

# Multi-Parameter Topological Data Analysis with MMA

Foundations of Computational Geometry and Topology @ ICERM

May 18th, 2026

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DataShape, Centre Inria d'Université Côte d'Azur

joint work with A. Blumberg, D. Loiseaux, L. Andrianirina

The Inria logo is written in a red, cursive script font. The word "Inria" is written in a fluid, handwritten style with a slight upward curve at the end.

- 1. Background: Persistence Theory**
- 2. MMA: Multi-parameter Module Approximation**
- 3. MMA Application: Machine Learning**
- 4. MMA Application: Clustering**

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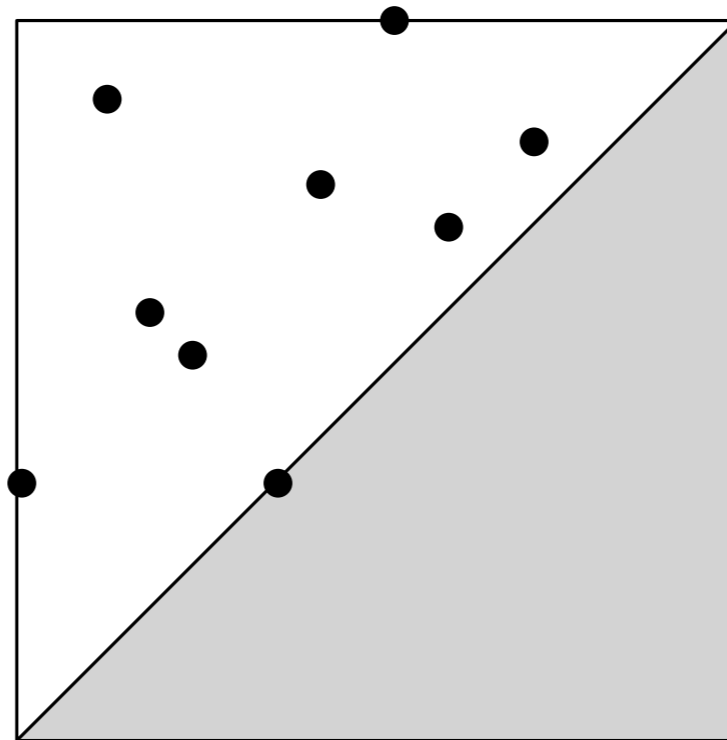
# What is Single Parameter Persistence?

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**Def:** A finite multiset  $D(M)$  in  $\{(x, y) \in \mathbb{R} \times \mathbb{R} \cup \{+\infty\} : x \leq y\}$  computed from a *single parameter persistence module*  $M$ .

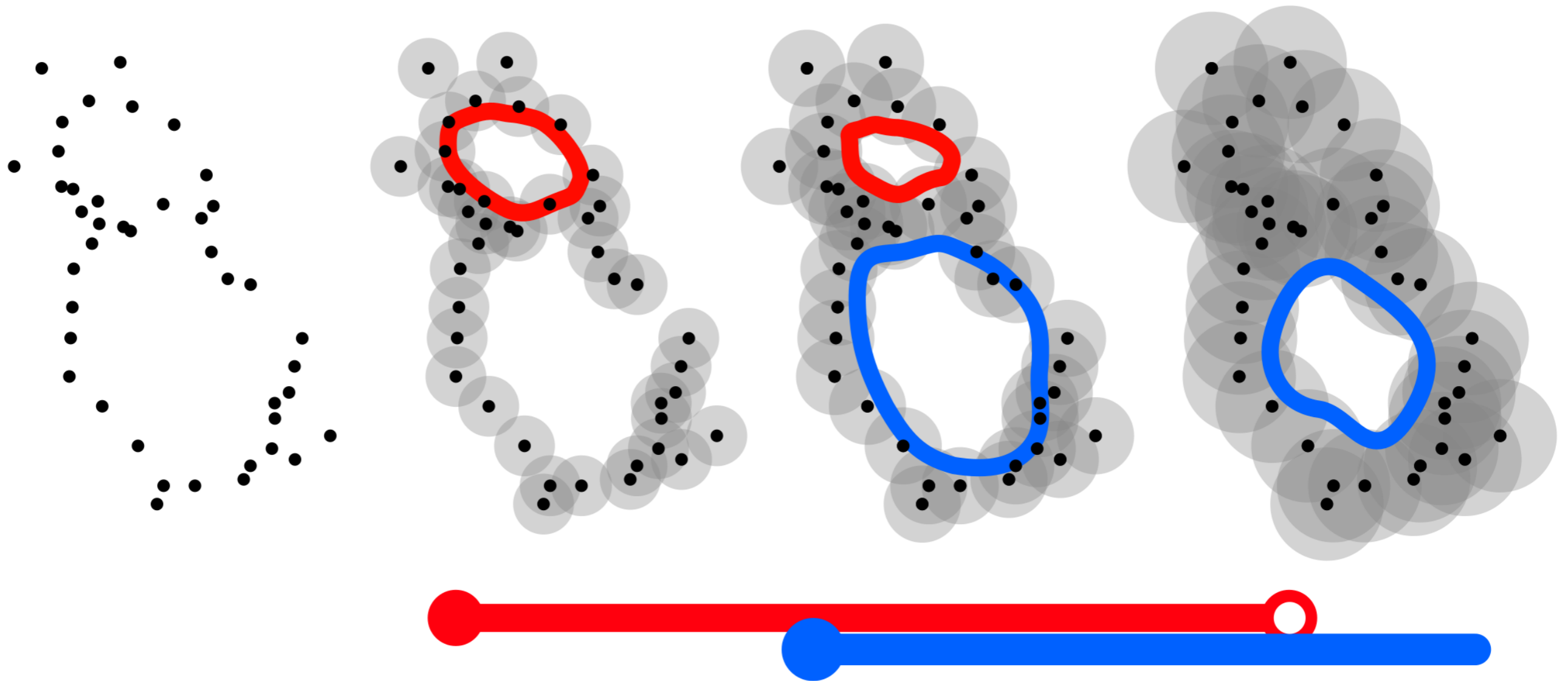
$$M = H_*(X_{\alpha_1}) \rightarrow \cdots \rightarrow H_*(X_{\alpha_M})$$

Each point represents a **topological feature** (connected component, loop, cavity, etc.) and the coordinates are proxies for its size.



# What is Single Parameter Persistence?

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# What is Multi-parameter Persistence?

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Multiparameter persistence is the study of *multiparameter persistence modules*.

**Def:** A multiparameter persistence module is a functor from  $\mathbb{R}^n$  to  $\text{Vect}_{\mathbf{k}}$ , the vector spaces over field  $\mathbf{k}$ .

$$M = \{ \{M_x : x \in \mathbb{R}^n\}, \{\Phi_{x,y} : M_x \rightarrow M_y\}_{x,y \in \mathbb{R}^n, x \leq y} \}$$

where  $x \leq y \iff x_i \leq y_i \ \forall 1 \leq i \leq n$

Multiparameter persistence modules can be compared with the *interleaving distance*  $d_I$ .

**Def:** The interleaving distance  $d_I$  between multiparameter persistence modules  $M, M'$  is defined as:

$$d_I(M, M') = \inf \{ \epsilon > 0 : M, M' \text{ are } \epsilon\text{-interleaved} \}$$

where  $M, M'$  are  $\epsilon$ -interleaved if  $\exists A_x : M_x \rightarrow M'_{x+\epsilon}, B_x : M'_x \rightarrow M_{x+\epsilon}$  s.t.

$$\Phi_{x,x+2\epsilon} = B_{x+\epsilon} \circ A_x \text{ and } \Psi_{x,x+2\epsilon} = A_{x+\epsilon} \circ B_x, \forall x \in \mathbb{R}^n$$

# What is Multi-parameter Persistence?

Multiparameter persistence modules often come from applying the homology functor to *multiparameter filtrations*.

**Def:** A multiparameter filtration  $\mathcal{F}$  of a topological space  $X$  is a family of subsets of  $X$  indexed by  $\mathbb{R}^n$  such that:

$$\forall x, y \in \mathbb{R}^n, x \leq y \implies \mathcal{F}_x \subseteq \mathcal{F}_y$$

Multiparameter filtration

Associated multiparameter persistence module

$$X_{1,3} \subseteq X_{2,3} \subseteq X_{3,3}$$

$$H_*(X_{1,3}) \longrightarrow H_*(X_{2,3}) \longrightarrow H_*(X_{3,3})$$

$$\cup \quad \cup \quad \cup$$

$$\uparrow \quad \uparrow \quad \uparrow$$

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Multiparameter persistence modules can also be compared with the *rank invariant* and the *fibered barcode*.

**Def:** The rank invariant of a multiparameter persistence module  $M$  is:

$$\text{rk}(M) : \begin{cases} \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{N} \\ (x, y) \mapsto \dim(\text{im}(M_x \rightarrow M_y)) := \beta^{x,y} \end{cases}$$

$\beta^{x,y}$  is called the *multiparameter persistent Betti number*.

**Def:** The fibered barcode of a multiparameter persistence module  $M$  is:

$$\mathcal{L}(M) : \ell \mapsto D(M|_{\ell})$$

where  $\ell$  is a line in  $\mathbb{R}^n$ , and  $D(M|_{\ell})$  stands for the barcode/persistence diagram obtained by restricting  $M$  to  $\ell$ .

# What is Multi-parameter Persistence?

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Finally, multiparameter persistence modules can be *decomposed* into a direct sum of summands.

$$M \simeq \bigoplus_i M_i,$$

where  $M_i$  cannot be decomposed, i.e., is *indecomposable*.

Contrary to 1D persistence, indecomposable summands in  $\mathbb{R}^n$  are **not** necessarily made of *indicator modules*, i.e., modules that contain only single copies of the field  $\mathbb{k}$ . Among all indecomposable summands, the ones called *intervals* are of particular interest.

**Def:** An interval module is an indicator module supported on a subset  $\mathcal{I} \subseteq \mathbb{R}^n$  which satisfies:

(i)  $\mathcal{I} \neq \emptyset$ ,

(ii)  $\forall x, y \in \mathcal{I}$ , if  $\exists z$  s.t.  $x \leq z \leq y$  then  $z \in \mathcal{I}$ ,

(iii)  $\forall x, y \in \mathcal{I}$ ,  $\exists x_0 = x, x_1, \dots, x_{n-1}, x_n = y$  s.t.  $x_i \leq x_{i+1}$  or  $x_{i+1} \leq x_i$ .

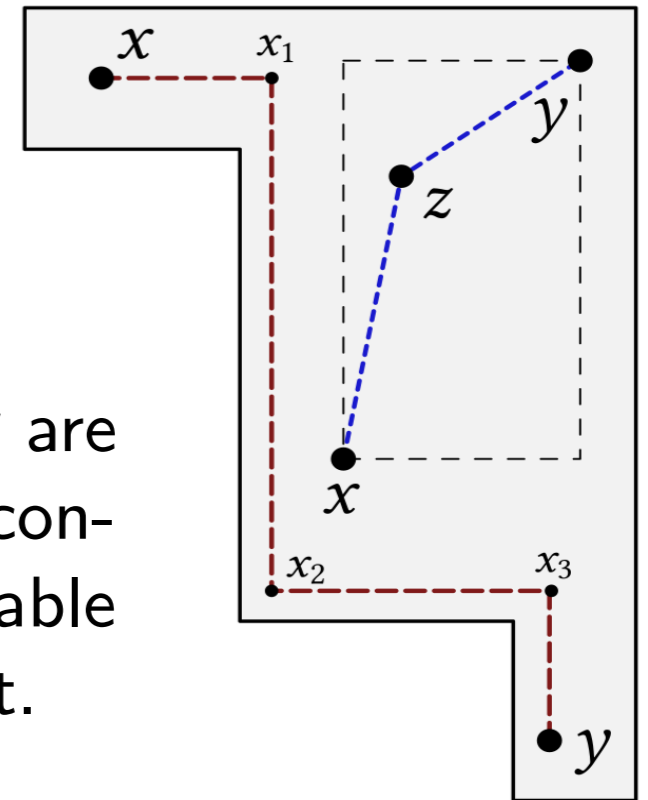
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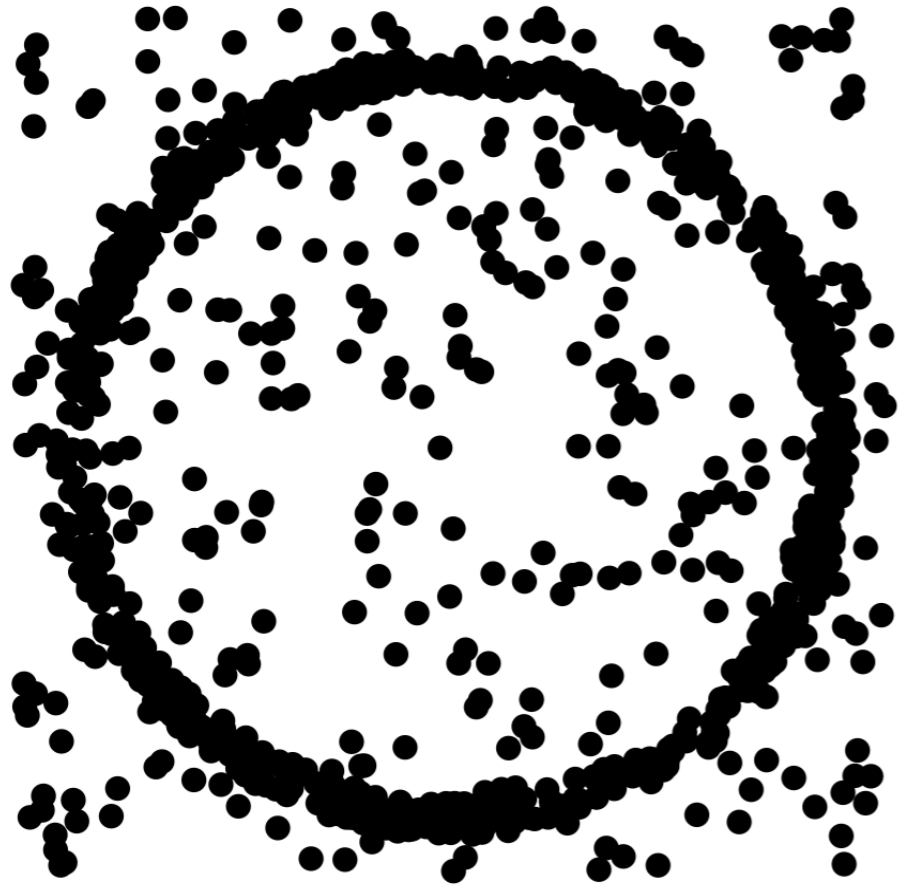
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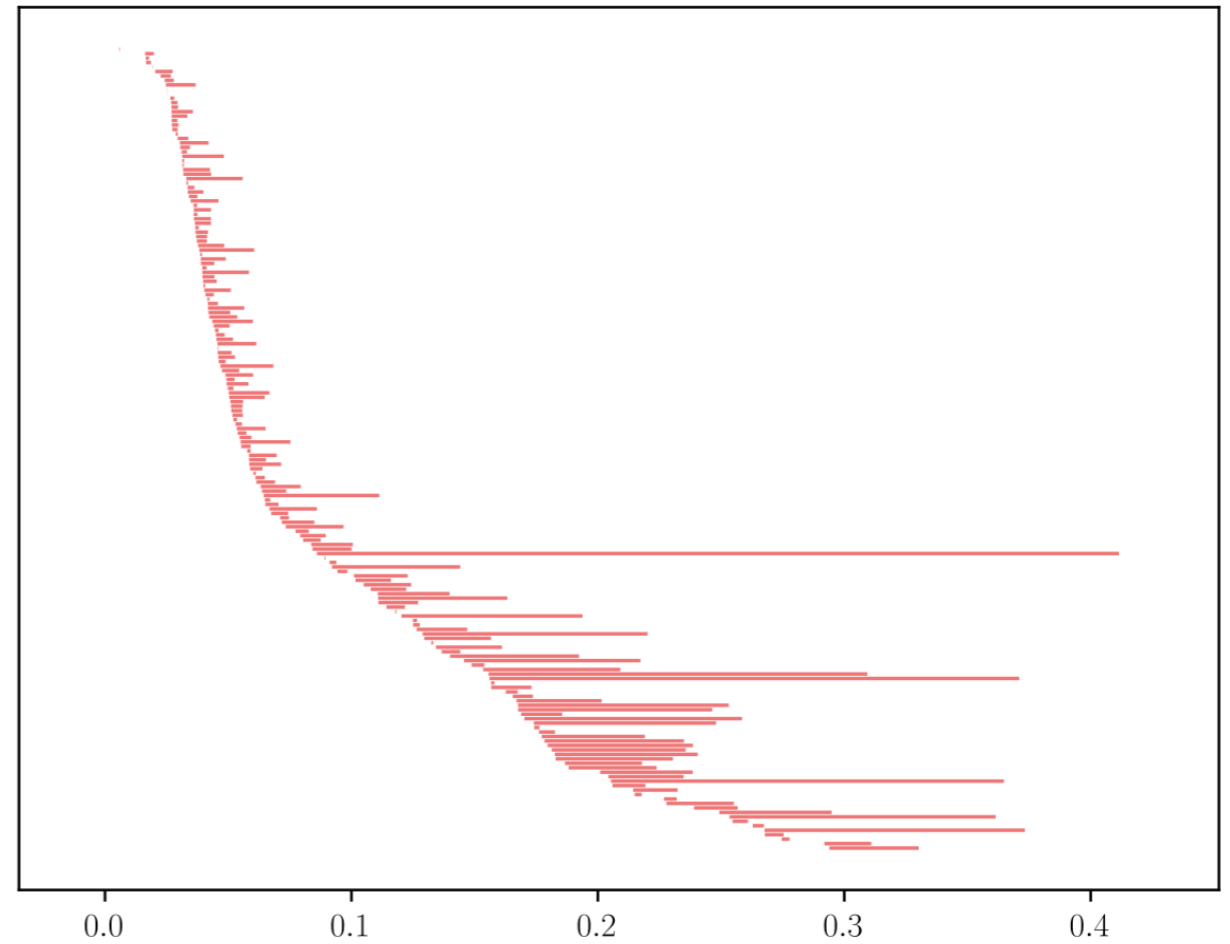
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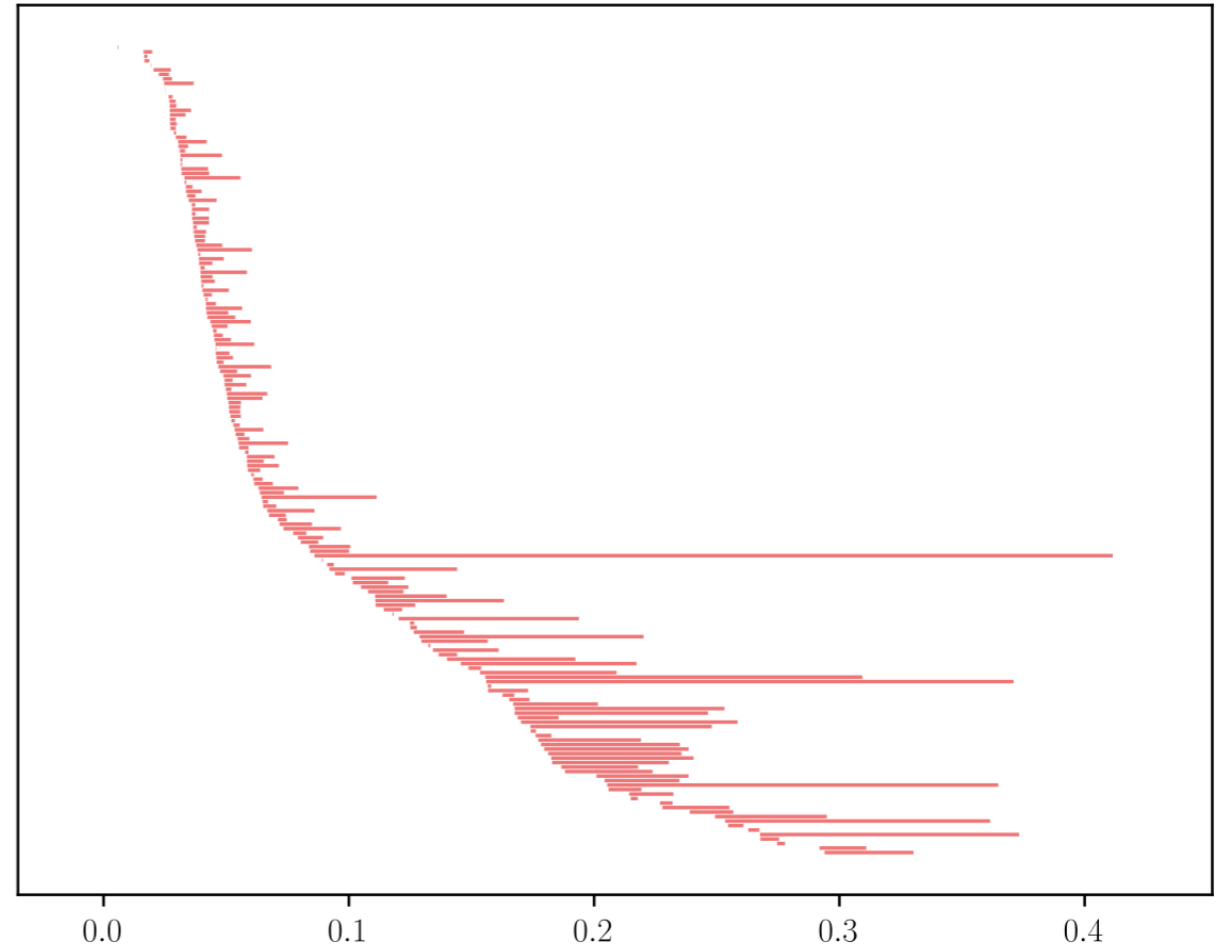


