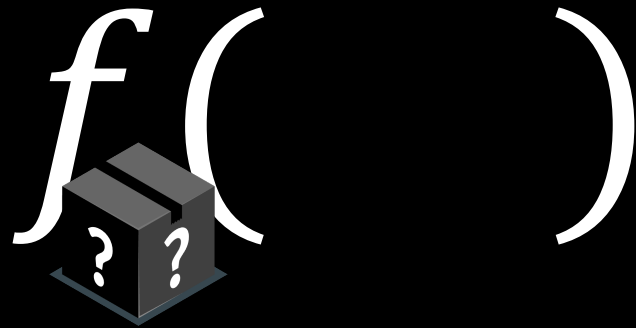
Aleksandar Bojchevski

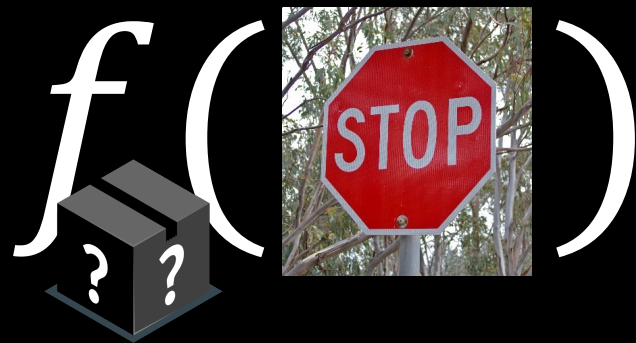
ICERM – Applied and Computational Discrete Algorithms in AI and Data Science

Based on joint work with S. Zargarbashi, S. Akhondzadeh, S. Antonelli.

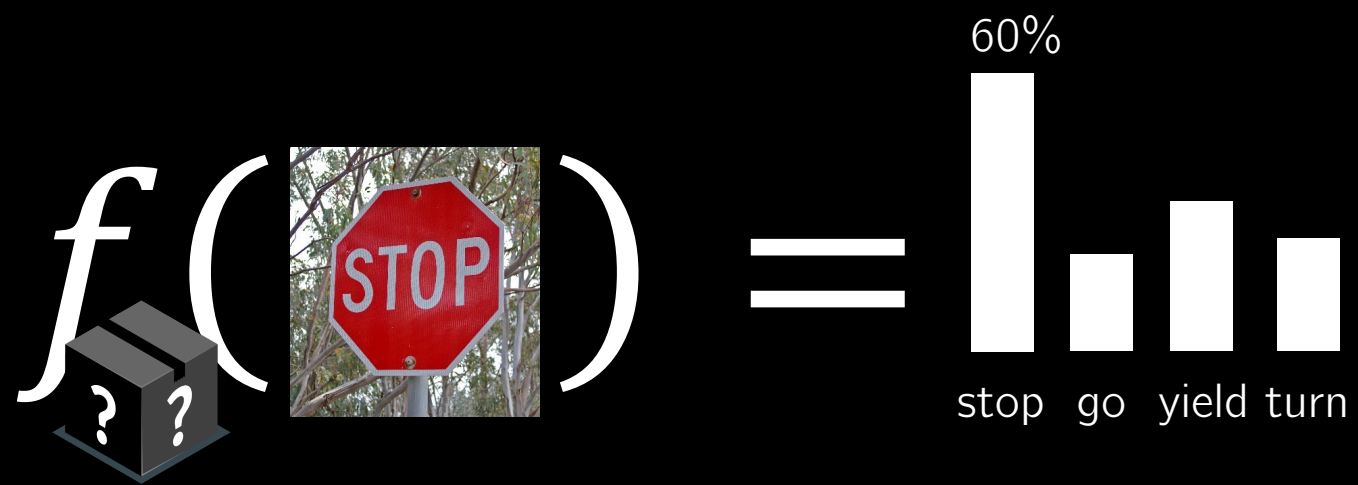
How reliable is the black box?