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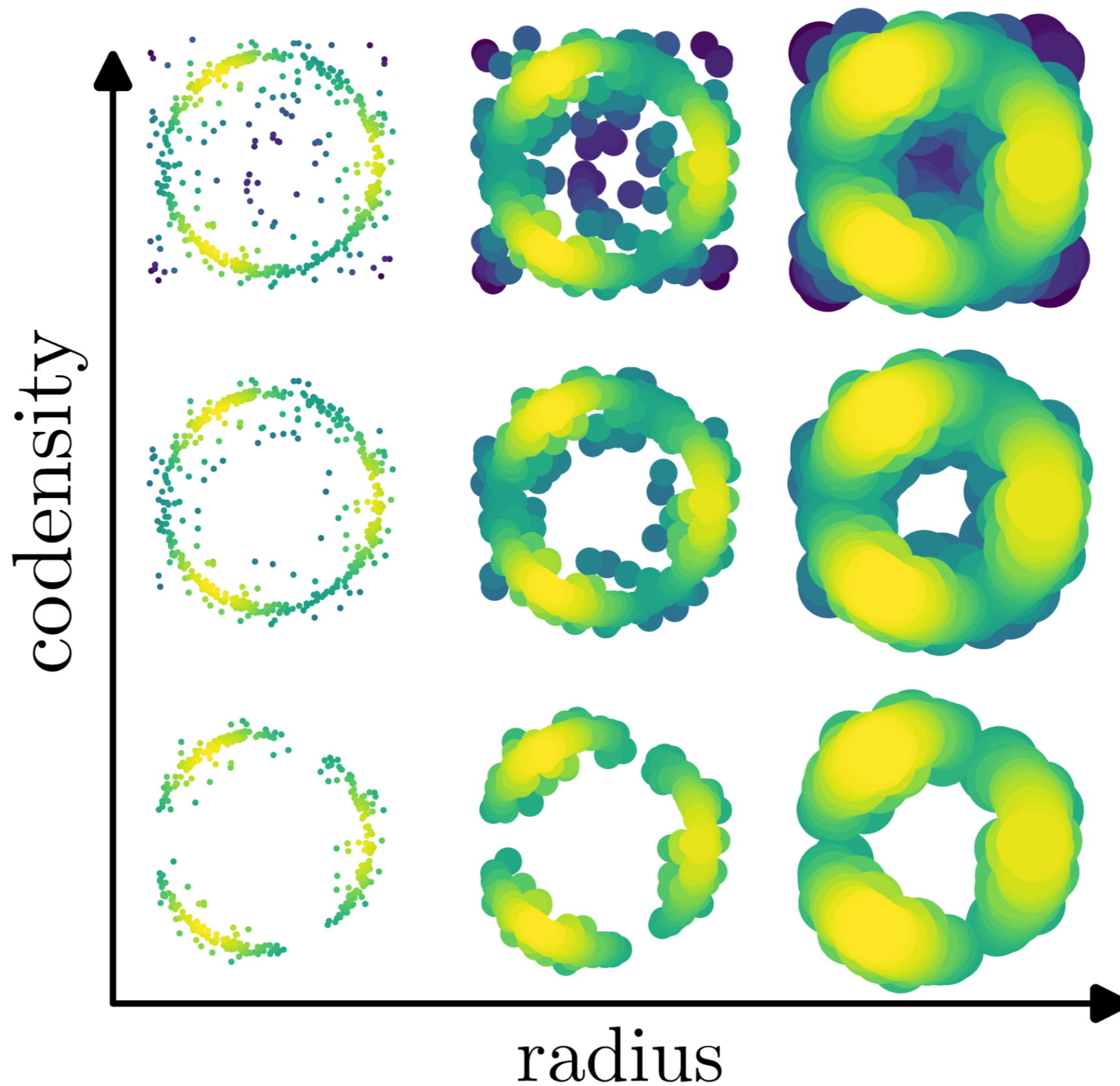


Persistence barcode



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[Loiseaux, C., Blumberg, **Multi-Parameter Module Approximation: An Efficient and Interpretable Invariant for Multi-Parameter Persistence Modules with Guarantees.** JACT, 2025]

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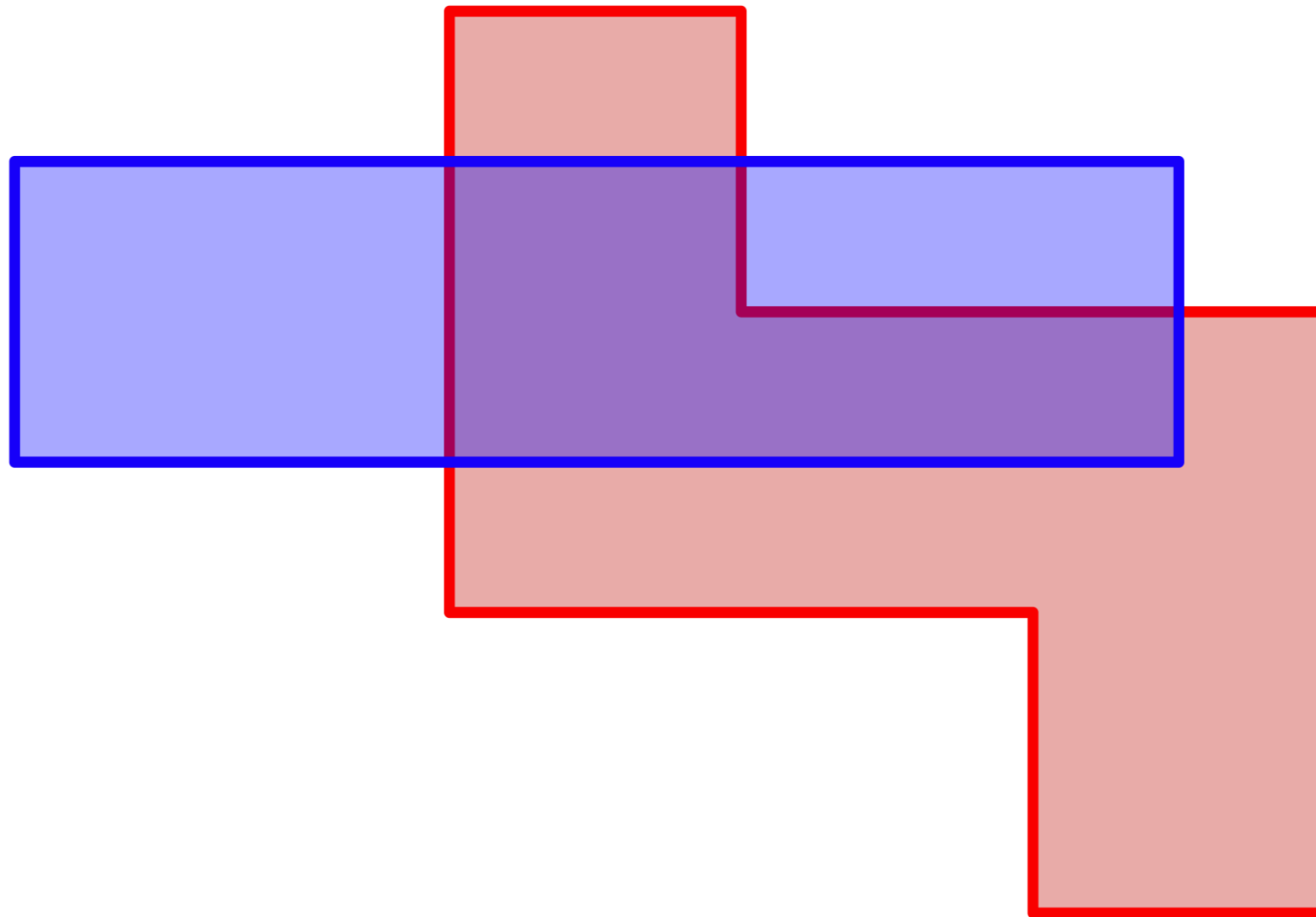
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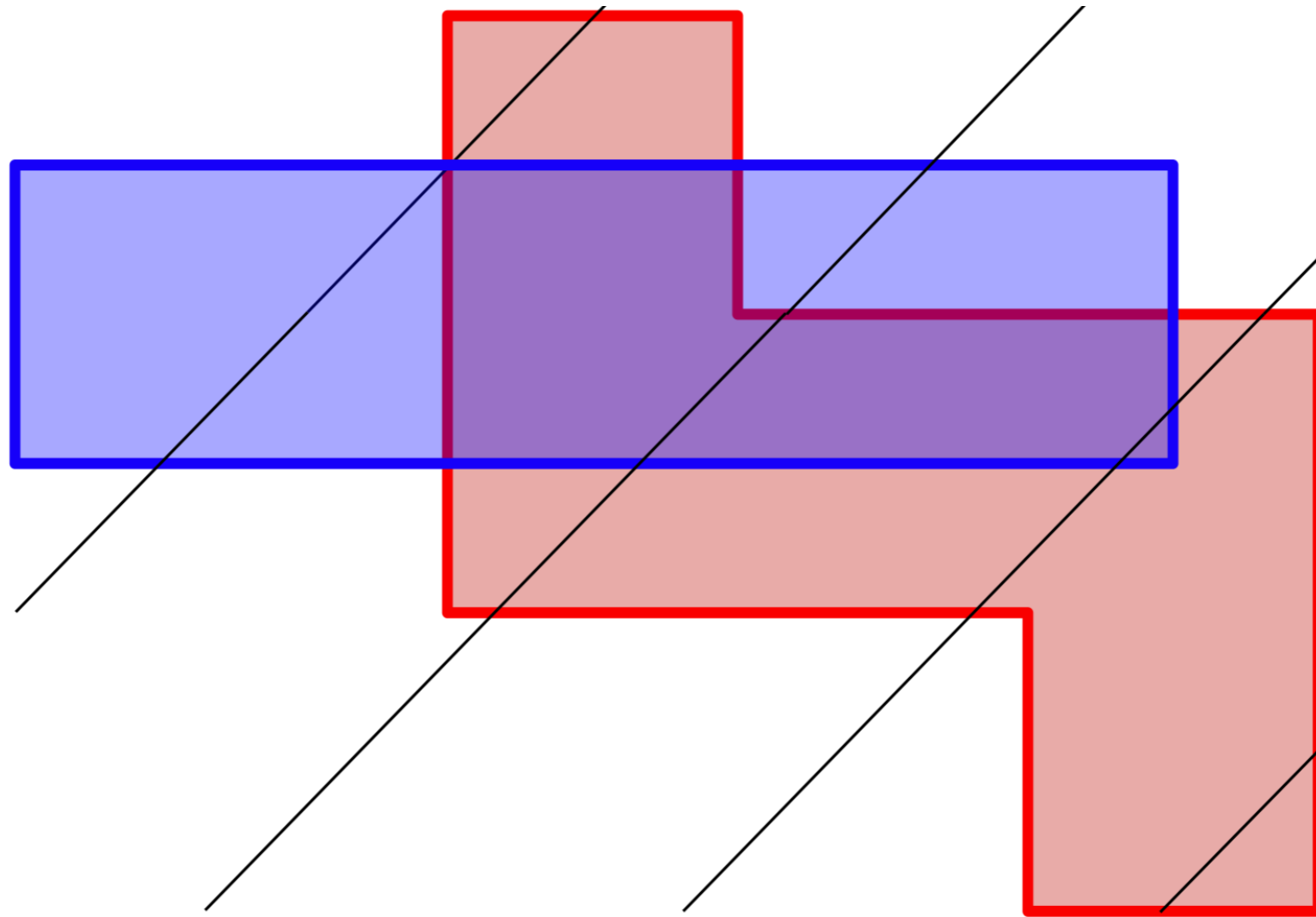
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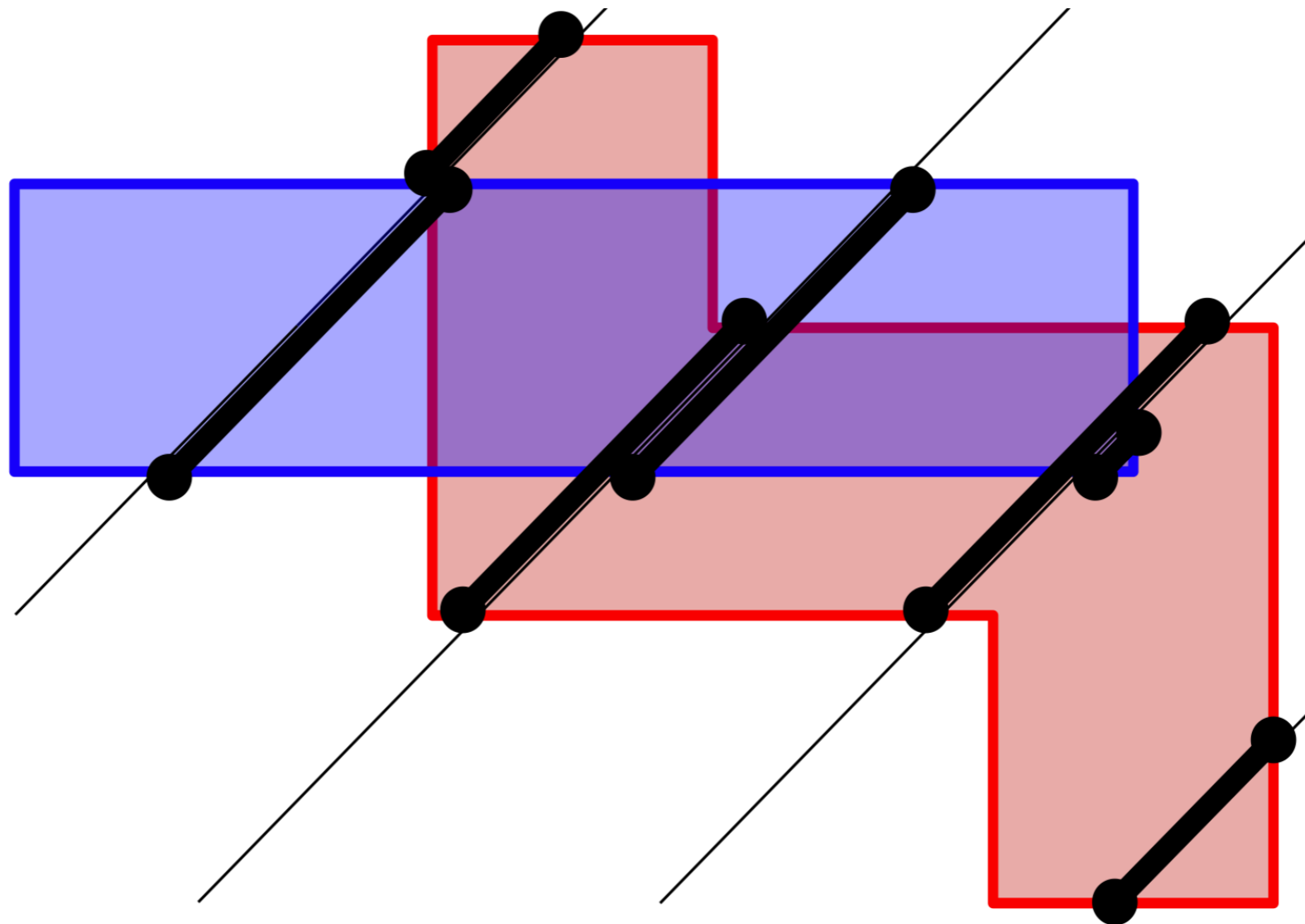
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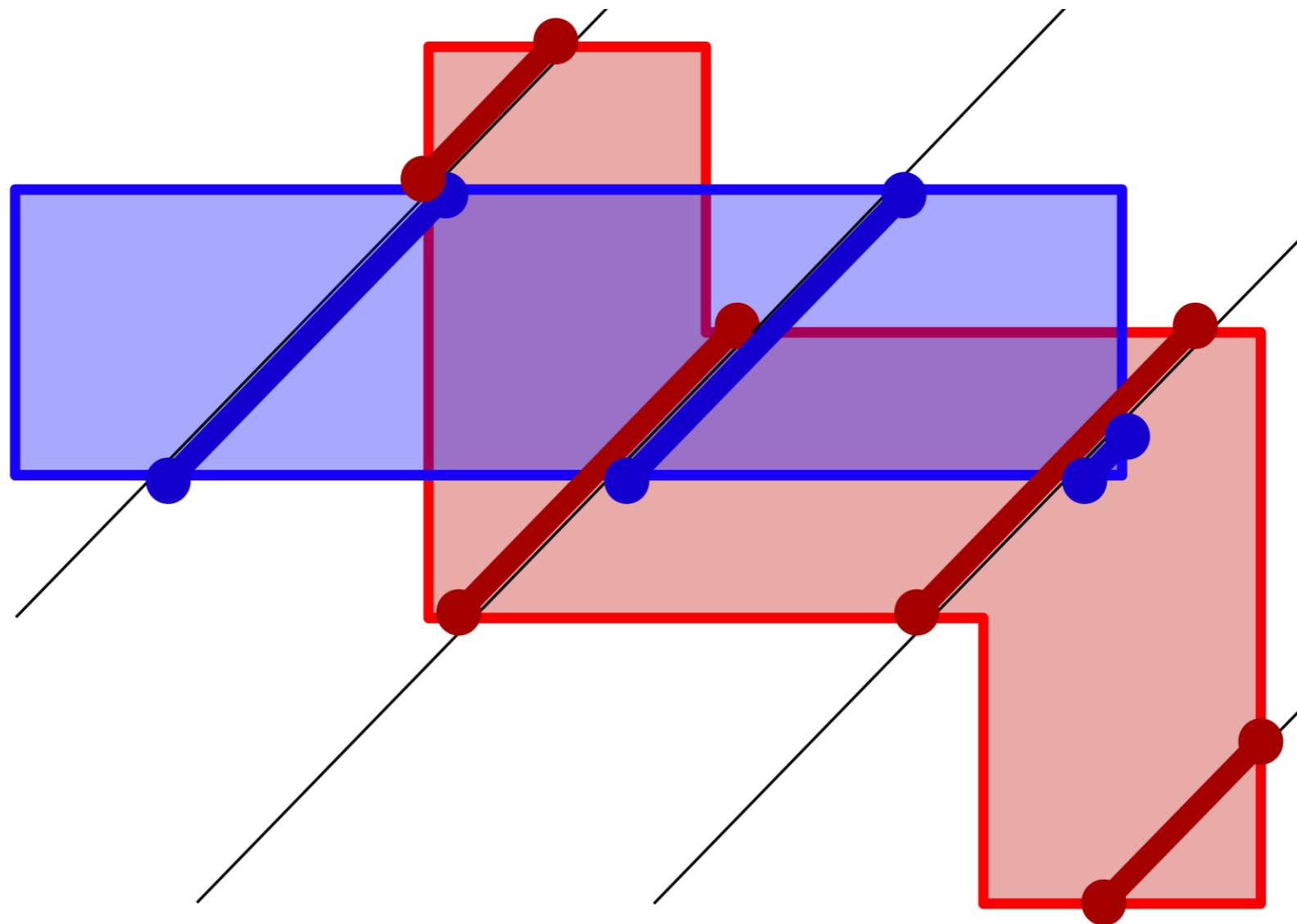
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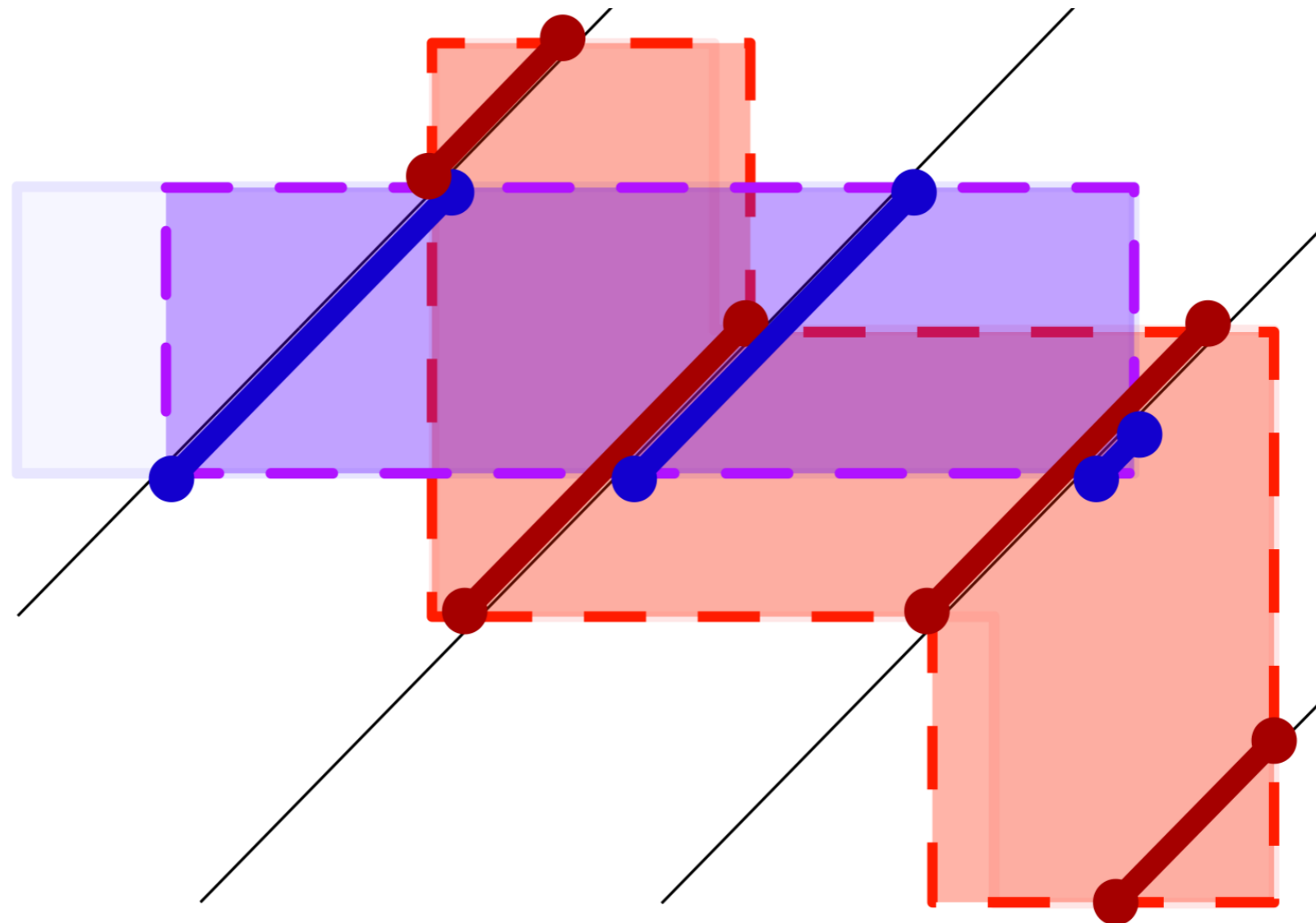
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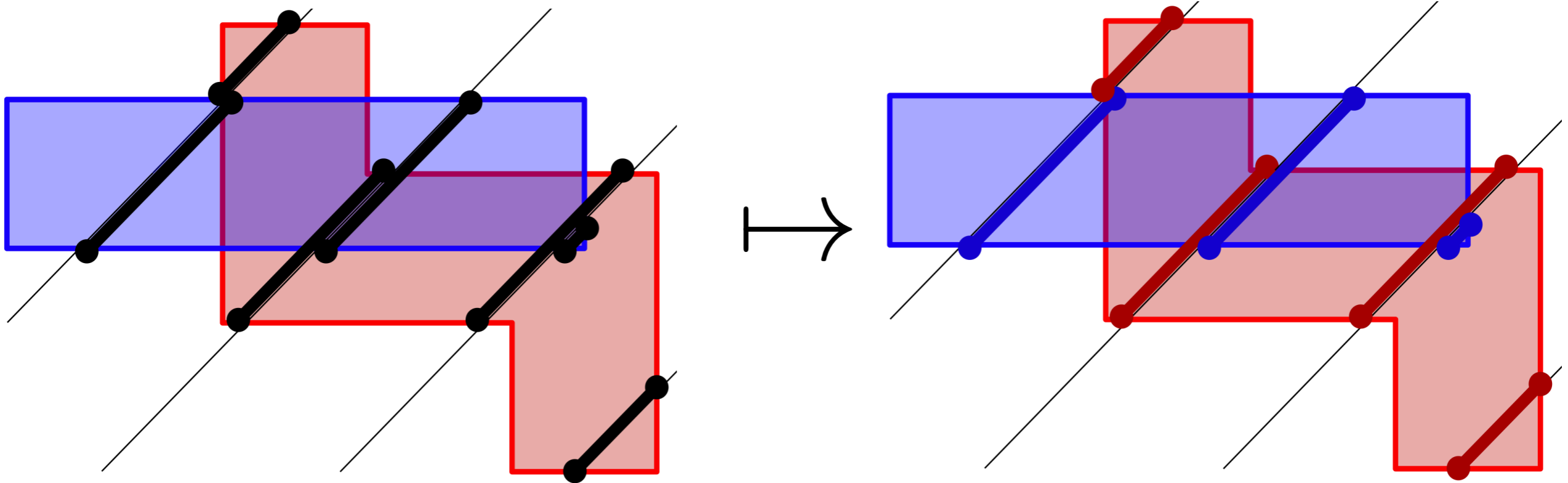
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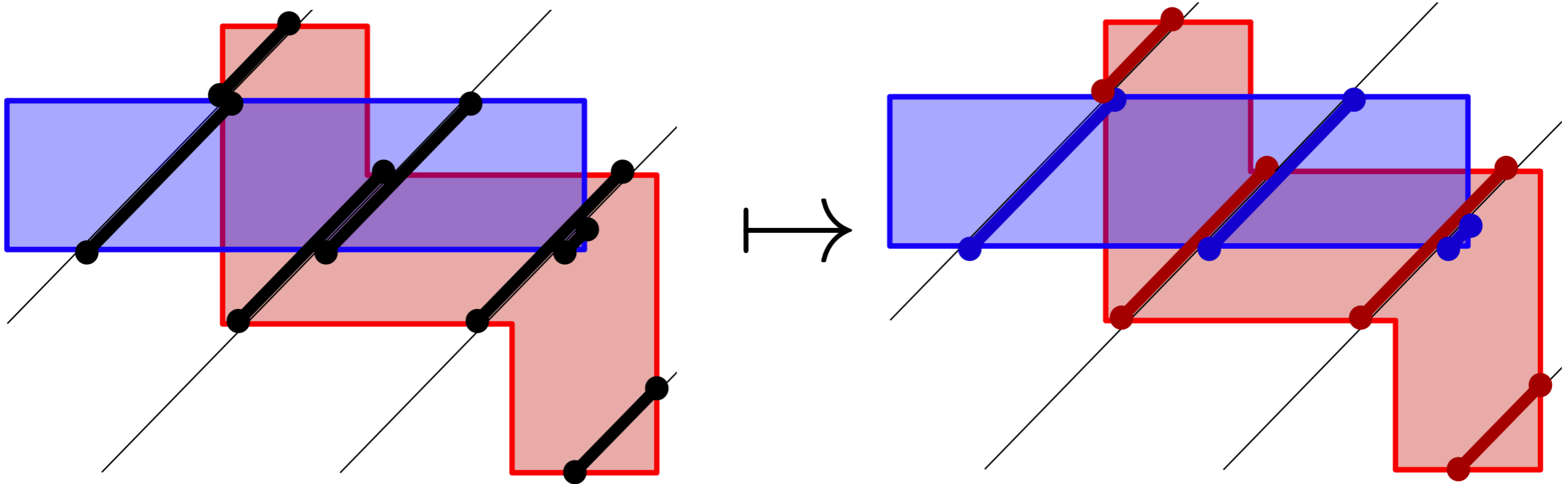


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**Ex:** Induced matchings:



**In practice:** vineyards, Wasserstein distance, etc.

# Compatible Matchings and Candidate Decompositions

**Def:** A matching  $m$  of  $M$  is *compatible* if there exists  $N$  s.t.

- (i)  $N$  is interval decomposable,
- (ii)  $D(M|_\ell) = D(N|_\ell), \forall \ell \in L$ , and
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**Th:** Let  $m$  be a compatible matching of a module  $M$ . Let  $N$  be its corresponding candidate decomposition. Then:

$$d_b(\mathcal{L}(M), \mathcal{L}(N)) \rightarrow 0 \text{ as } |L| \rightarrow +\infty.$$

Moreover, if  $M$  is interval decomposable, and  $|L|$  is large enough:

$$d_I(M, N) = 0.$$

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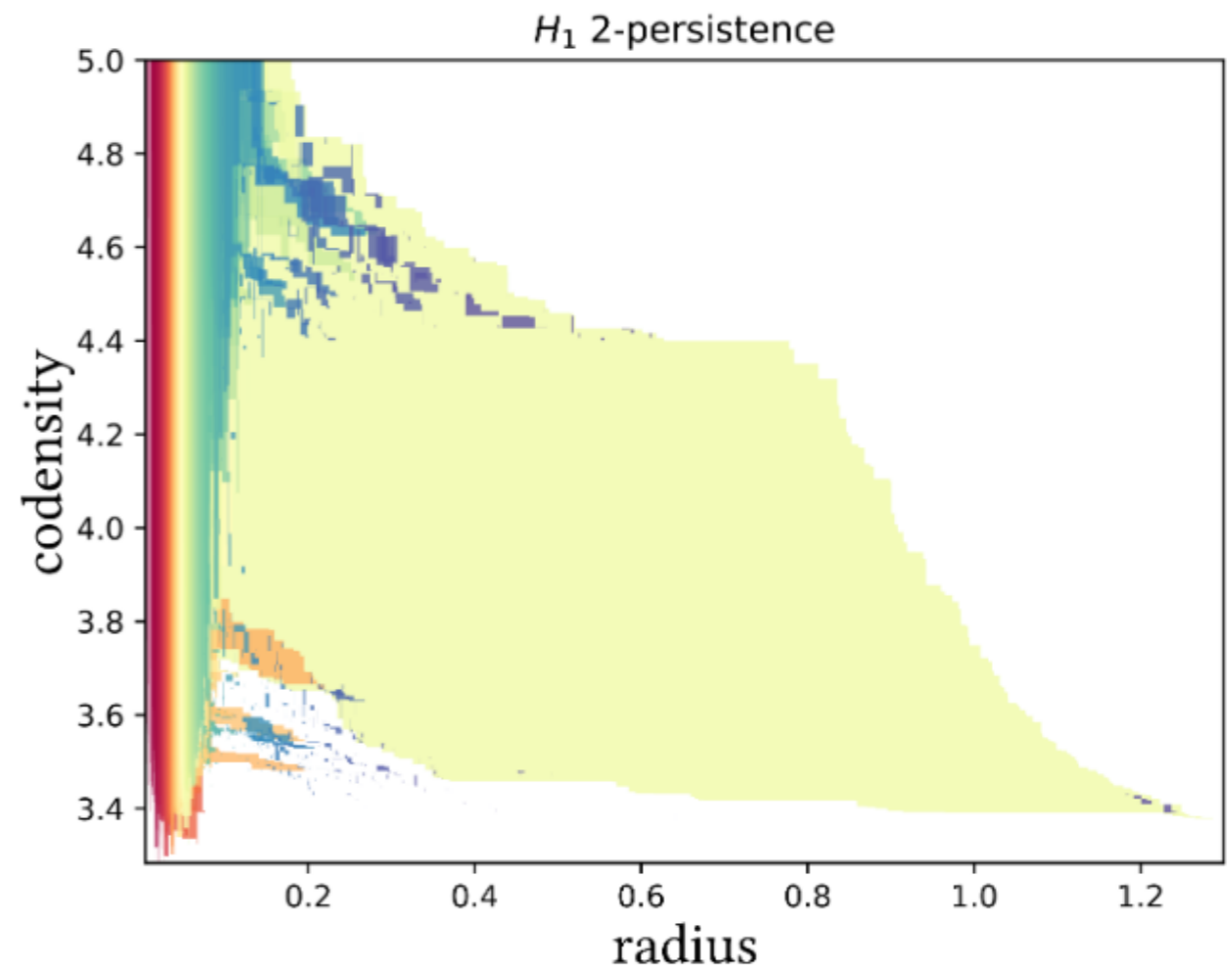
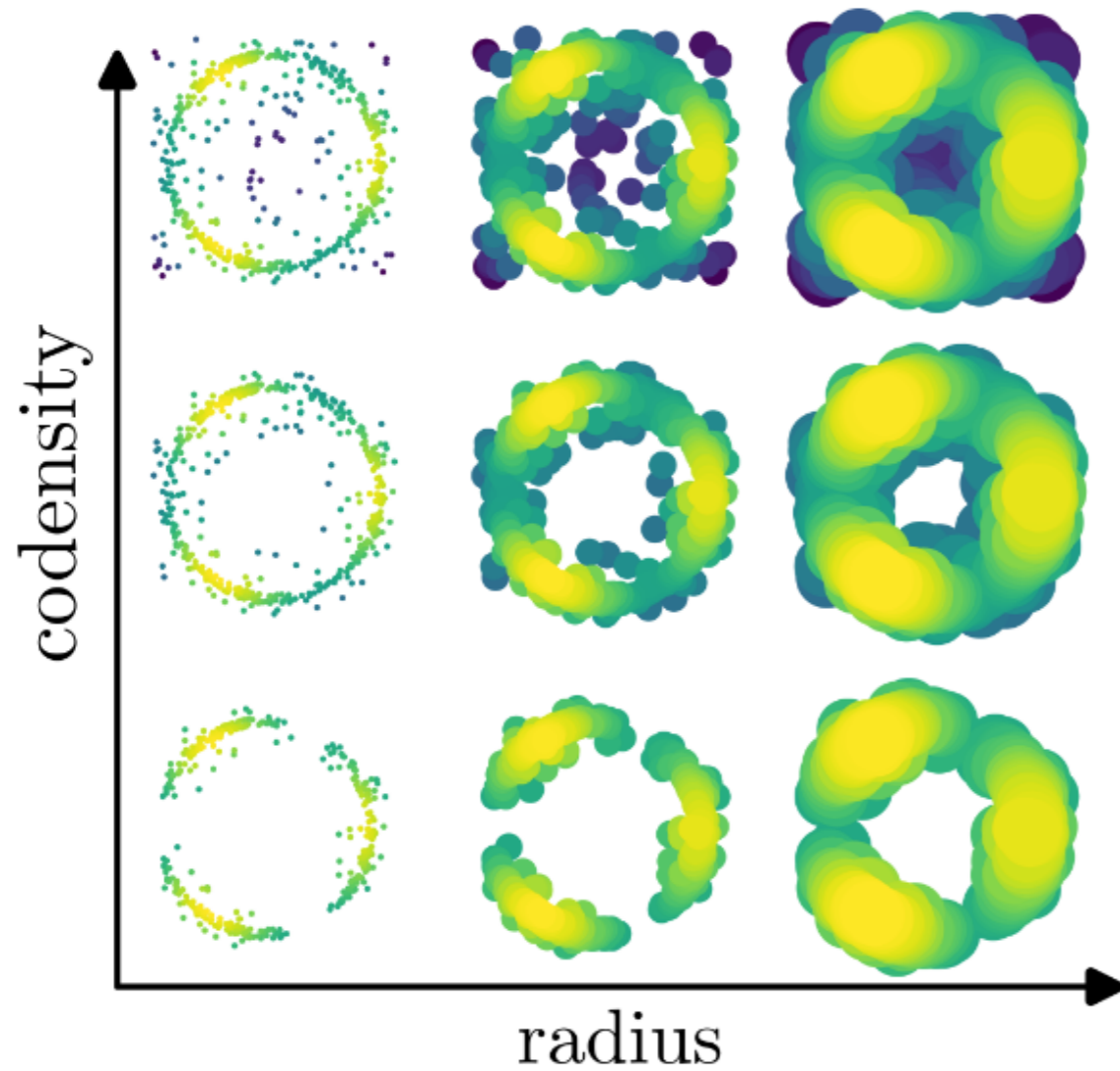
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**In practice:** usual matchings are compatible under genericity assumptions.