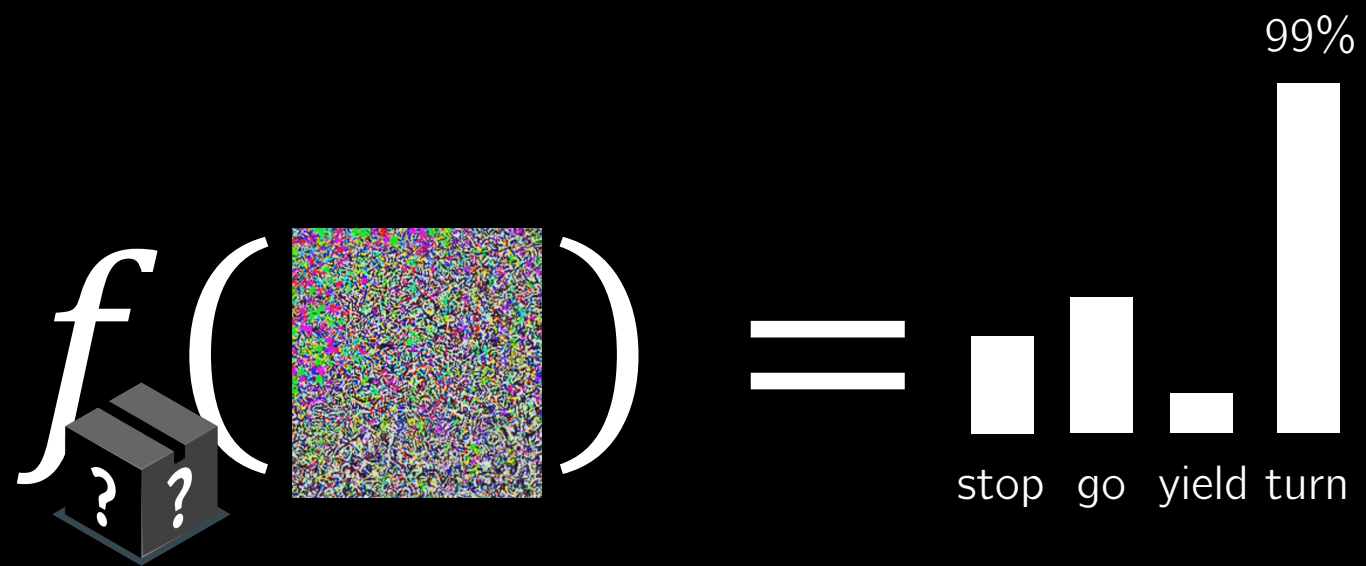






$$f(\text{? ? } \text{STOP}) = \text{stop}$$





Uncertainty quantification

Should we trust a prediction with 60% confidence?

How about 99%?

Is it calibrated? $\mathbb{P}(\text{correct} \mid \text{confidence} = \alpha) = \alpha, \forall \alpha$

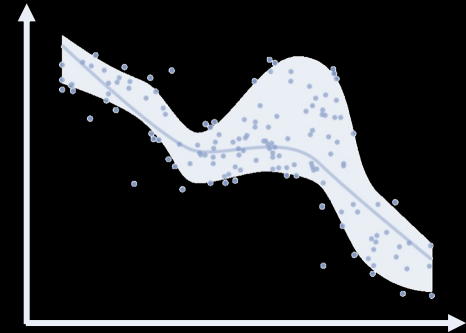
Most models are not!

Conformal prediction

Output a **set** (or interval), larger set $\Rightarrow$ more uncertain

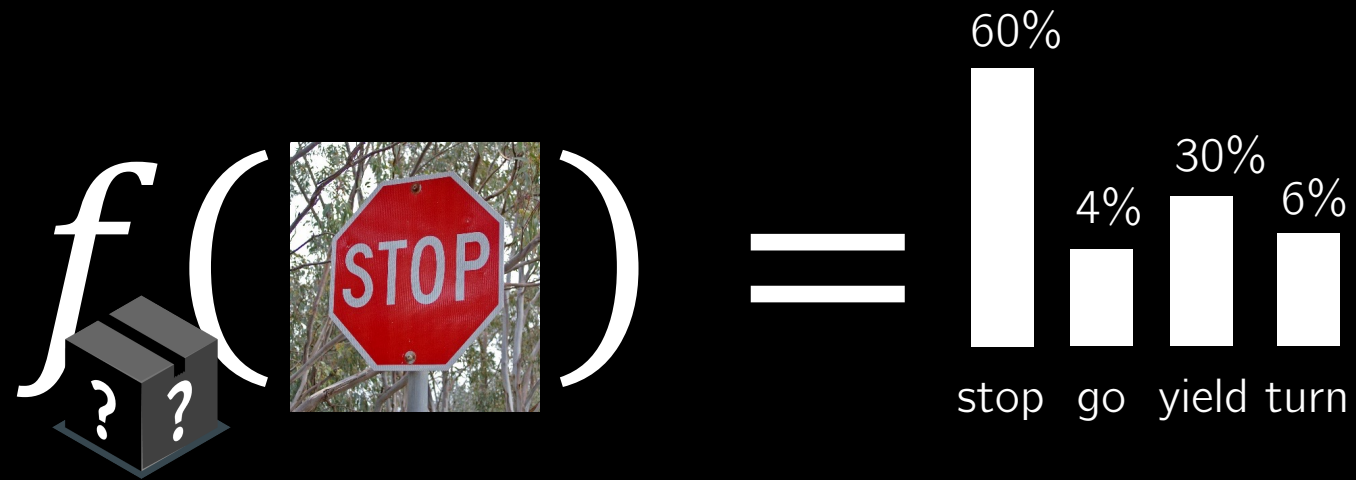
$$\mathcal{C}(\text{??}) = \{1, 7\}$$

$$\mathcal{C}(8) = \{8\}$$



Distribution-free guarantee that $\mathbb{P}(y_{\text{true}} \in \mathcal{C}(\mathbf{x})) \geq 1 - \alpha$