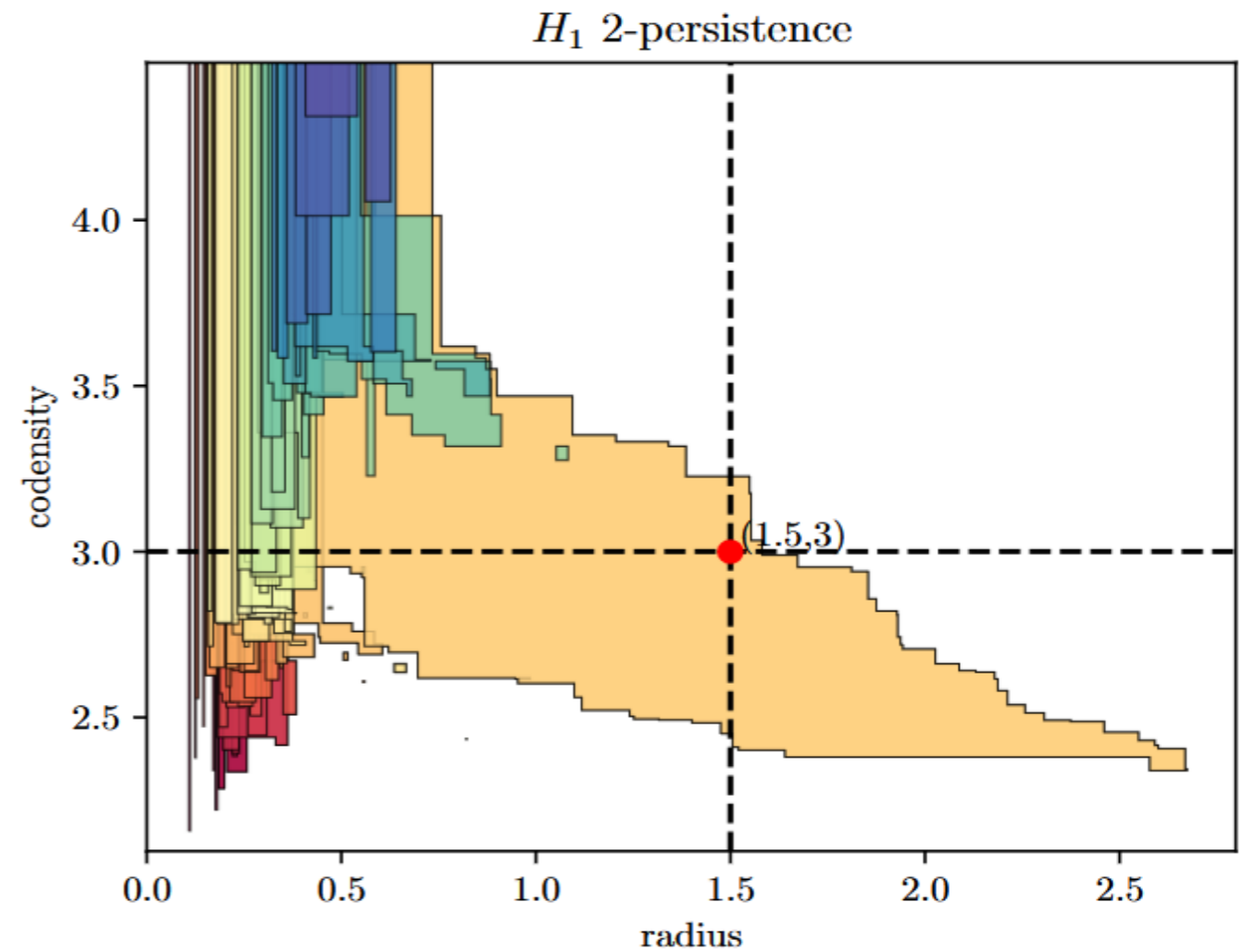
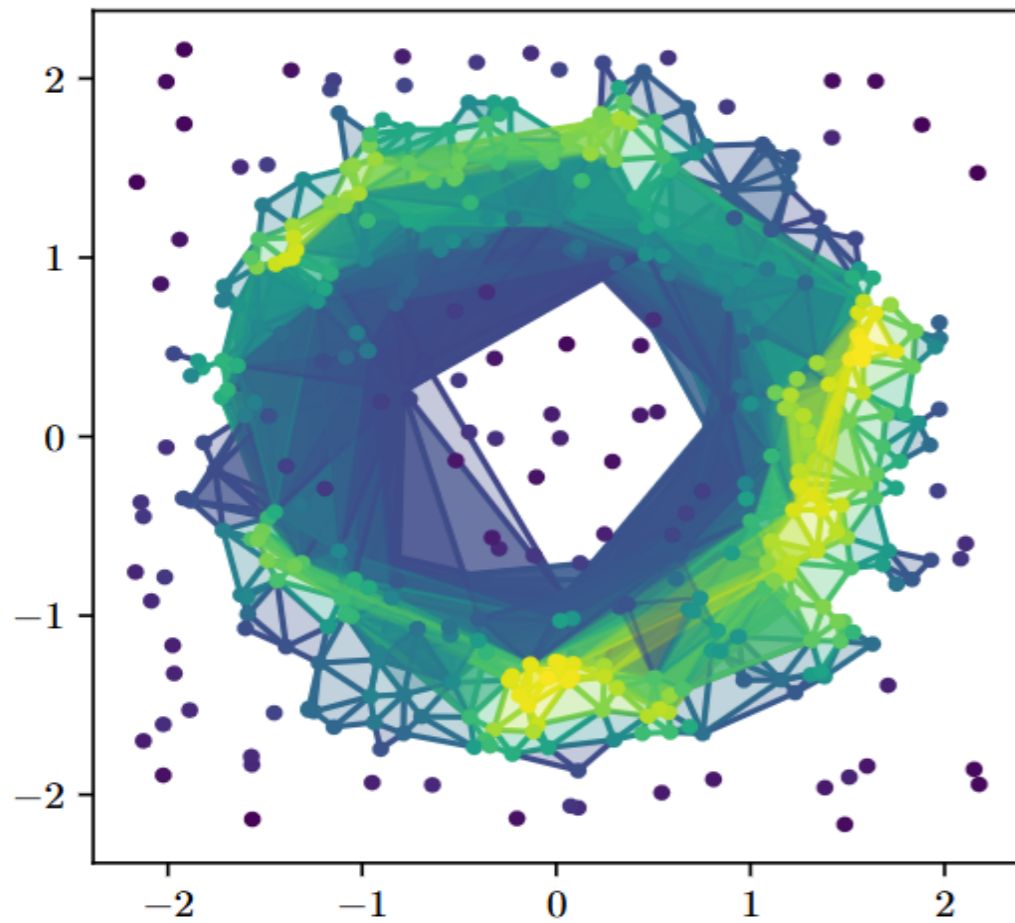
# Algorithms

**In practice:** Candidate decompositions can be computed with multipers.



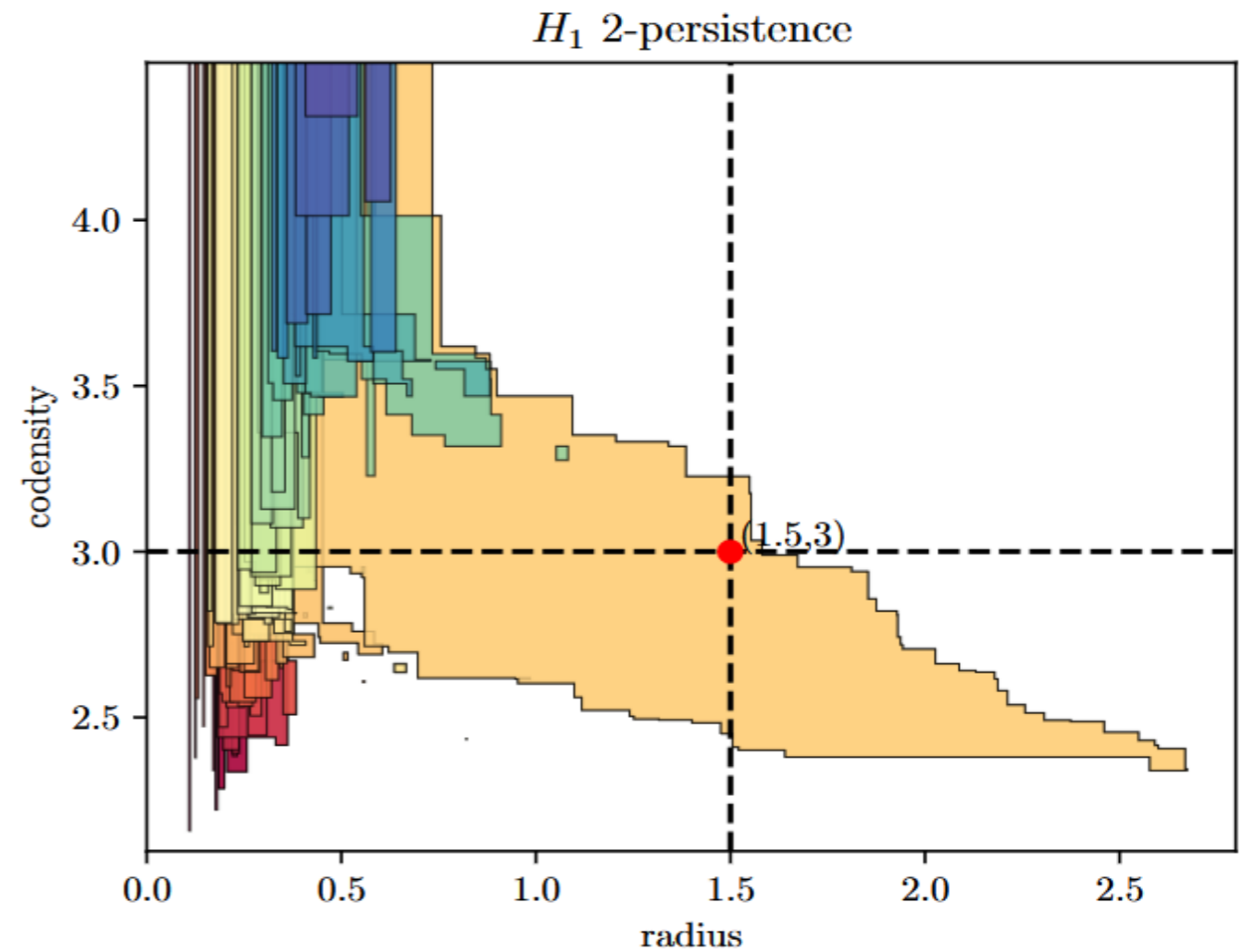
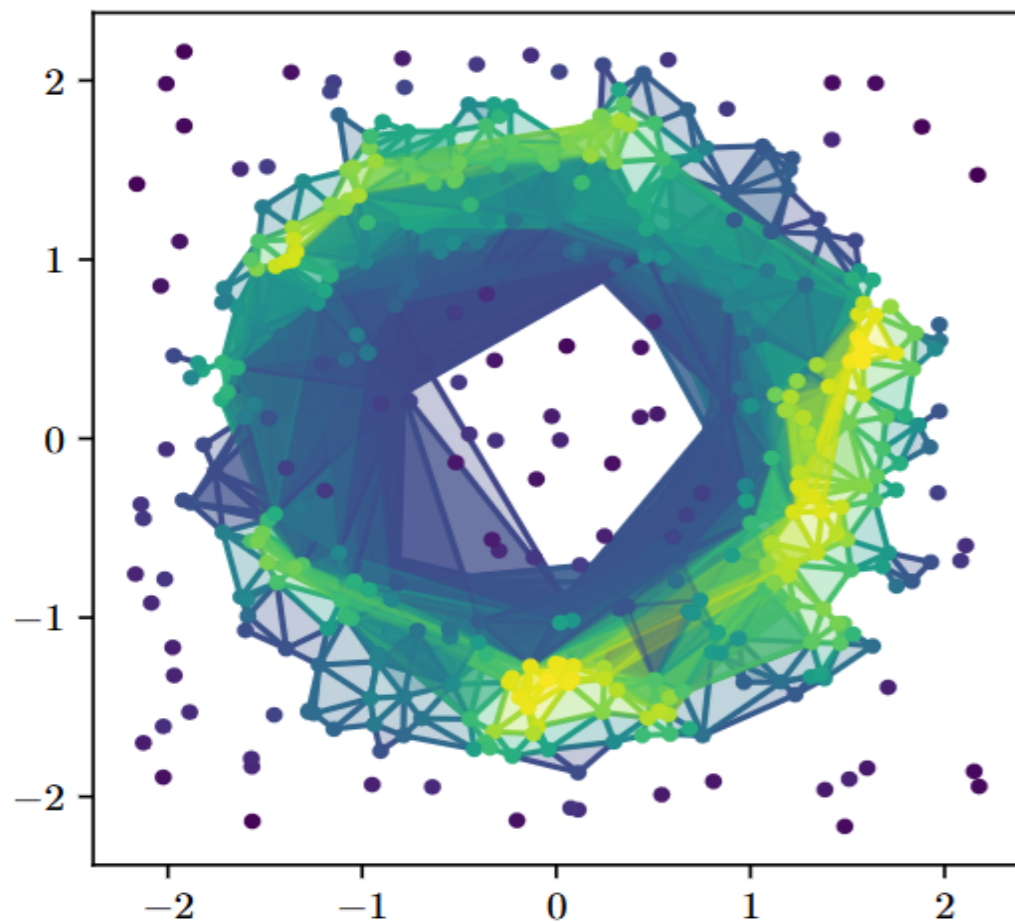
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Other candidate decompositions are possible  $\rightarrow$  Harvard's talk.

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[Loiseaux, C., Blumberg, **A Framework for Fast and Stable Representations of Multiparameter Persistent Homology Decompositions.** NeurIPS, 2023]

# Candidate Decompositions $\rightarrow$ Descriptors

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**Idea:** Use a generalized, "templated" version of persistence images:

**Def:** Let  $M = \bigoplus_i M_i$  be a candidate decomposition. Then,

$$V(M) = \text{op}(\{w(M_i) \cdot \phi(M_i)\}_i)$$

is called a *template candidate decomposition representation* (T-CDR).

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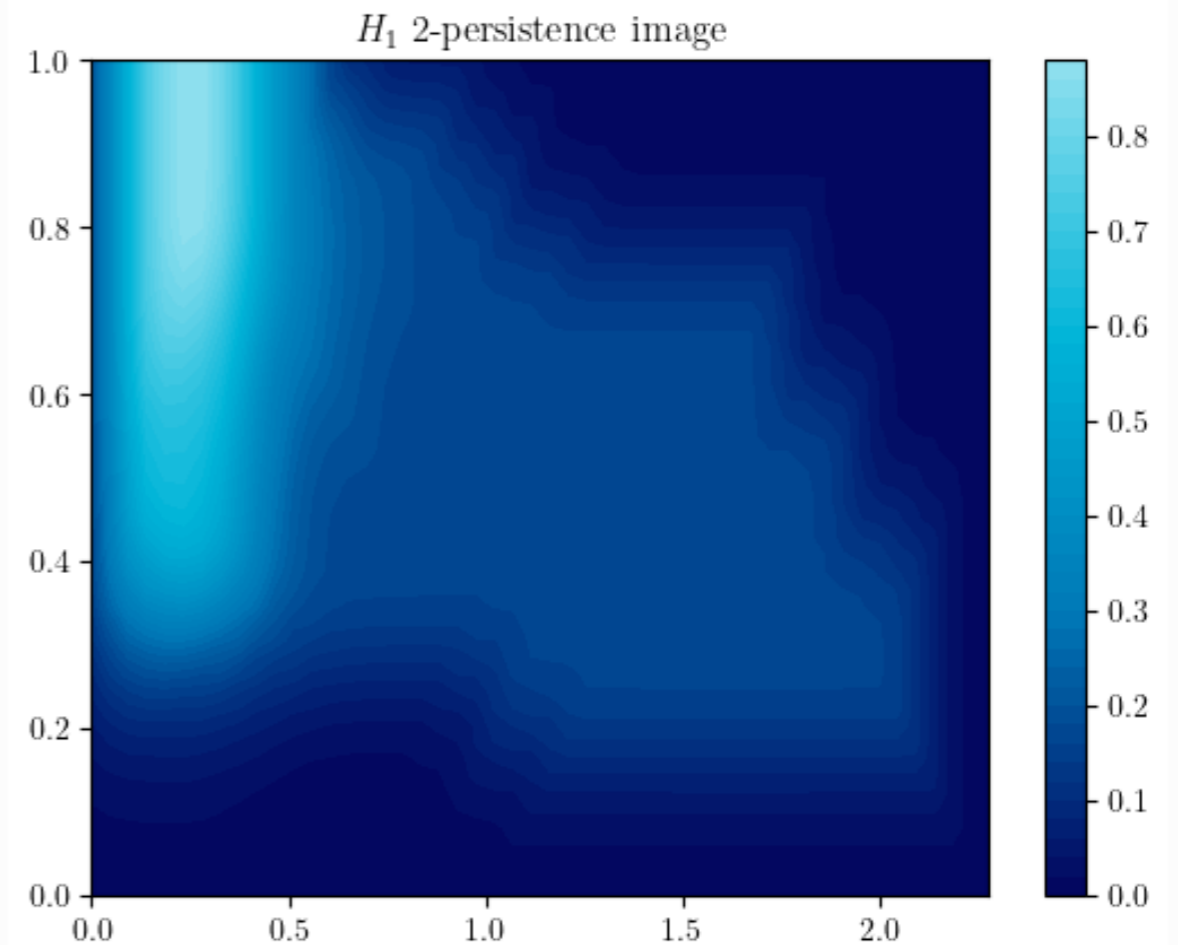
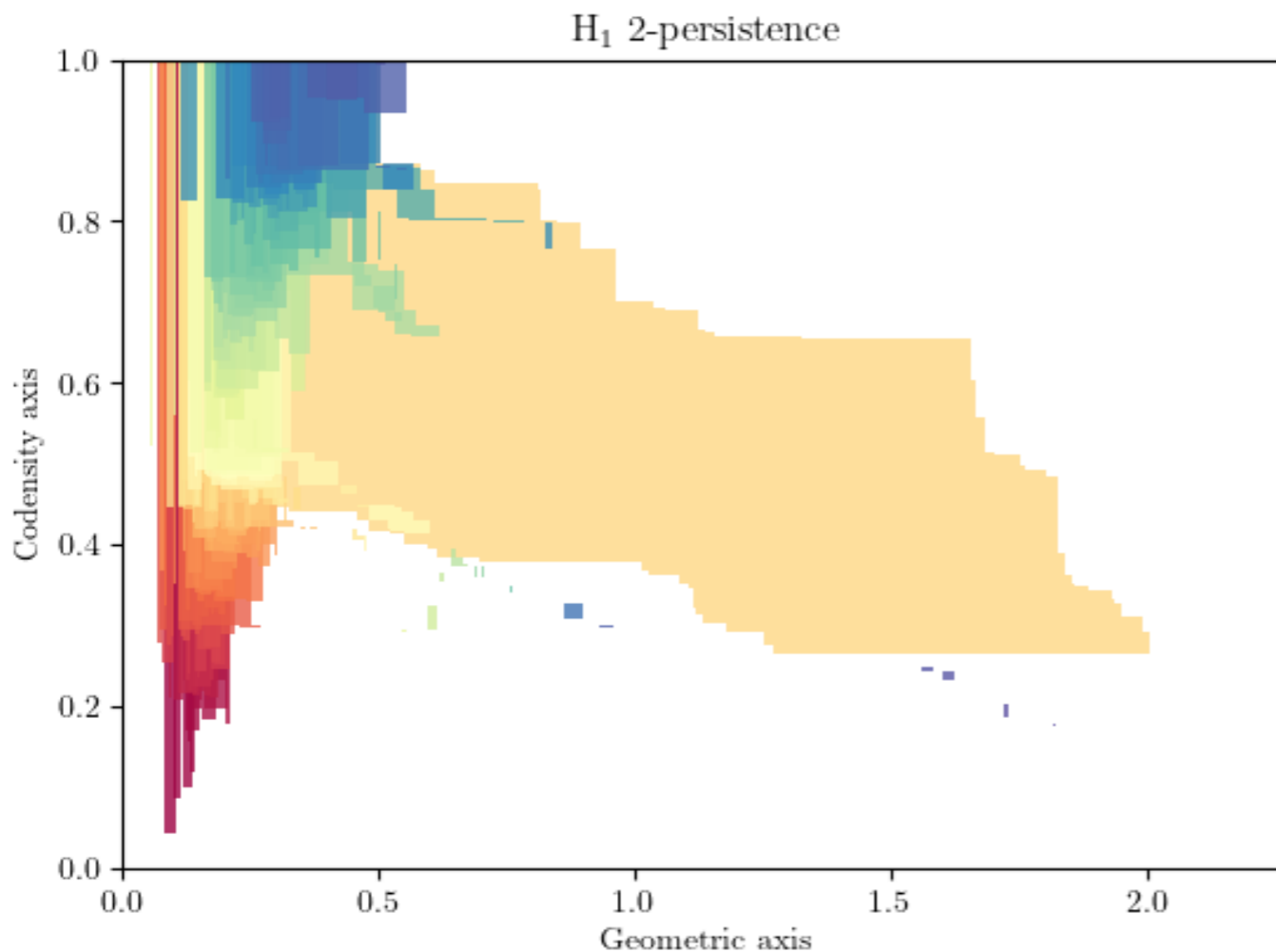
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Appropriate choices of  $\text{op}$ ,  $w$  and  $\phi$  reproduce the multi-parameter landscape, fibered barcode kernel, etc.

# Candidate Decompositions $\rightarrow$ Descriptors

**Ex:** The *stable candidate decomposition representation* (S-CDR) uses:

- $\text{op} = \sum_i$ ,
- $w = \text{longest diagonal in } M_i$ ,
- $\phi_\delta : x \mapsto \text{volume of } M_i \cap B(x, \delta)$



# Stability

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**Th:** Let  $M, M'$  be two candidate decompositions. Then, S-CDR satisfy:

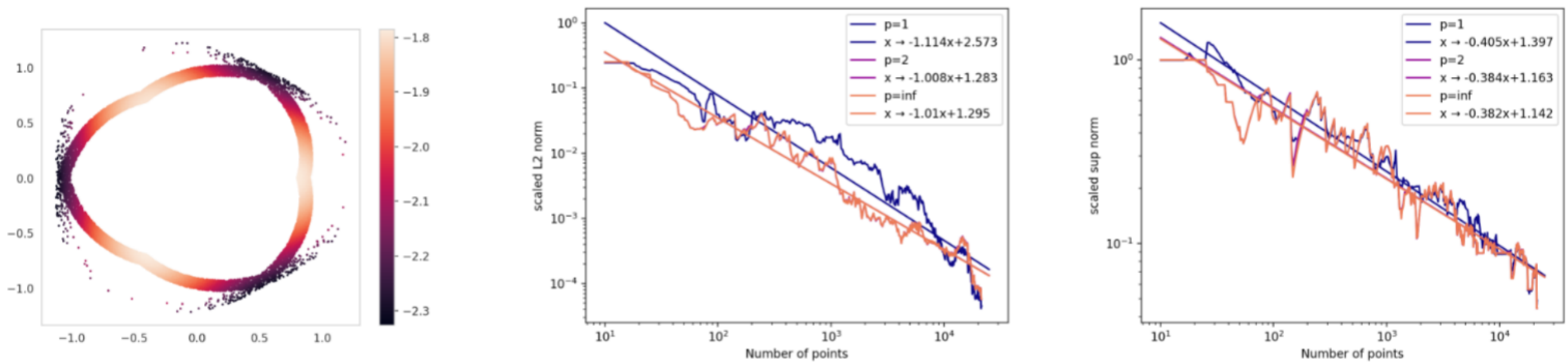
$$\|V(M) - V(M')\|_{\infty} \leq K d_b(M, M') \leq K d_I(M, M').$$

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**Application:** statistical convergence rate:



$$\mathbb{P}(\|V(M) - V(M')\|_{\infty} \geq \varepsilon) \leq \mathbb{P}(d_I(M, M') \geq \varepsilon/K) \leq \mathbb{P}(\|f - f'\|_{\infty} \geq \varepsilon/K).$$

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**Application:** accuracies in classification tasks:

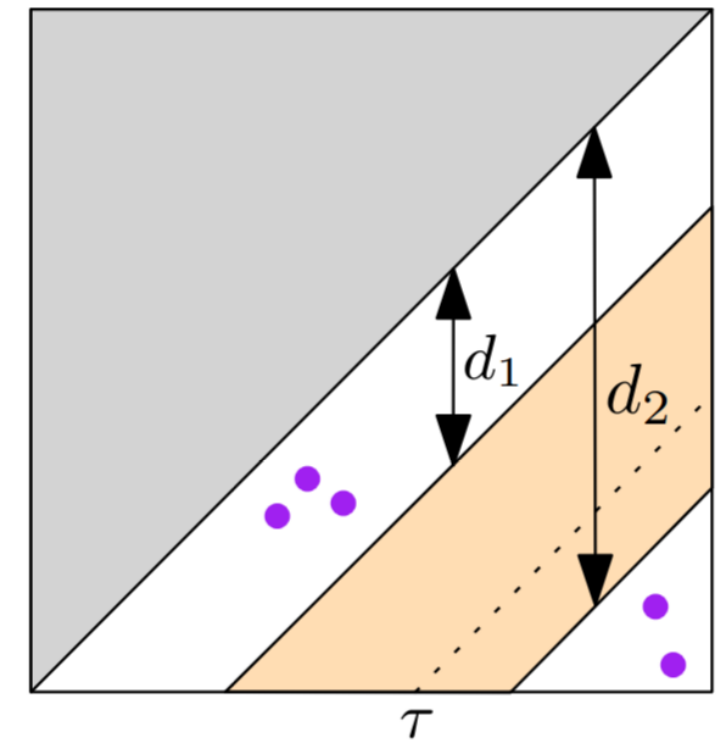
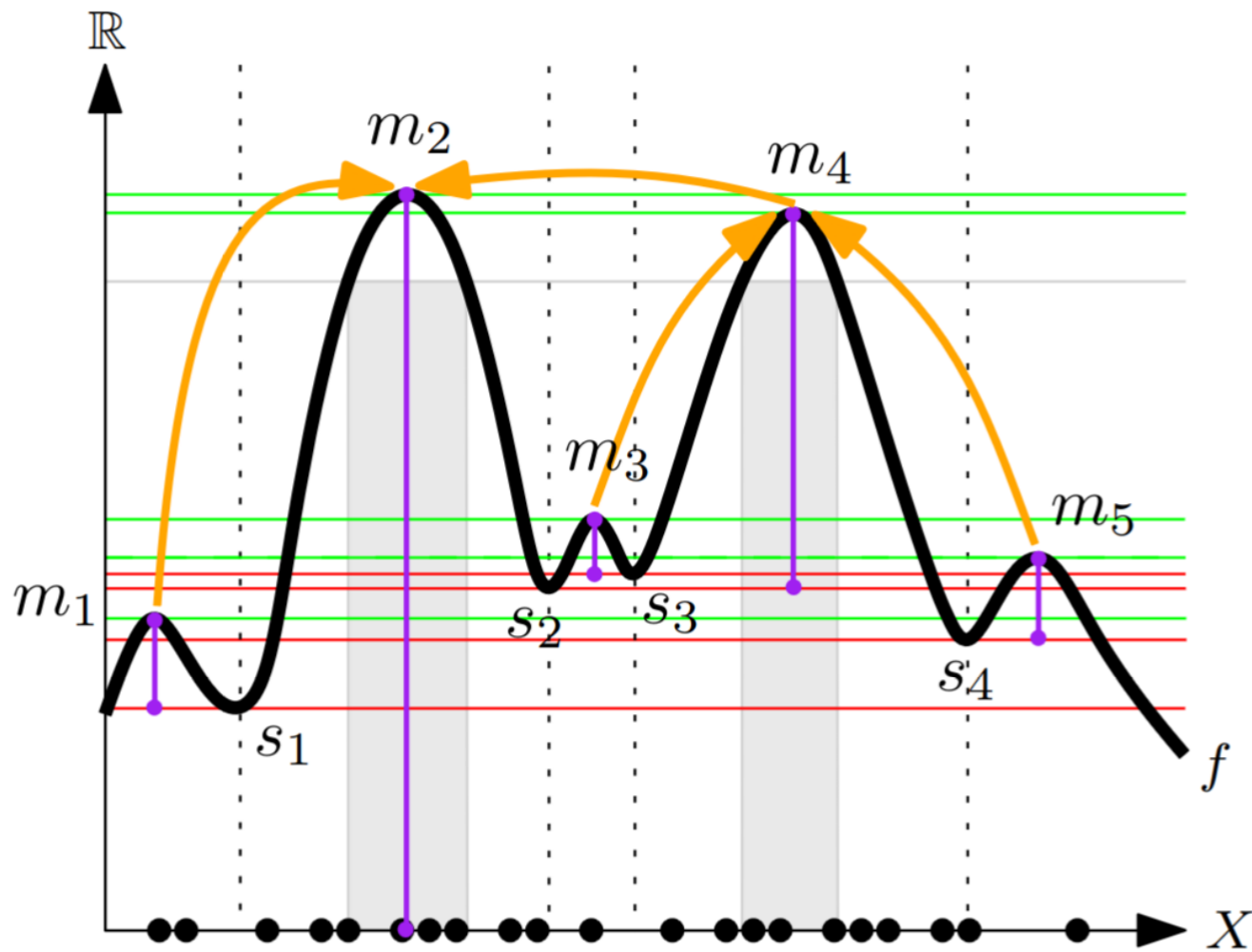
Dataset	B1	B2	B3	PSS-K	P-I	P-L	MPK	MPL	MPI	S-CDR (Rips + KDE)	S-CDR (Alpha + DTM)
DPOAG	62.6	62.6	<b>77.0</b>	<u>76.9</u>	69.8	70.5	67.6	70.5	71.9	71.9	71.9
DPOC	71.7	72.5	71.7	47.5	67.4	66.3	<b>74.6</b>	69.6	71.7	73.8	<b>74.6</b>
PPOAG	78.5	78.5	80.5	75.9	82.0	78.0	<u>78.0</u>	78.5	81.0	81.9	<b>84.9</b>
PPOC	80.8	79.0	78.4	78.4	72.2	72.5	78.7	78.7	81.8	79.4	<b>83.2</b>
PPTW	70.7	75.6	75.6	61.4	72.2	73.7	<b>79.5</b>	73.2	76.1	75.6	75.1
IPD	<b>95.5</b>	<b>95.5</b>	95.0	-	64.7	61.1	80.7	78.6	71.9	<u>81.2</u>	77.2
GP	91.3	91.3	90.7	90.6	84.7	80.0	88.7	94.0	90.7	<b>96.3</b>	92.7
GPAS	89.9	<b>96.5</b>	91.8	-	84.5	87.0	93.0	85.1	90.5	88.0	<u>93.7</u>
GPMVF	97.5	97.5	<b>99.7</b>	-	88.3	87.3	<u>96.8</u>	88.3	95.9	95.3	95.9
PC	<b>93.3</b>	92.2	87.8	-	83.4	76.7	85.6	84.4	86.7	<u>93.1</u>	90.0
	Ripley			P			MPL			S-CDR	
Immuno	67.2(2.3)			60.7(4.2)			65.3(3.0)			<b>91.4(1.6)</b>	

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[Andrianirina, C., ToMAToMP: Robust and Multi-parameter Topological Clustering. Preprint, 2026]

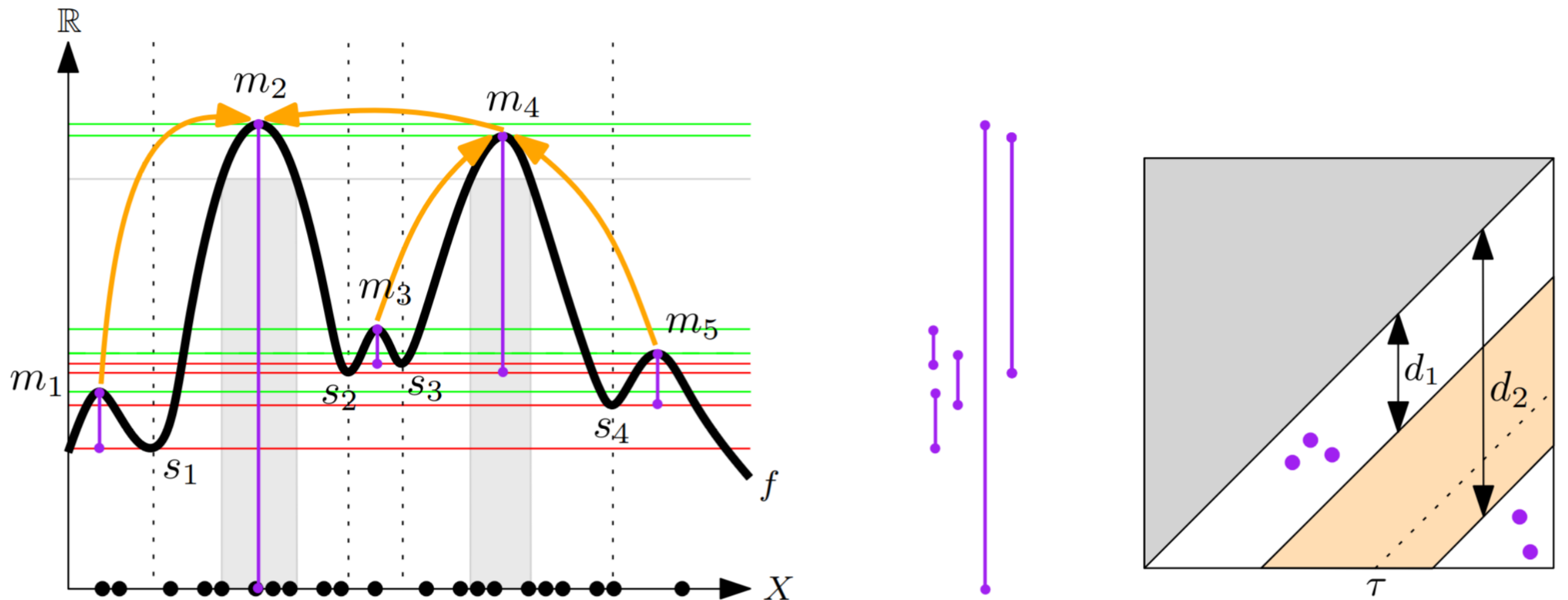
# Persistence-based Clustering: ToMATo

ToMATo (Topological Mode Analysis Tool) uses 0-th persistence of a function  $f$  to cluster data, using an input graph  $G$  and persistence threshold  $\tau$ .



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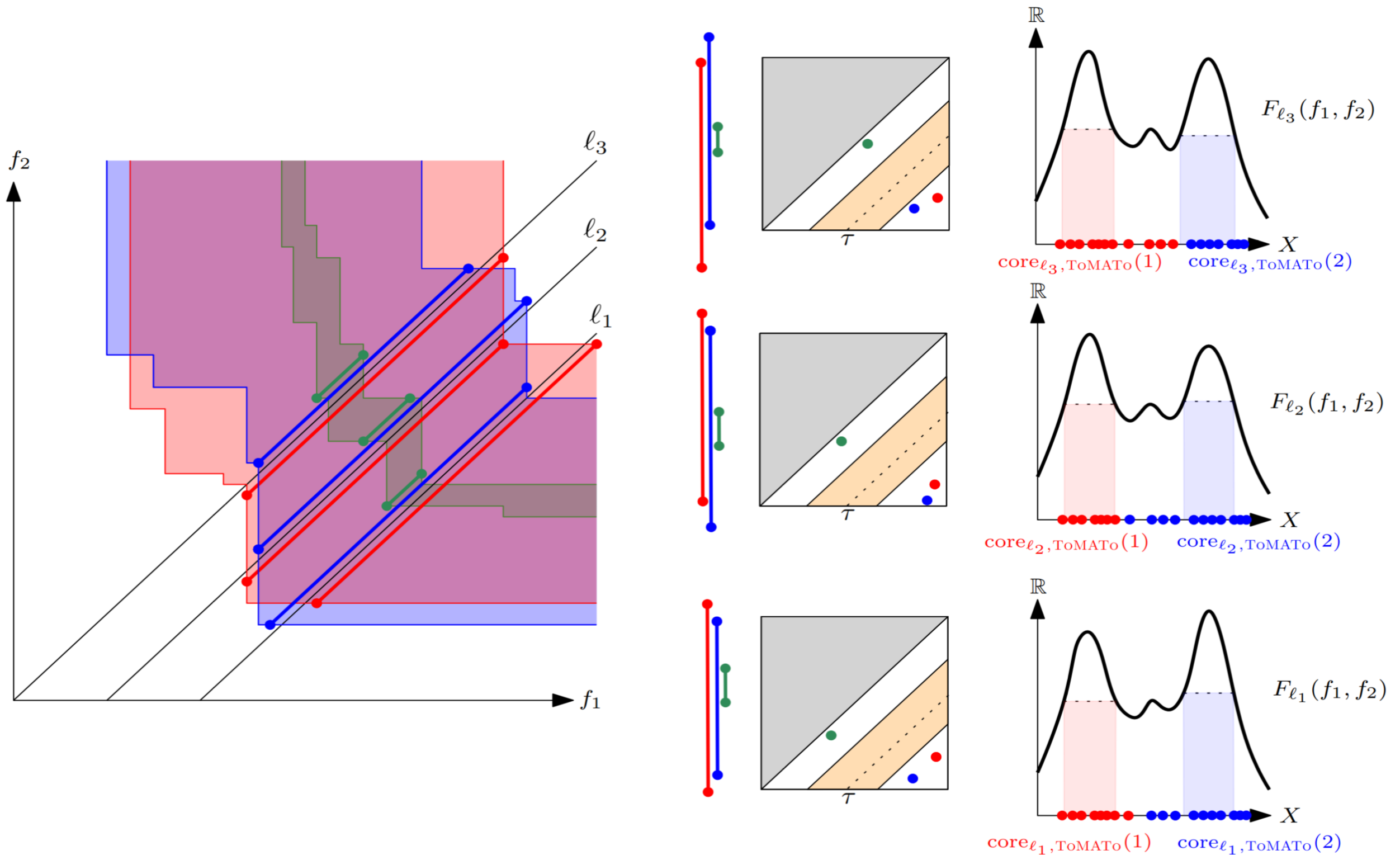
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**Goal:** Use candidate decompositions to avoid dependence on  $G$  (using  $f + \text{Rips}$ ) + improve robustness to outlier values (using  $f + \text{outlier score}$ ).

# Multi-parameter Clustering: ToMAToMP

**Idea:** ToMAToMP: apply ToMATo on lines and pick majoritary labels.



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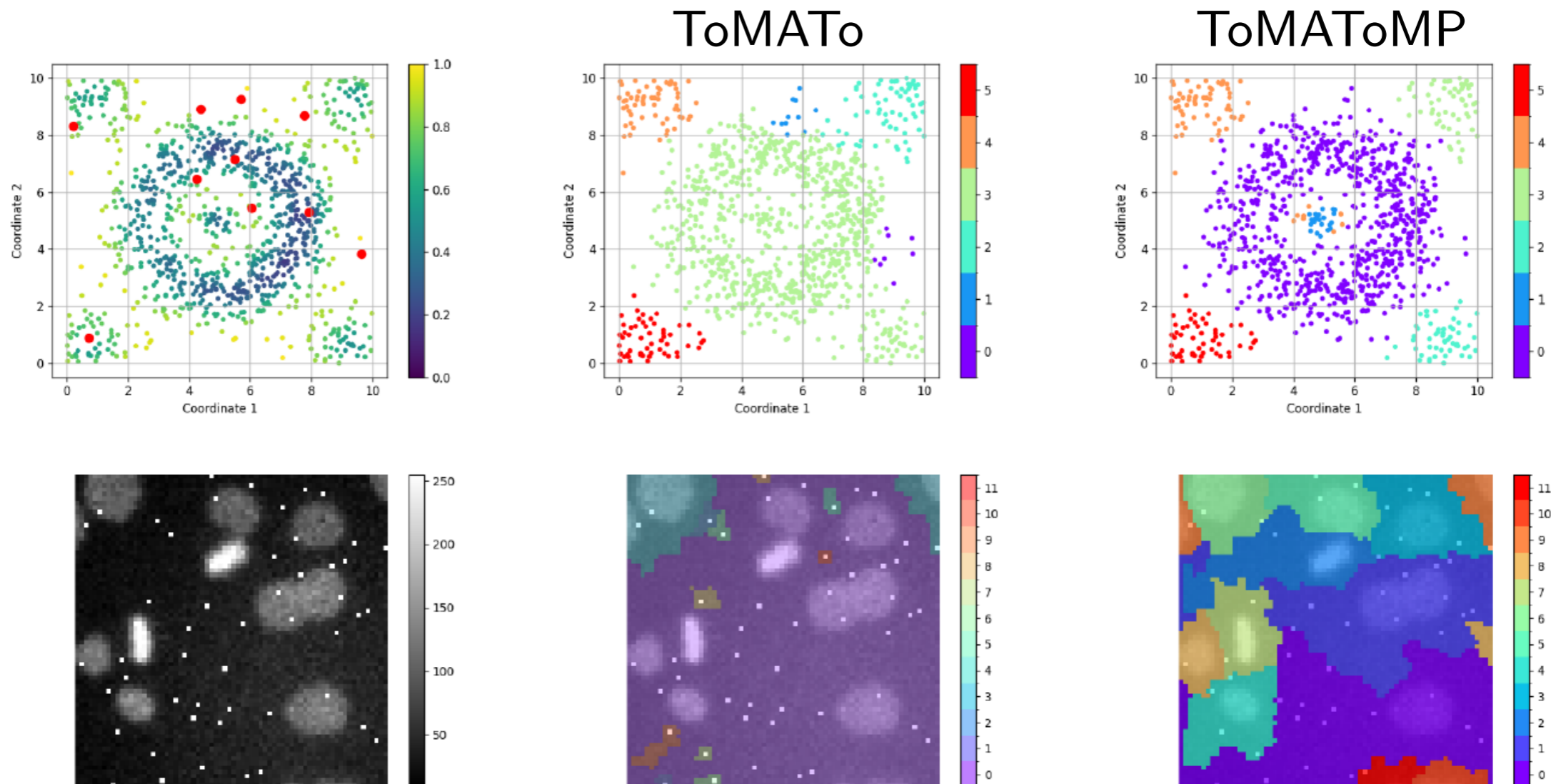
**Th:** If the fibered barcode is sufficiently separated, and  $\tau$  is chosen accordingly, then ToMAToMP produces the right number of clusters.

# Multi-parameter Clustering: ToMAToMP

**Idea:** ToMAToMP: apply ToMATo on lines and pick majoritary labels.

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**Application:** clustering with outliers values.