Constructing the sets

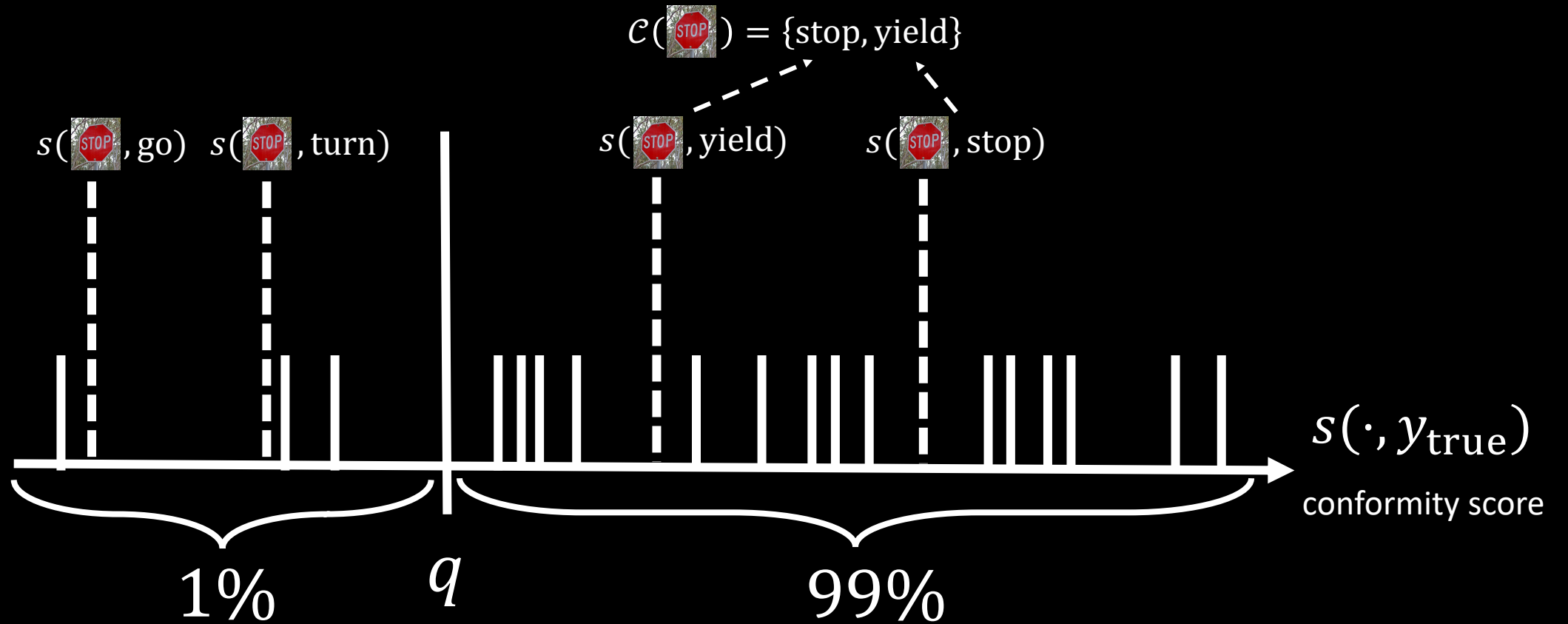


$$\mathbb{P}(y_{\text{true}} \in \{\text{stop}, \text{yield}\}) \neq 0.9$$

Algorithm

1. Define a conformity score function $s(\mathbf{x}, y)$
2. Compute a quantile threshold q on calibration data
3. Output the set $\mathcal{C}(\mathbf{x}) = \{y : s(\mathbf{x}, y) \geq q\}$

Algorithm



Exchangability

Only assumption is $\mathbb{P}(Z_1, \dots, Z_n, Z_{n+1}) = \mathbb{P}(Z_{\pi(1)}, \dots, Z_{\pi(n)}, Z_{\pi(n+1)})$ for $Z_i = (\mathbf{x}_i, y_i)$ and all permutations π , i.e. order does not matter

Weaker than the i.i.d. assumption (i.i.d. $\Rightarrow$ exchangability).

Each rank order equally likely

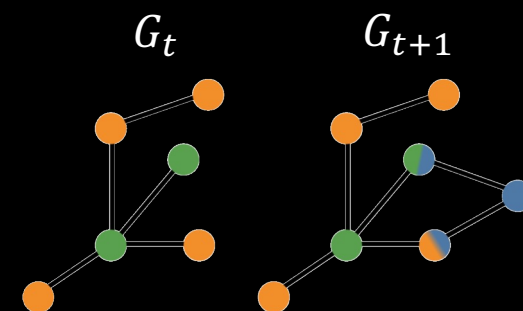
Exchangability on graphs

Transductive: given entire graph + exchangeable calibration labels
⇒ Scores are exchangeable for any permutation-equivariant model

Inductive: new nodes/edges arrive over time

1. Calibrate at time t
2. Construct sets at $t' > t$

⇒ Scores are **not** exchangeable even if the data is



Conformal inductive GNNs



Fix 1: Time-dependent threshold for each t' , recovers coverage guarantee for node exchangeable graphs.

But, node exchangeable $\Leftrightarrow$ graphons $\Leftrightarrow$ dense or empty

Fix 2: Time-dependent and node-frequency **weighted** threshold, recovers coverage guarantee for edge exchangeable graphs

Designing the score

Guarantee holds for **any** score $s(\mathbf{x}, y)$

Desiderata for $\mathcal{C}(\mathbf{x})$:

- **efficient**: size as small as possible
- **adaptive**: smaller for easy and larger for harder cases
- as many **singletons** as possible