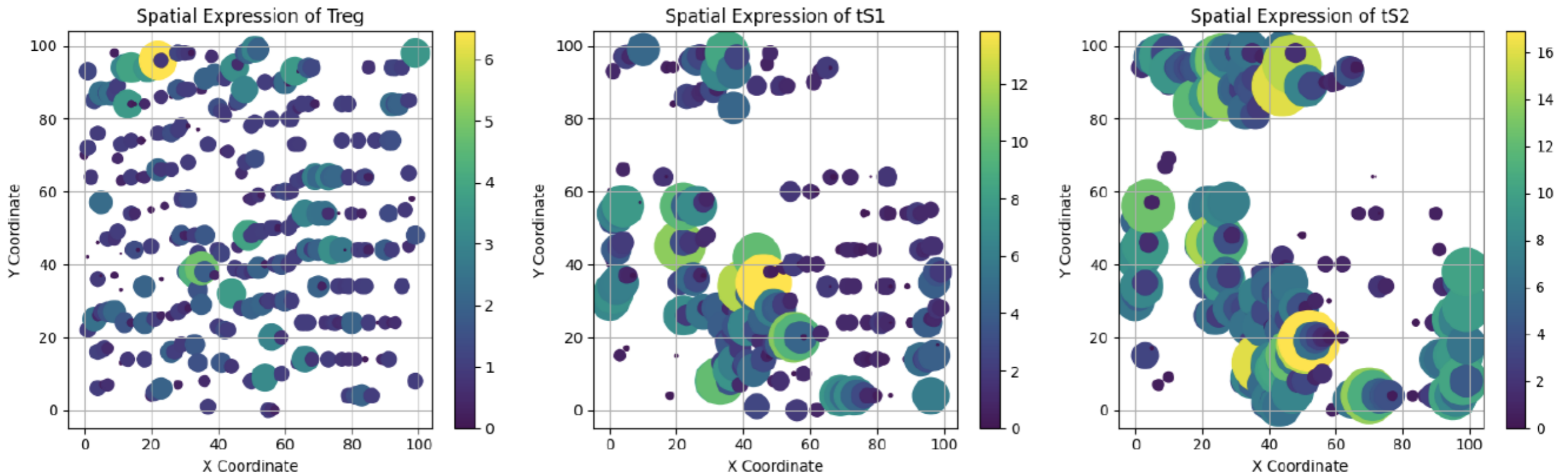


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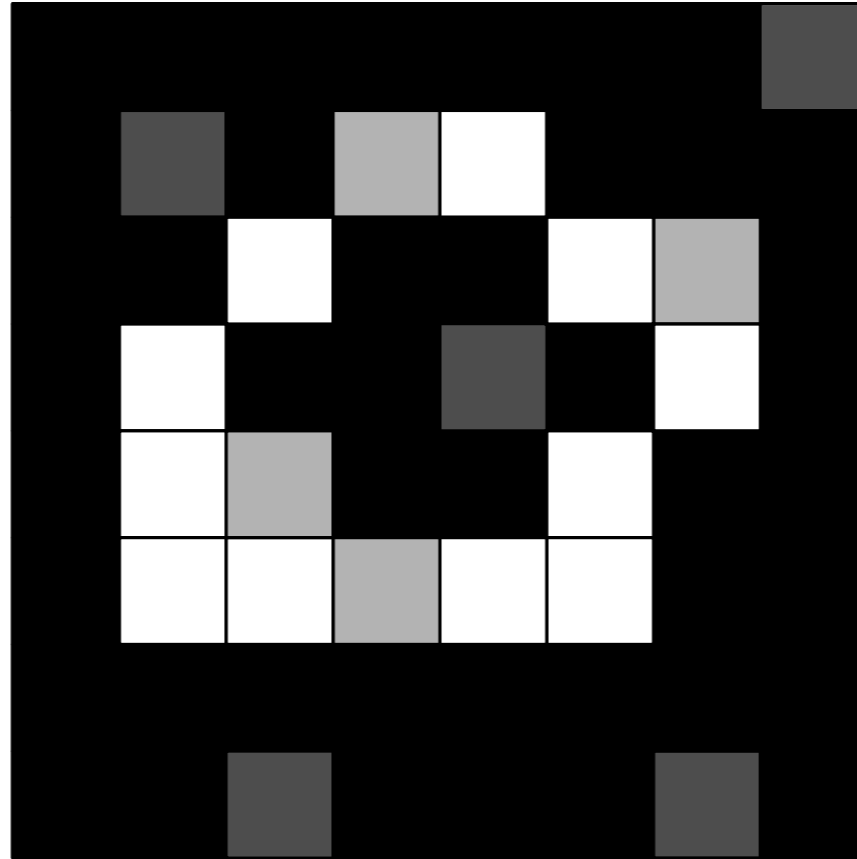
**Application:** gene co-localization in spatial transcriptomics.



Thank you!

# What is Single Parameter Persistence?

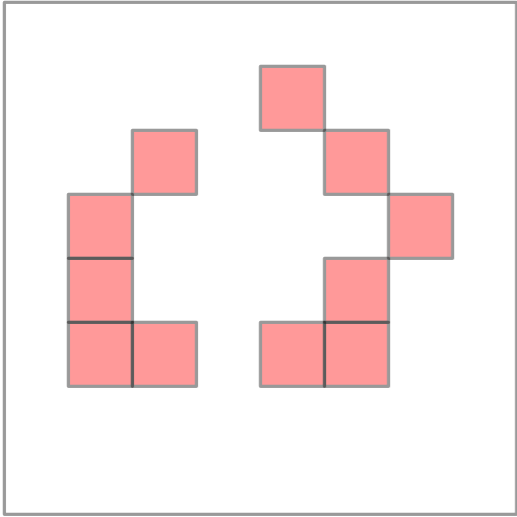
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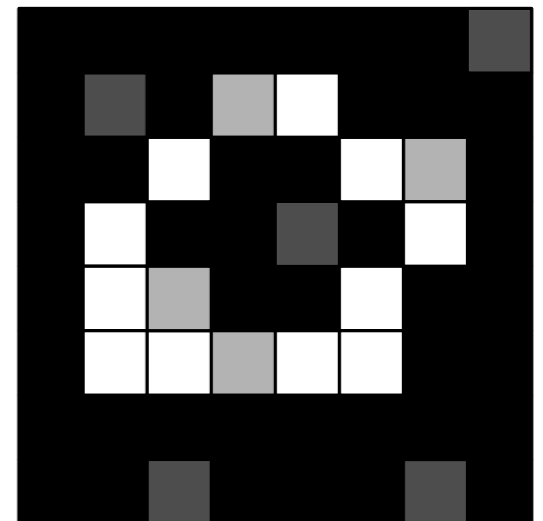
$f$  is grey-level function

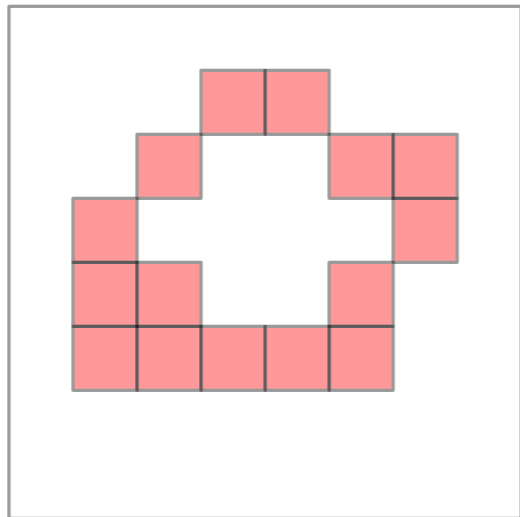
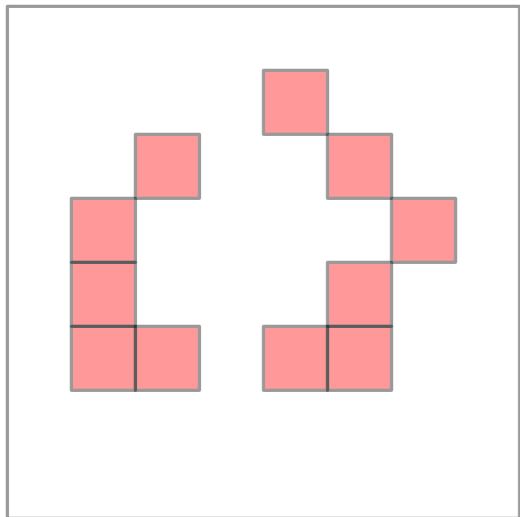
Encode topology of **sublevel sets** of  $f$   
(**filtration** induced by  $f$ )

$$X_\alpha := f^{-1}((-\infty, \alpha]) \text{ for all } \alpha \in \mathbb{R} \cup \{+\infty\}$$



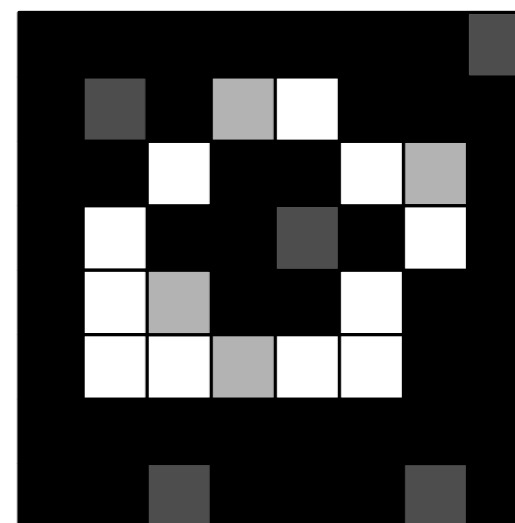
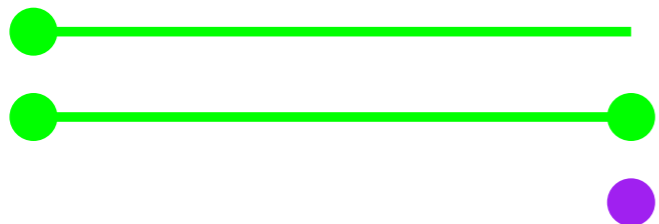
$$f \leq \square$$

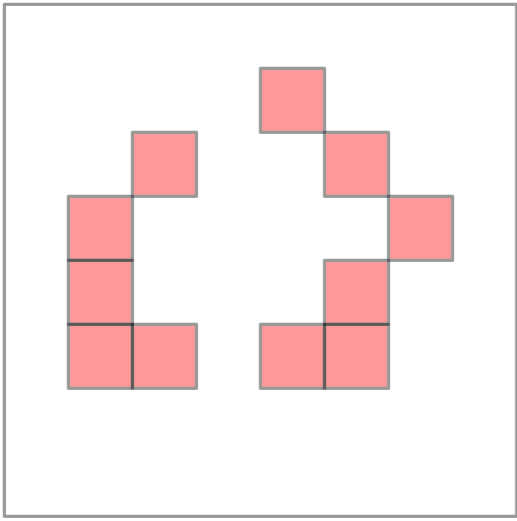




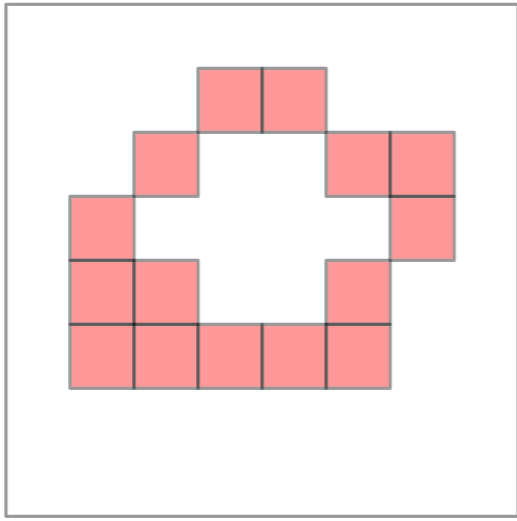
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$f \leq \blacksquare$

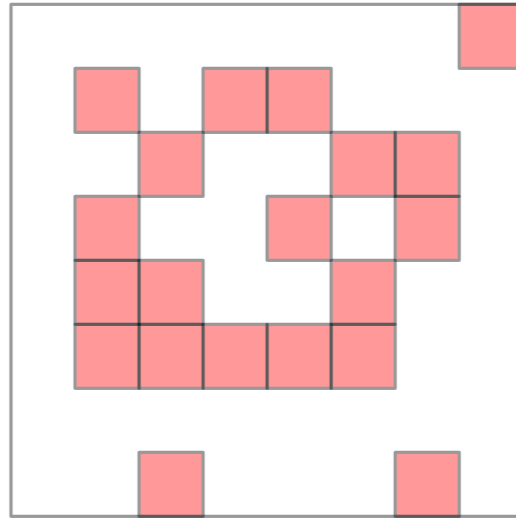




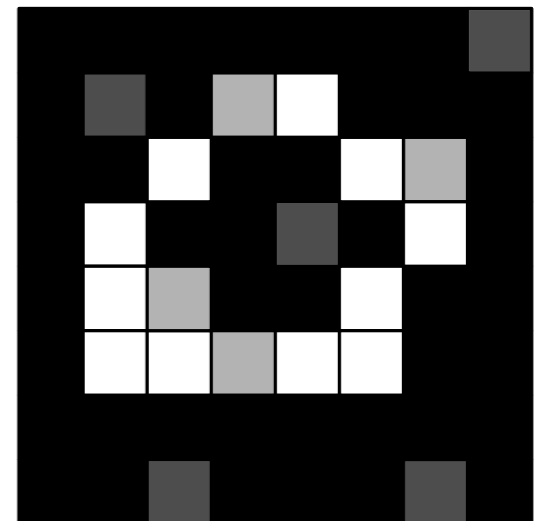
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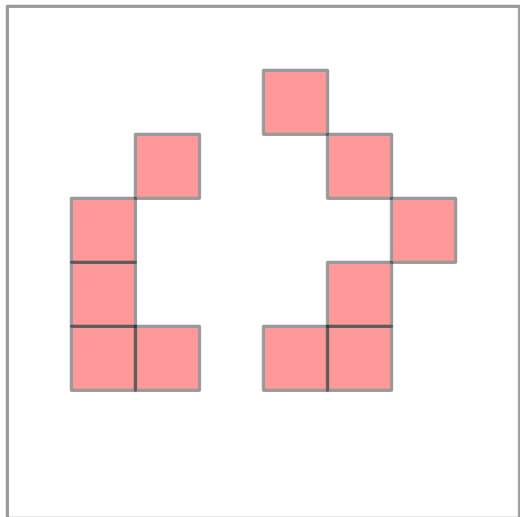


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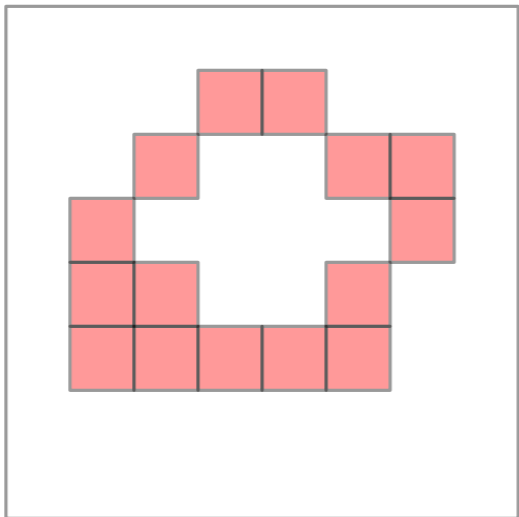


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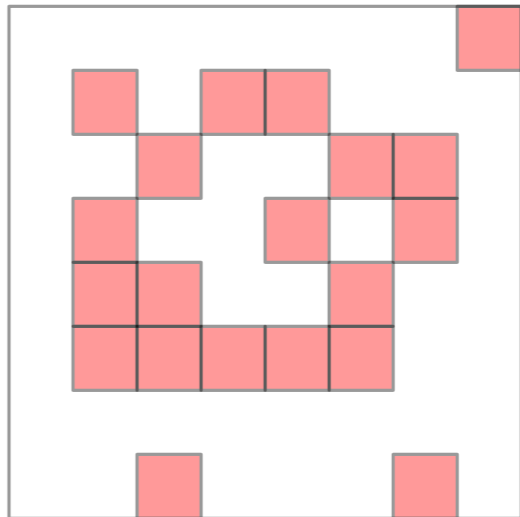




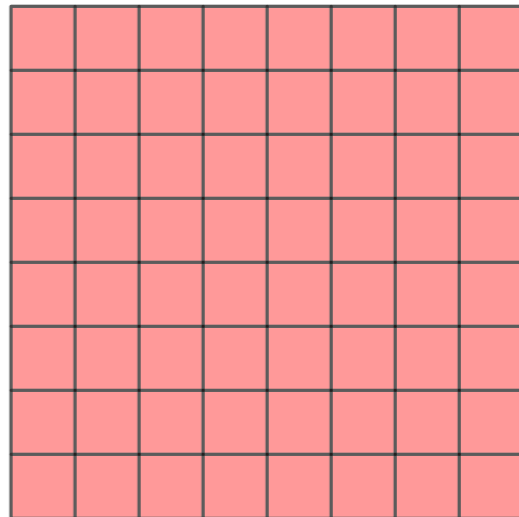
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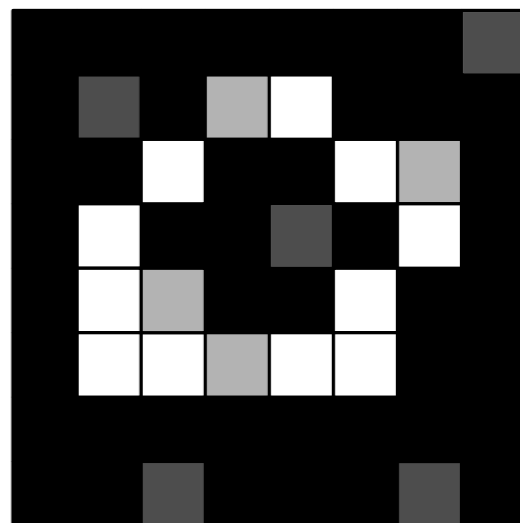
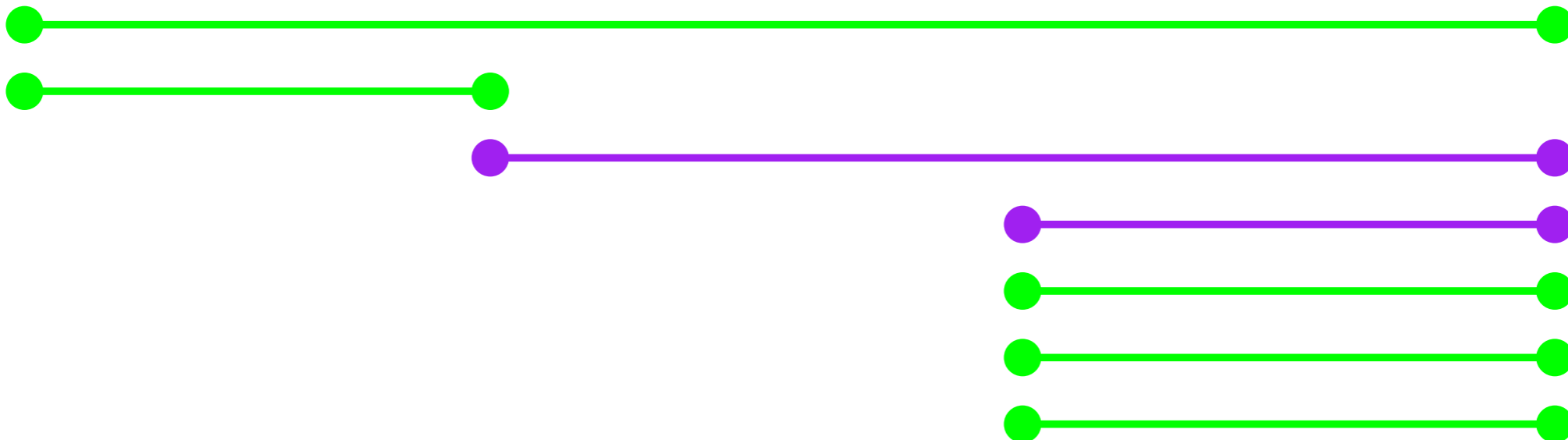
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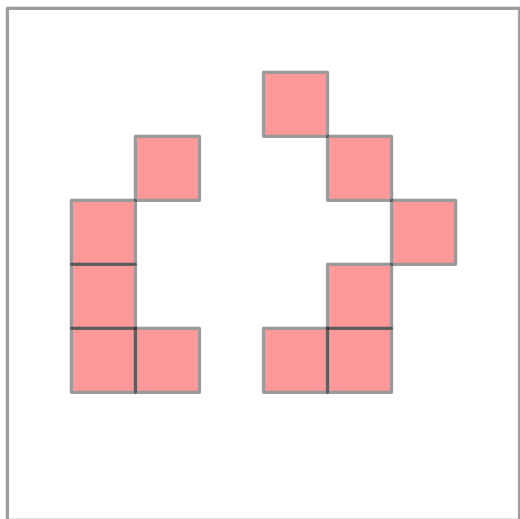


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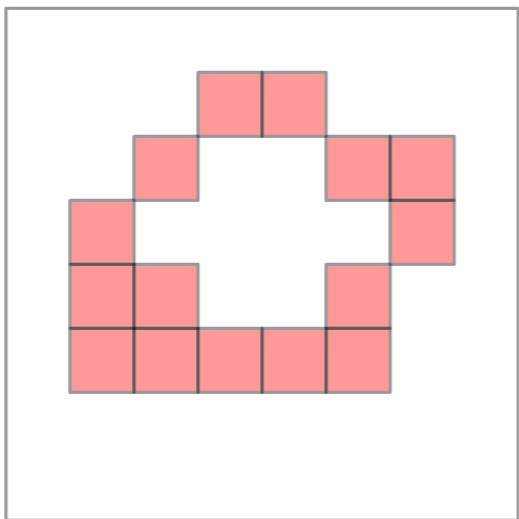


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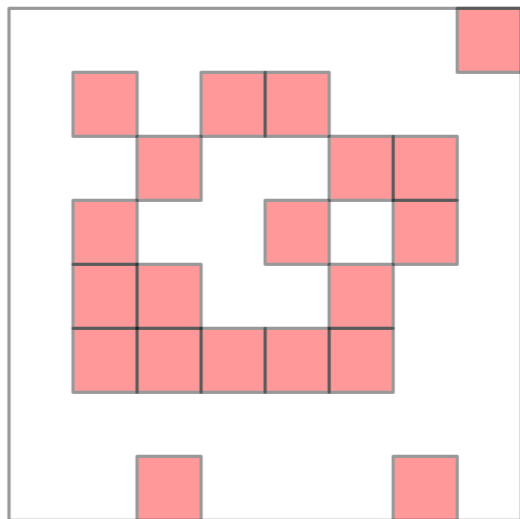




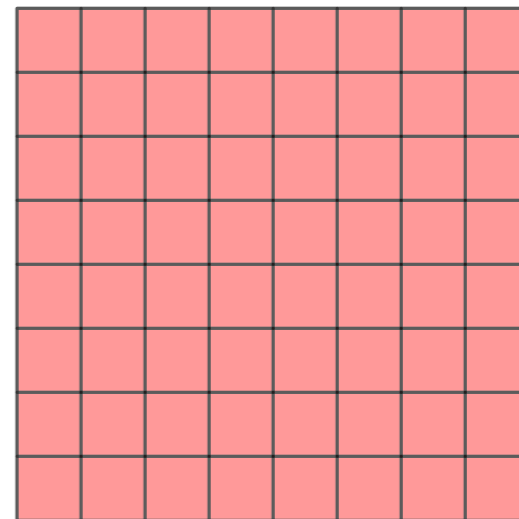
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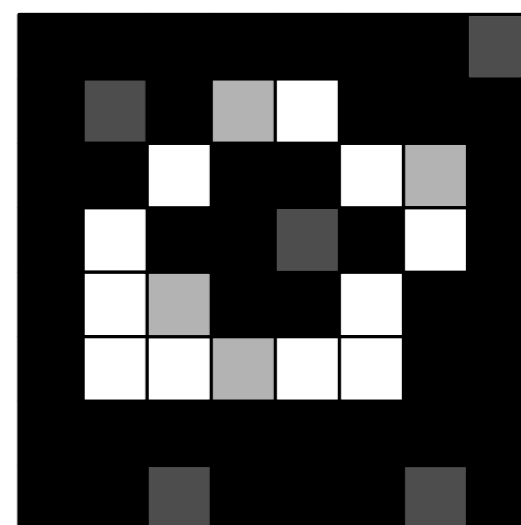
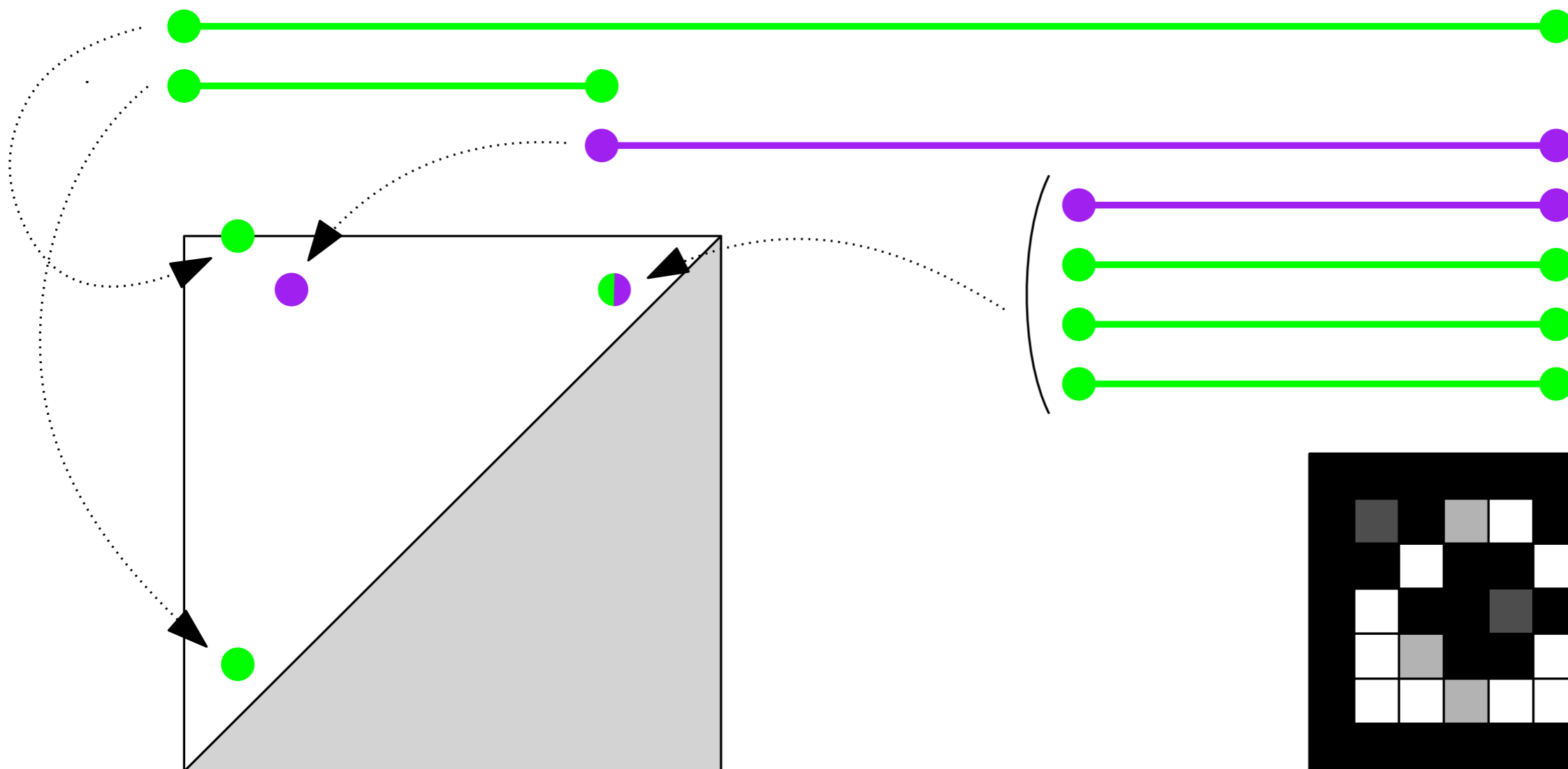
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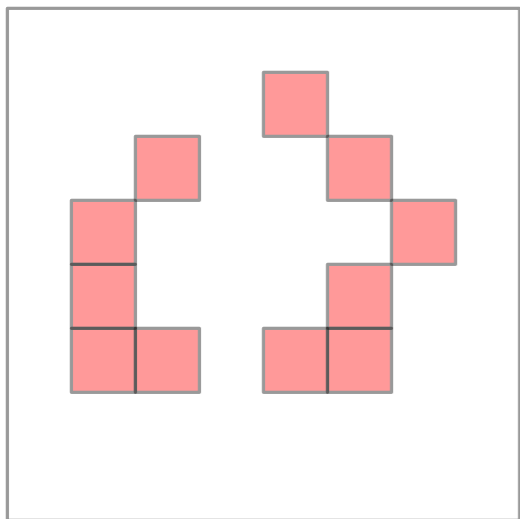


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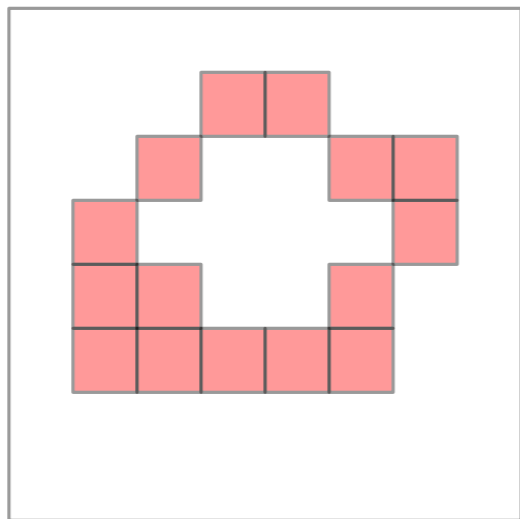


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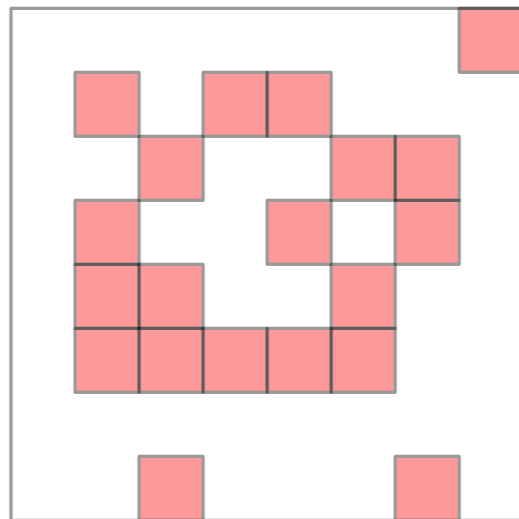




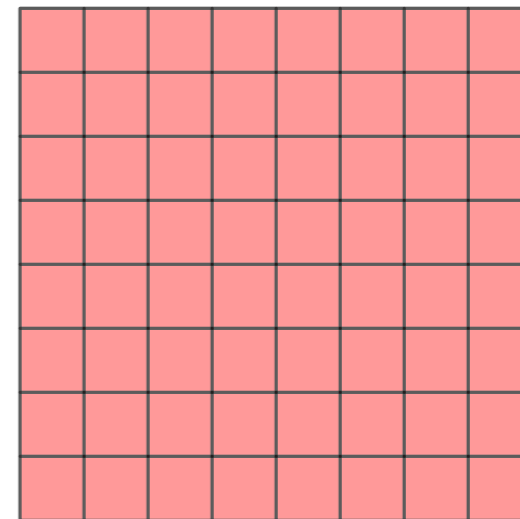
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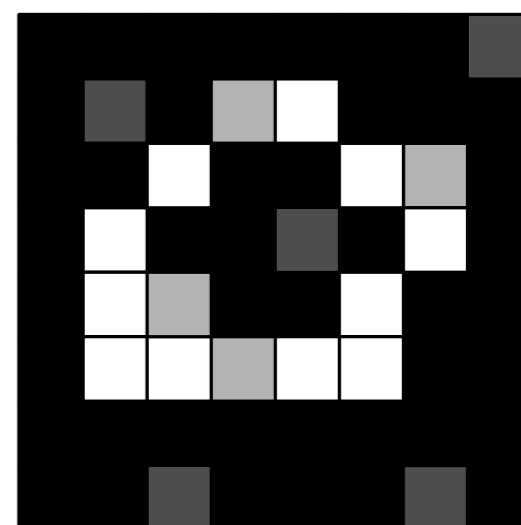
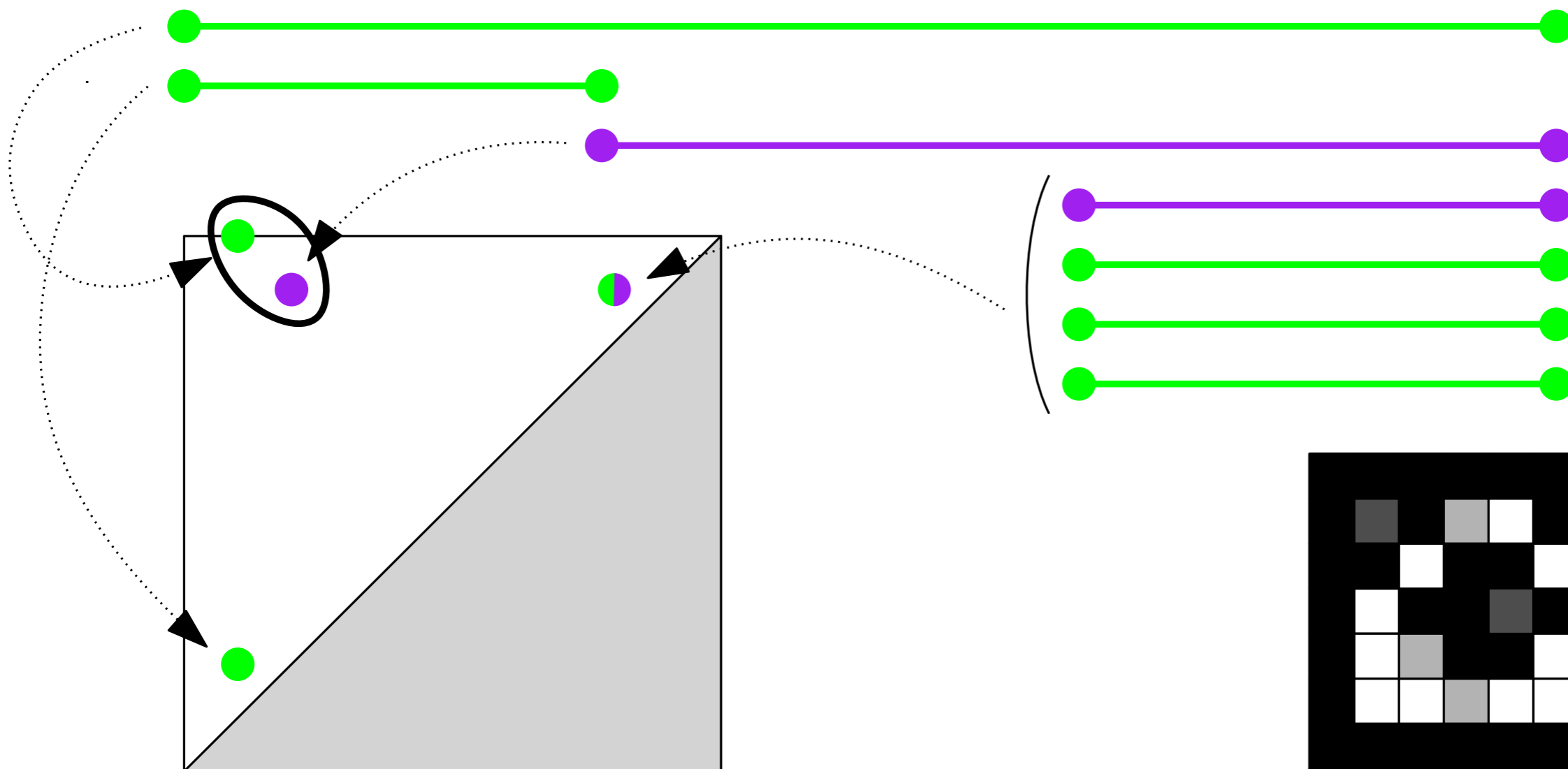
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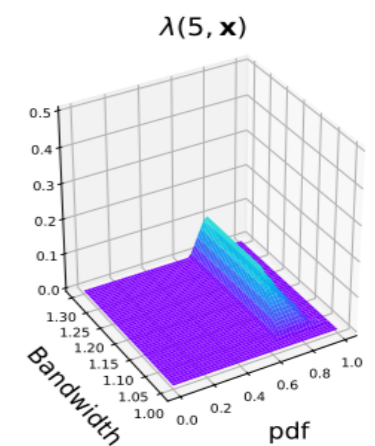
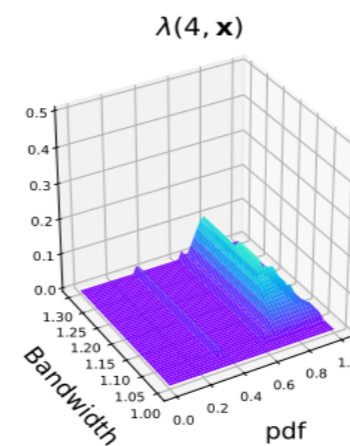
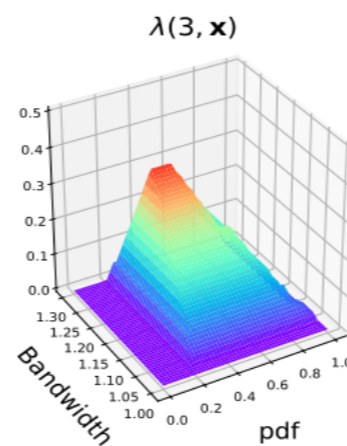
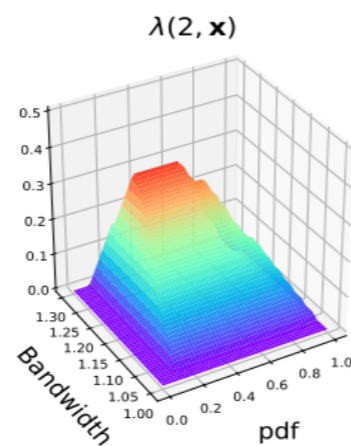
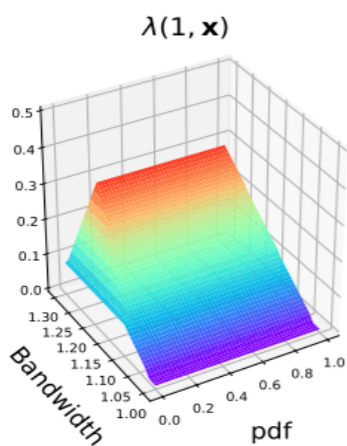
# Statistics/Invariants Based on Persistent Betti Numbers

**Def:** Let  $M$  be a multiparameter persistence module. The multiparameter persistence landscape  $\lambda(M)$  is defined as:

$$\lambda(M)(p, x) = \sup\{\epsilon > 0 : \beta^{x-h, x+h} \geq p, h \geq 0, \|h\|_\infty \leq \epsilon\}$$

Since  $\text{rk}(M)(x - h, x + h) \leq \text{rk}(M)(x - \epsilon \cdot \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix}, x + \epsilon \cdot \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix})$

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**Def:** Let  $M, M'$  be multiparameter persistence modules. Let  $K$  be a kernel ("scalar product") between 1D persistence diagrams and  $L$  be a family of lines. The multiparameter persistence kernel is defined as:

$$K(M, M') = \frac{1}{|L|} \sum_{\ell \in L} w(\ell) \cdot K(D(M|_\ell), D(M'|_\ell))$$

# What are Convergence Rates and Confidence Intervals?

A convergence rate is an inequality of the form:

$$\mathbb{E}[d(\hat{X}_n, X^*)] \leq f(n) \text{ with } f(n) \xrightarrow[n \rightarrow \infty]{} 0,$$

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Deriving a convergence rate gives confidence intervals "for free" with:

$$\mathbb{E}[d(\hat{X}_n, X^*)] = \int_{\varepsilon=0}^{+\infty} \mathbb{P}[d(\hat{X}_n, X^*) > \varepsilon] d\varepsilon$$

# Application to Support Estimation

---

Let  $\hat{X}_n$  be a point cloud obtained from sampling a probability distribution  $\mu_X$  with compact support  $X \subseteq \mathbb{R}^d$ , and let  $\mu_{\hat{X}_n}$  be its corresponding distribution.