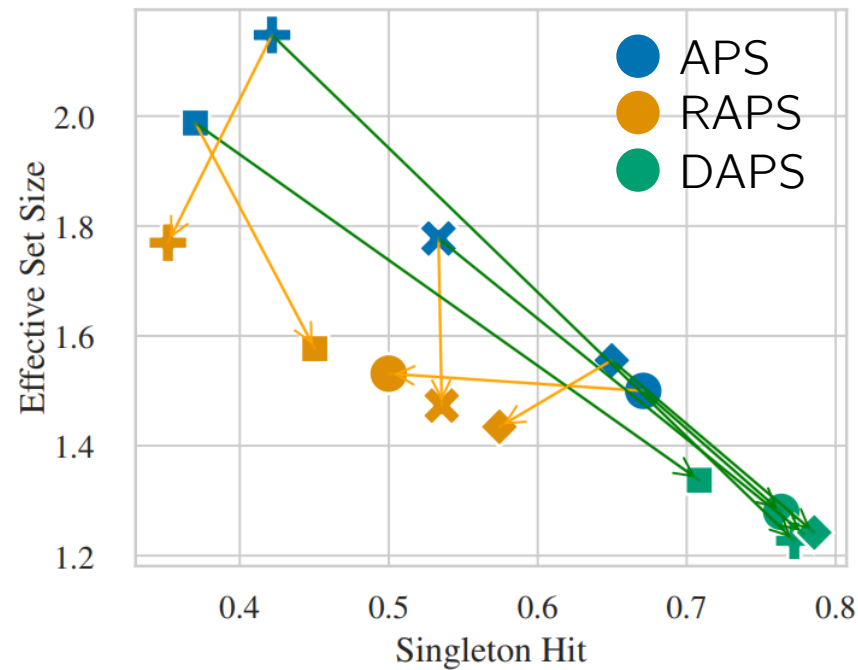
DAPS: Diffused Adaptive Prediction Sets

To improve the score of x use other scores from its neighborhood

$$\hat{s}(\mathbf{x}, y) = (1 - \lambda) \cdot s(\mathbf{x}, y) + \frac{\lambda}{|\mathcal{N}|} \sum_{\mathbf{x}' \in \mathcal{N}(\mathbf{x})} s(\mathbf{x}', y)$$

Theorem (inf.): Under homophily $\hat{s}$ leads to smaller sets

DAPS: Your neighbors improve you



Conformal risk control

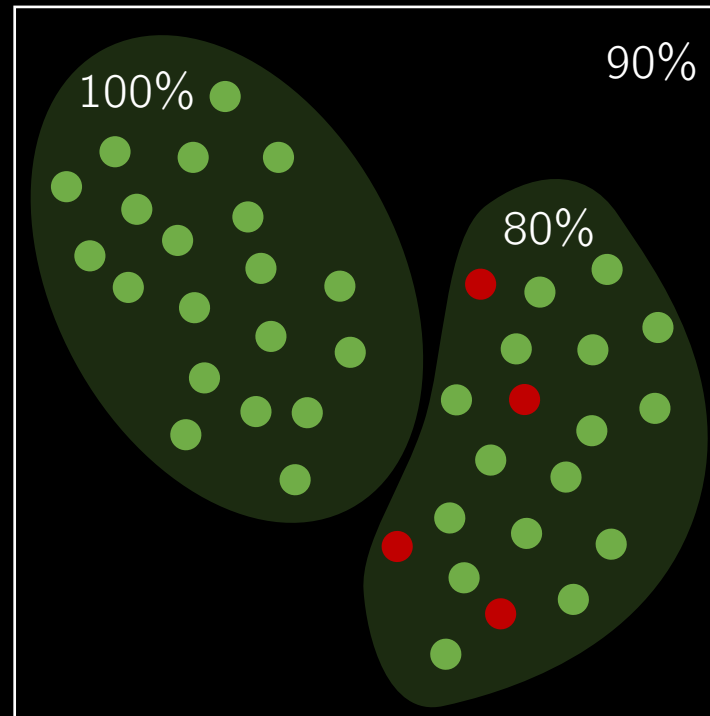
Guarantee $\mathbb{E}[\text{false negatives}] \leq 0.01$



Marginal vs. conditional

$$\mathbb{P}(y_{\text{true}} \in \mathcal{C}(\mathbf{x}))$$

$$\mathbb{P}(y_{\text{true}} \in \mathcal{C}(\mathbf{x}) \mid \mathbf{x} = \mathbf{x})$$



Intermediate summary

You can construct sets that promise to cover the true label

$$f(\text{? ? } \text{STOP}) = \text{stop}$$

$$f(\text{? ?}(\text{STOP})) = \text{stop}$$

$$f(\text{? ?}(\text{STOP})) = \text{go}$$

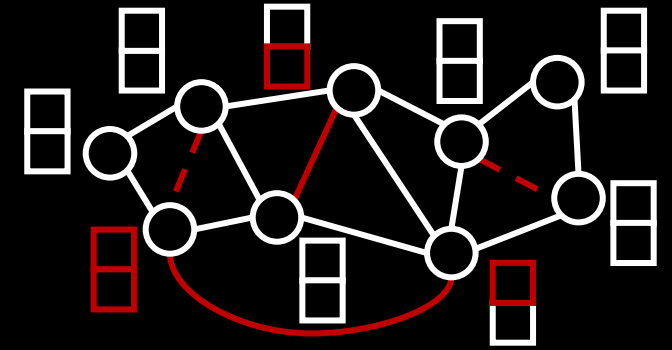
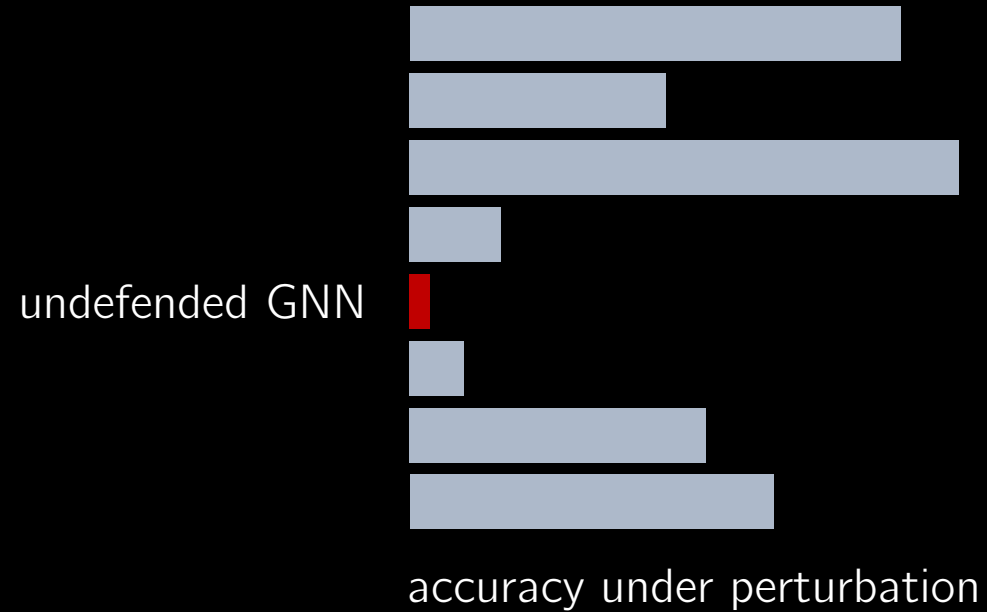
$$f(\text{? ?}(\text{STOP})) = \text{stop}$$

$$f(\text{? ?}(\text{STOP} + \text{noise})) = \text{go}$$

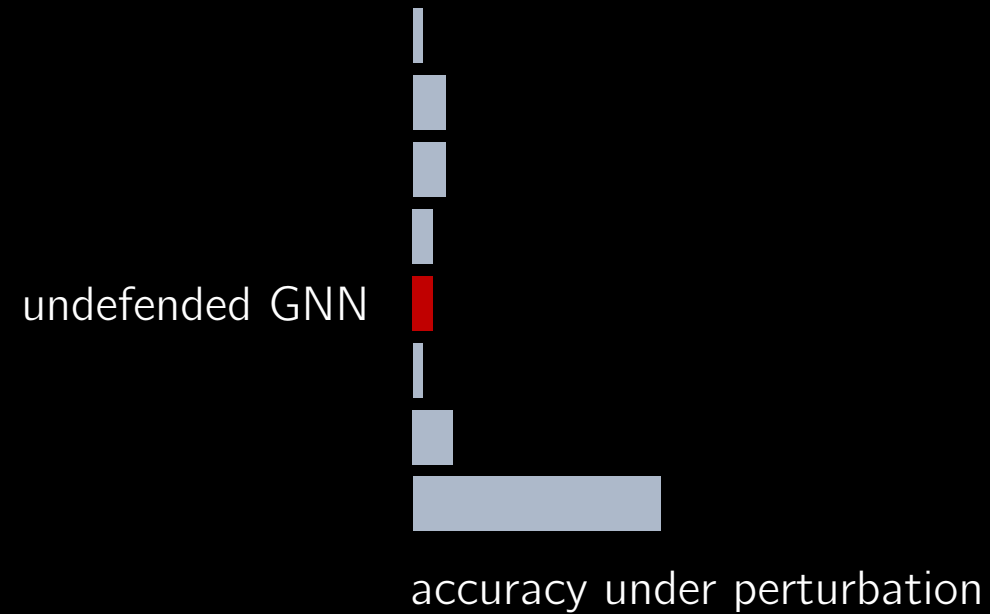
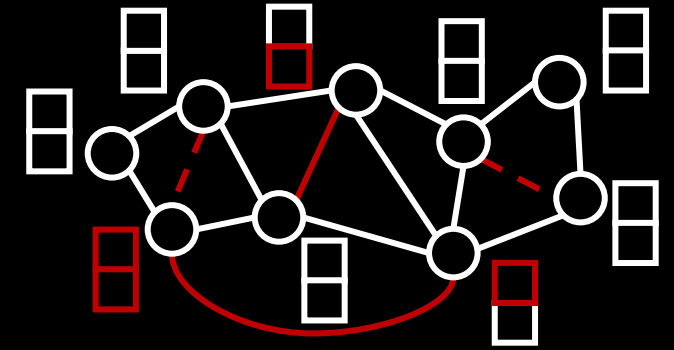
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Are defenses robust?



Are defenses robust? **No!**



Bitter lesson: Defenses are easily broken

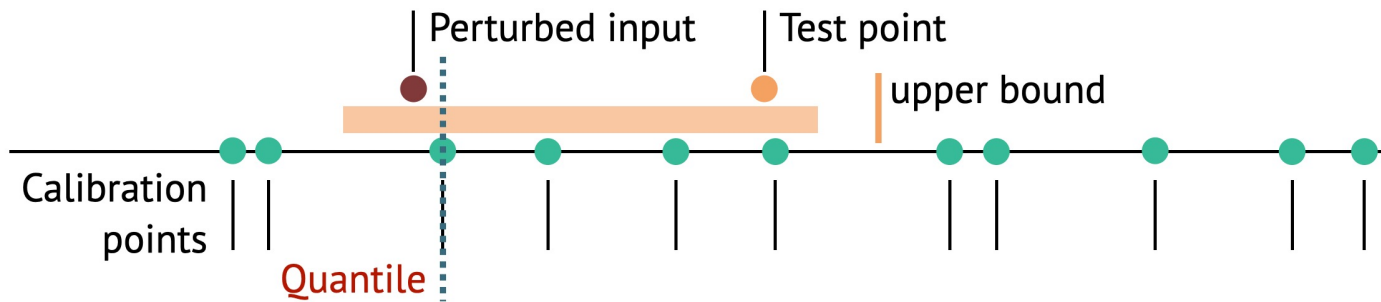
Adversarial Examples Are Not Easily Detected: Bypassing Ten Detection Methods by Carlini and Wagner broke 10 defenses.

Obfuscated Gradients Give a False Sense of Security: Circumventing Defenses to Adversarial Examples by Athalye et al. broke 7 defenses.

On Adaptive Attacks to Adversarial Example Defenses by Tramer et al. broke 13 defenses.

Are Defenses for Graph Neural Networks Robust? by Mujkanovic et al. broke 7 defenses.

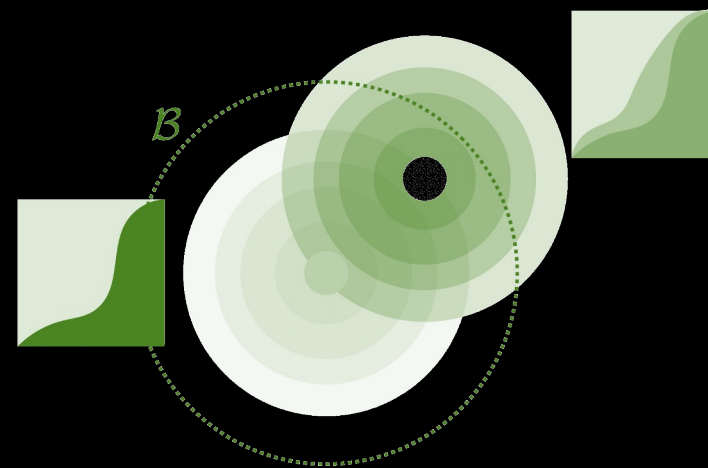
Conformal prediction is not robust



Randomized smoothing

1. Replace $s(\mathbf{x}, y)$ with $\mathbb{E}_{\mathbf{z} \sim p} [s(\mathbf{x} + \mathbf{z}, y)]$

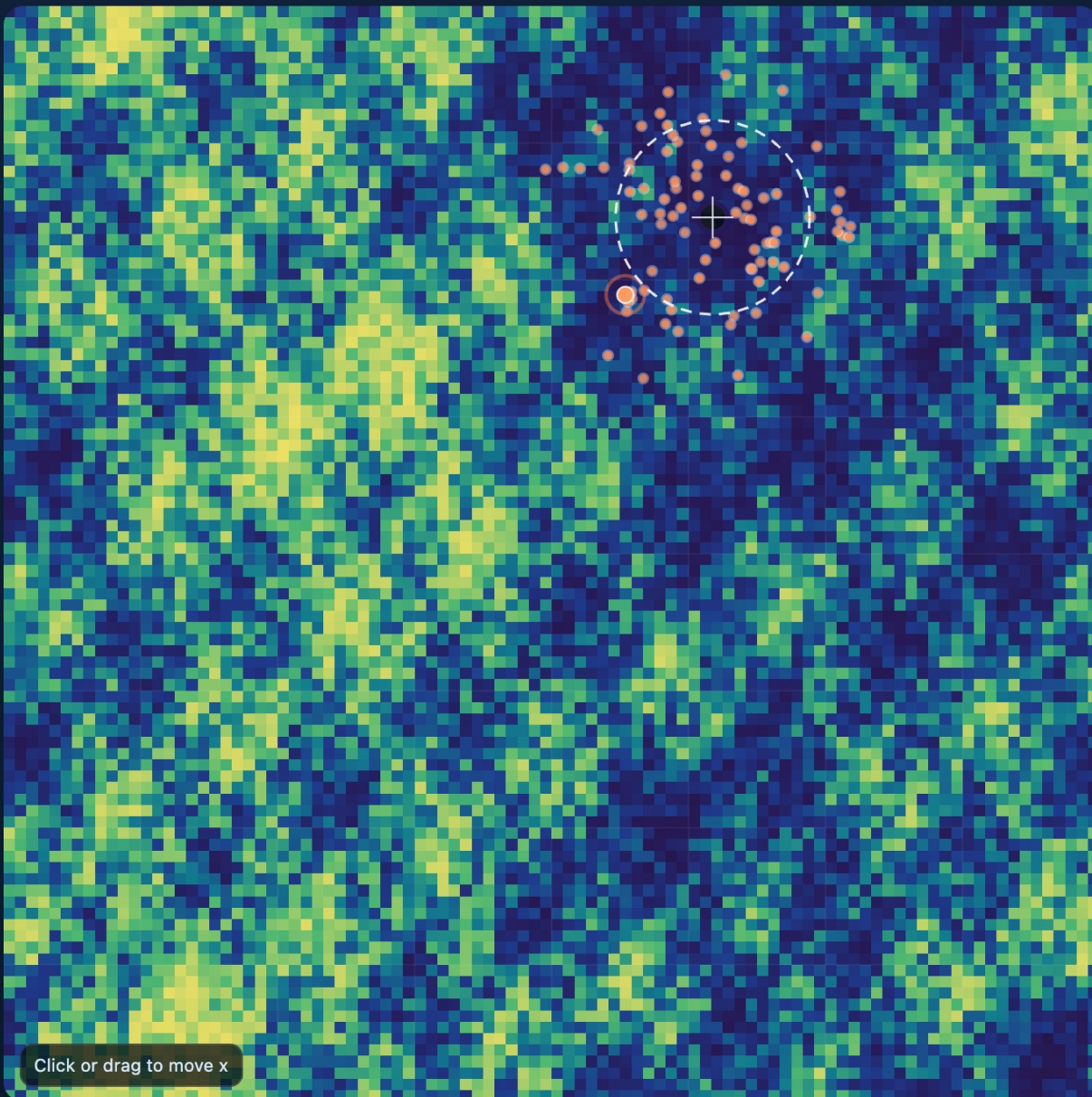
2. Bound $\max_{\mathbf{x}_{\text{adv}} \in \mathcal{B}(\mathbf{x})} \mathbb{E}_{\mathbf{z} \sim p} [s(\mathbf{x}_{\text{adv}} + \mathbf{z}, y)]$



RAW FIELD

Raw scores $f(x)$

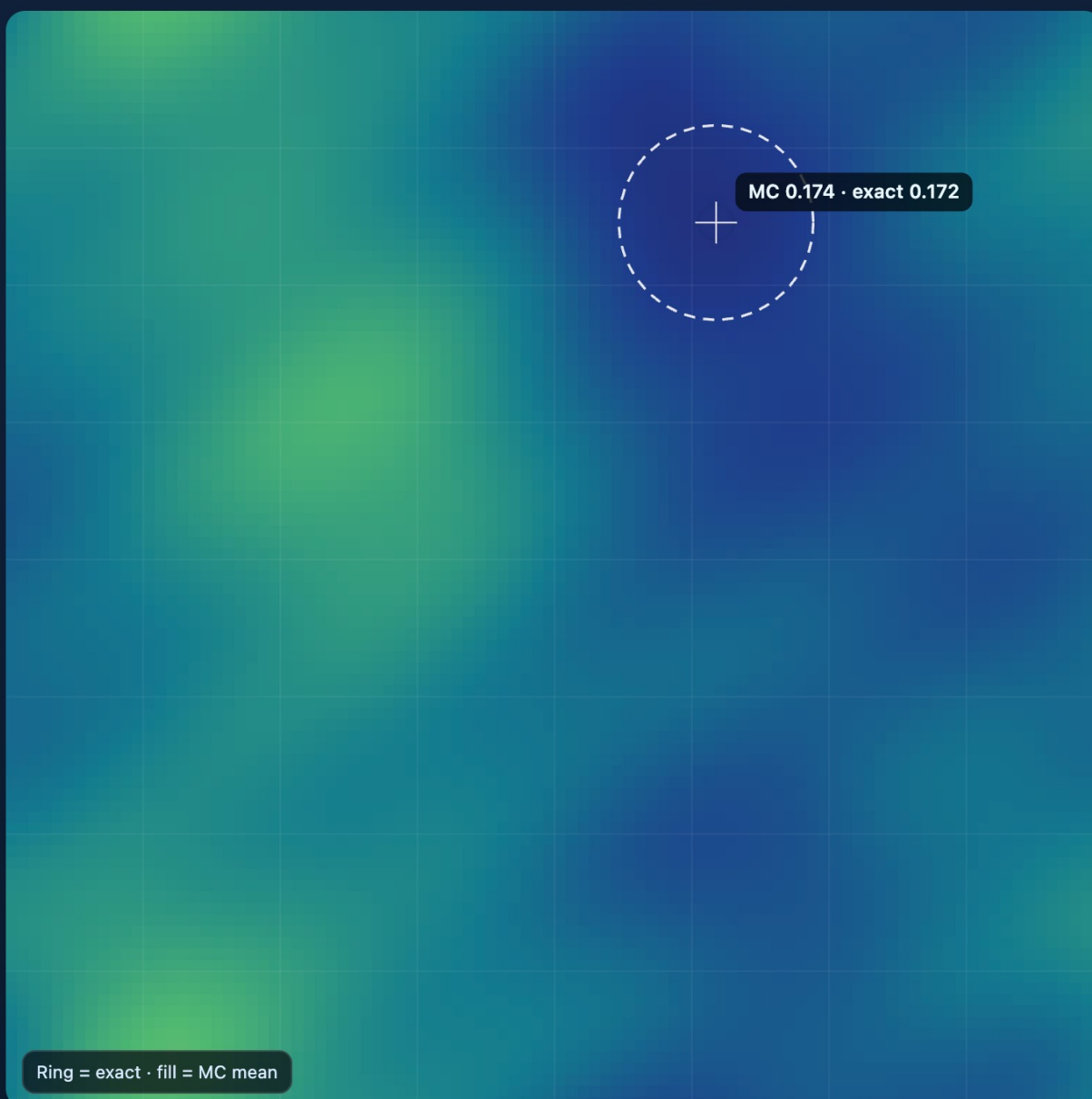
A jagged score surface. Coral dots show Gaussian perturbations around the selected point. The dashed circle marks the radius used for heuristic local bounds.



SMOOTHED FIELD

Smoothed scores $g_{\sigma}(x)$

The full field is computed by Gaussian convolution. The marker fill shows the running Monte Carlo mean; the ring shows the exact smoothed value.



Example bound for Gaussian noise

$$\text{adversarial score} \leq \Phi \left(\Phi^{-1}(\mathbb{E}[s(\mathbf{x} + \mathbf{z}, y)]) + \frac{r}{\sigma} \right)$$

need lots of MC samples to bound $\mathbb{E}[s(\mathbf{x} + \mathbf{z}, y)]$

Improving the sample efficiency

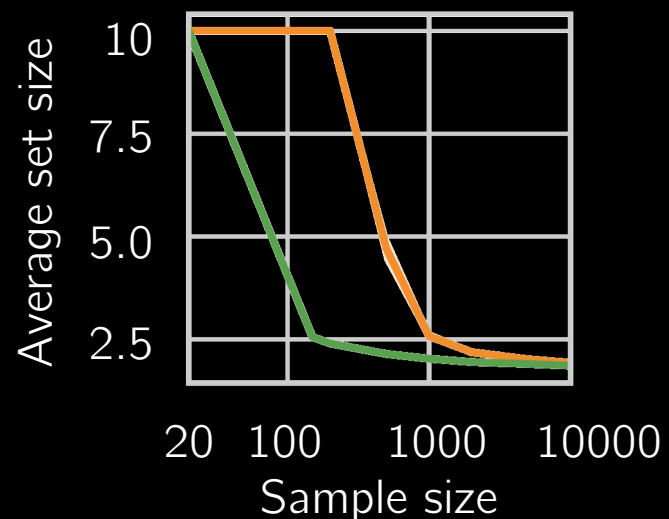
Method	Cal. samples	Test samples	Set size	Key idea
RSCP	$\sim 10^4$	$\sim 10^4$	trivial	Baseline

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RCP1	1	1	$\approx \text{BinCP}@ \sim 120$	Convexity of bounds + Jensen ³
FLoR	$10^3 - 10^4$	1	↓↓	Calibration happens once ⁴

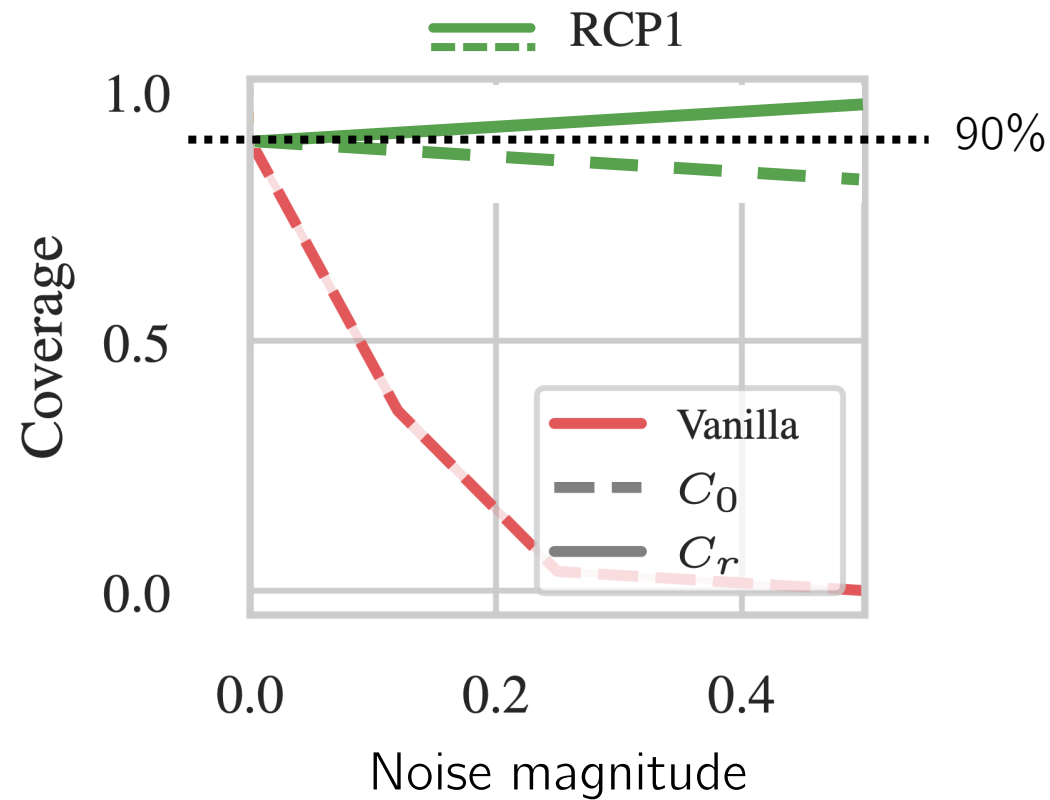
1. Zargarbashi et al. 2024. "Robust yet Efficient Conformal Prediction Sets"

2. Zargarbashi & Bojchevski 2025. "Robust Conformal Prediction with a Single Binary Certificate"

3. Zargarbashi et al. 2025. "One Sample is Enough to Make Conformal Prediction Robust"

4. Zargarbashi et al. 2026. "Front-Loaded Robust Conformal Prediction: Heavy Calibration, Minimal Test-Time Cost"

Randomness is inherently usefull



Summary

You can construct sets that promise to cover the true label

Randomness helps against adversaries