Convergence rates for probability distributions supported on  $\mathbb{R}^d$ :

$$\mathbb{E}[W_p(\mu_{\hat{X}_n}, \mu_X)] \leq C_p n^{-1/d},$$

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$$\text{Then: } d_I(\hat{M}_n, M) \leq d_{\text{Pr}}(\mu_{\hat{X}_n}, \mu_X) \leq W_p(\mu_{\hat{X}_n}, \mu_X)^{\frac{p}{p+1}}$$

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Hence, it only suffices to find Lipschitz persistence module invariants  $\Phi(M)$ , i.e., such that  $\|\Phi(M) - \Phi(M')\| \leq C \cdot d_I(M, M')$ , in order to retrieve convergence rates/confidence intervals (for  $\Phi(M)$ )!!

# Application to Sublevel Sets

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Stability theorem for multiparameter persistence modules obtained from sublevel sets of multivariate function:

$$\text{Then: } d_I(M(f), M(g)) \leq \|f - g\|_\infty.$$

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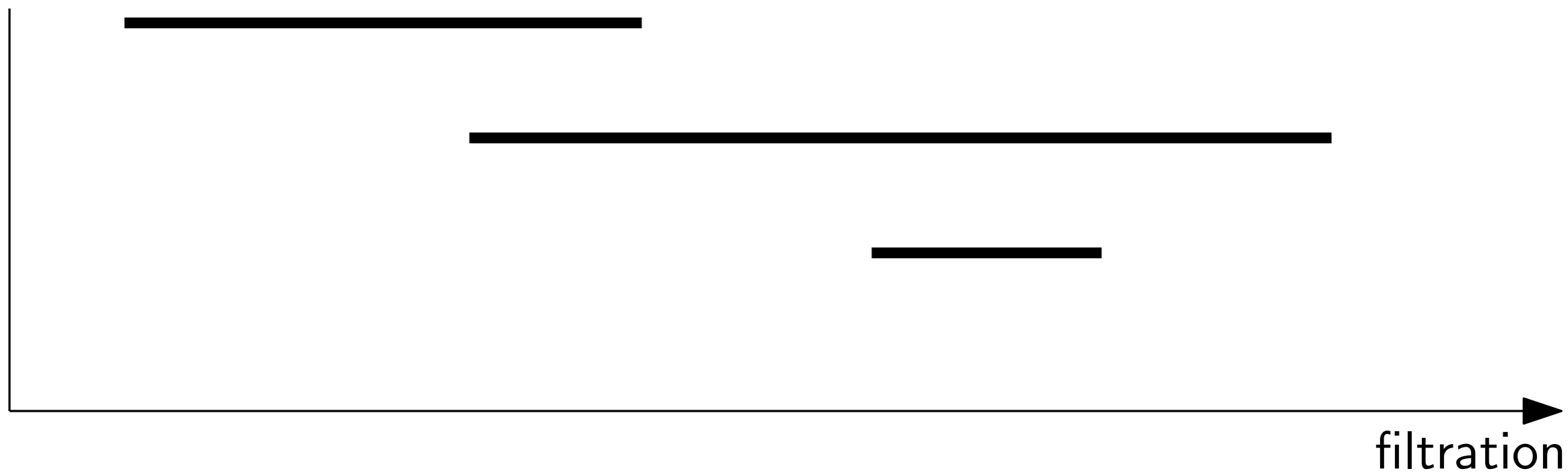
As well as the rate of convergence of Hausdorff distance:

$$\mathbb{E} \left[ d_H(X, \hat{X}_n) \right] \leq C \cdot \left( \frac{\log(n)}{n} \right)^{1/d}.$$

# The Single Parameter Case

---

Let's look at the barcode:

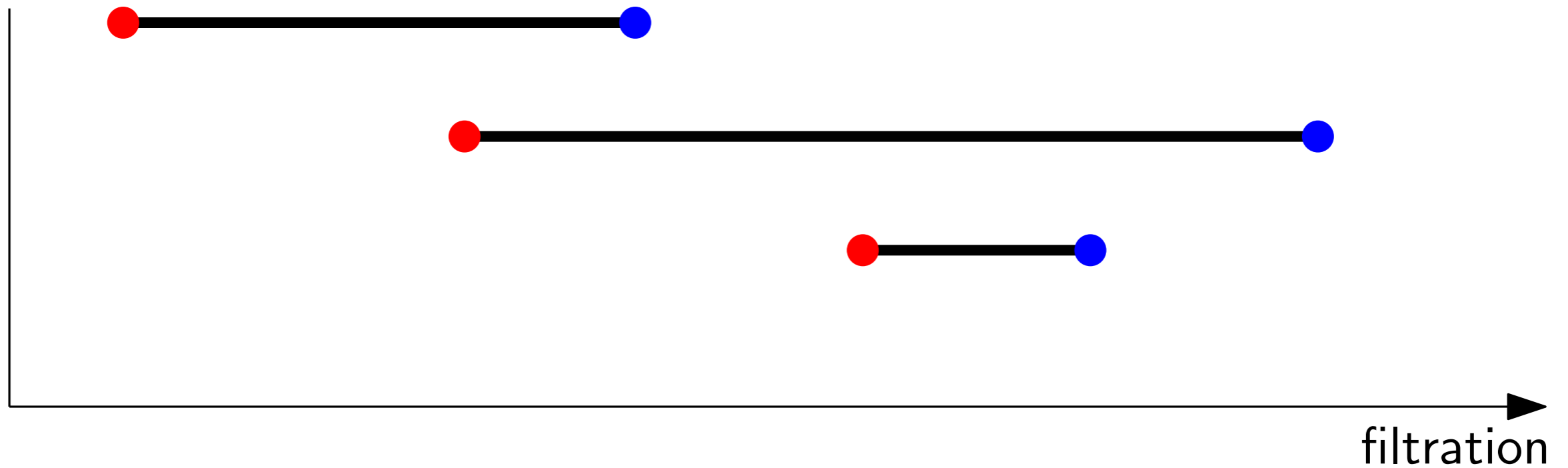


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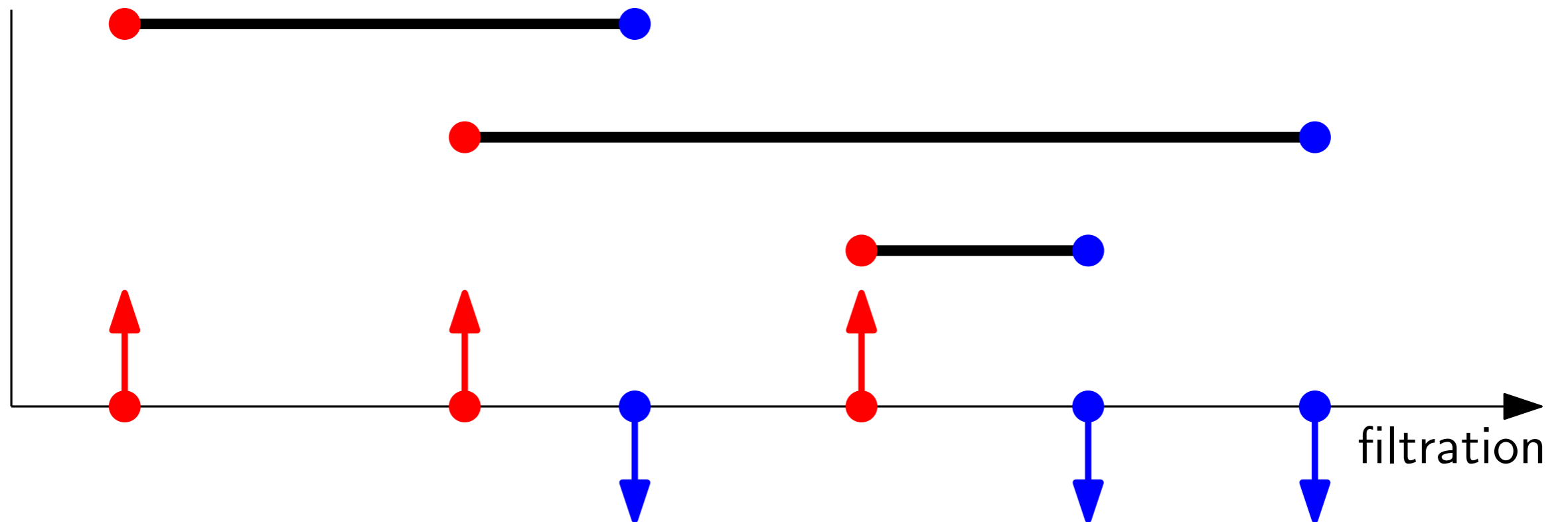


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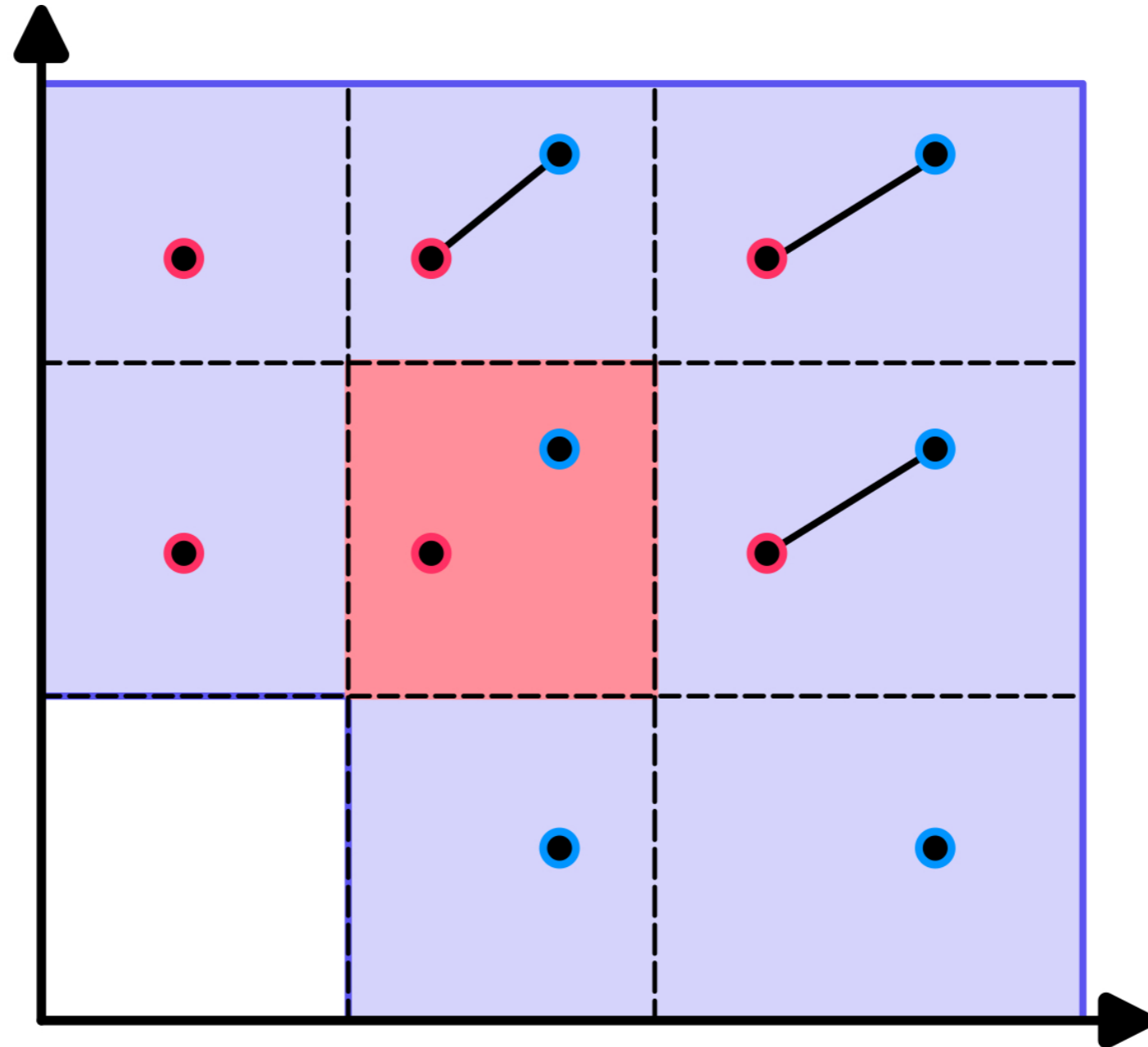
It has birth and death times, that can be interpreted as an empirical measure, of total mass 0.



# Extension to the Multiparameter Case

---

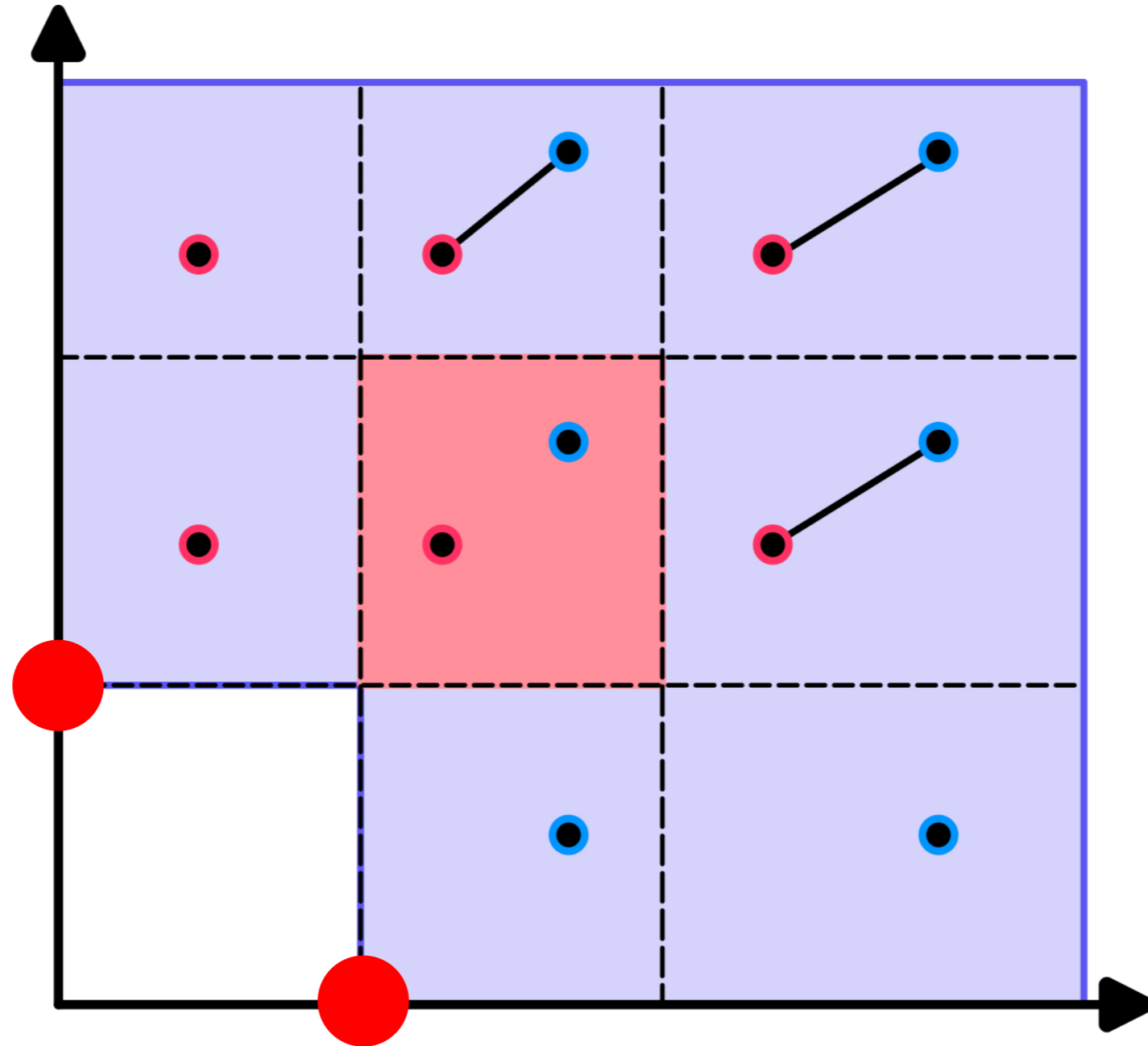
The same game can be played on multiparameter persistence modules!



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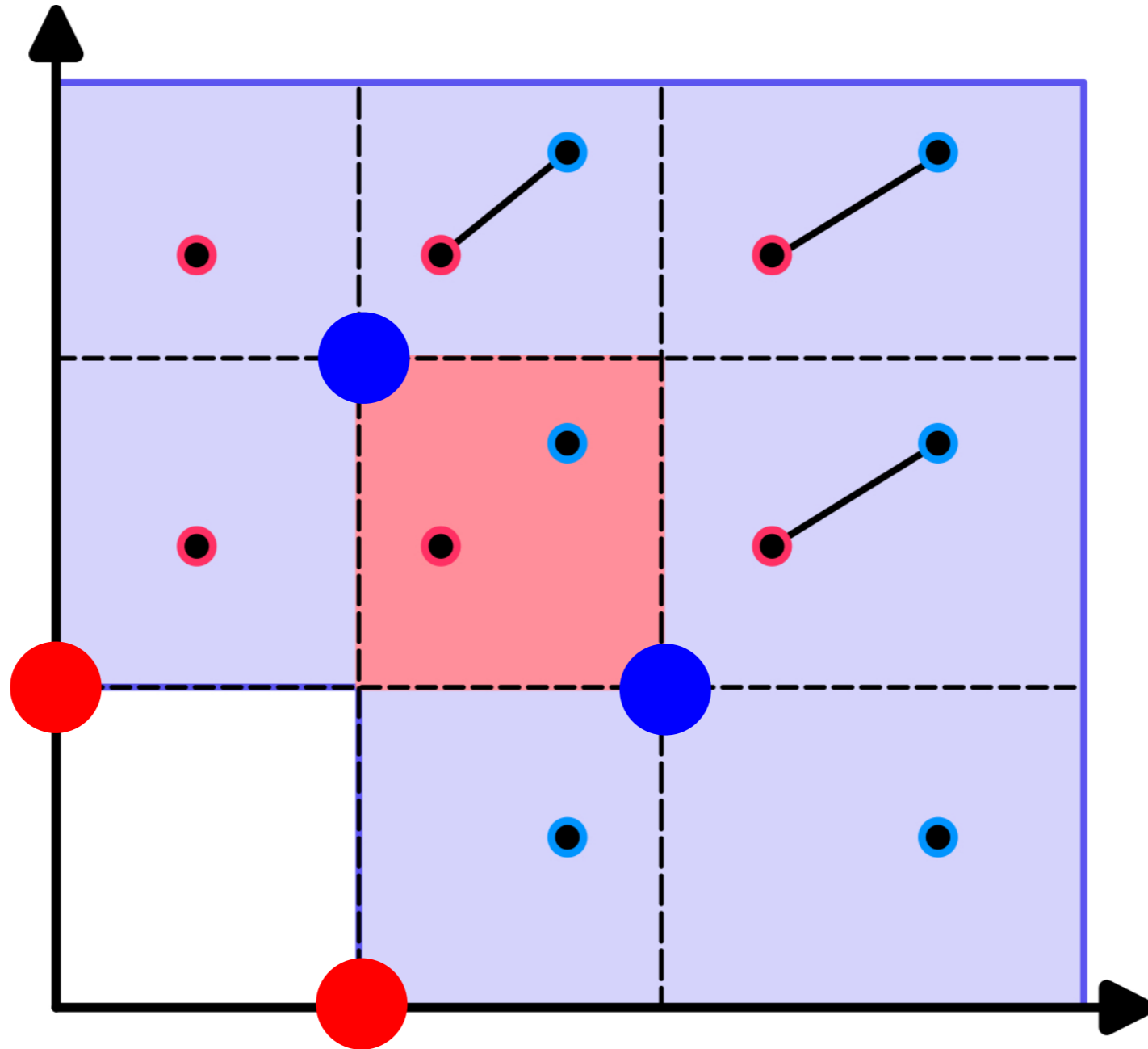
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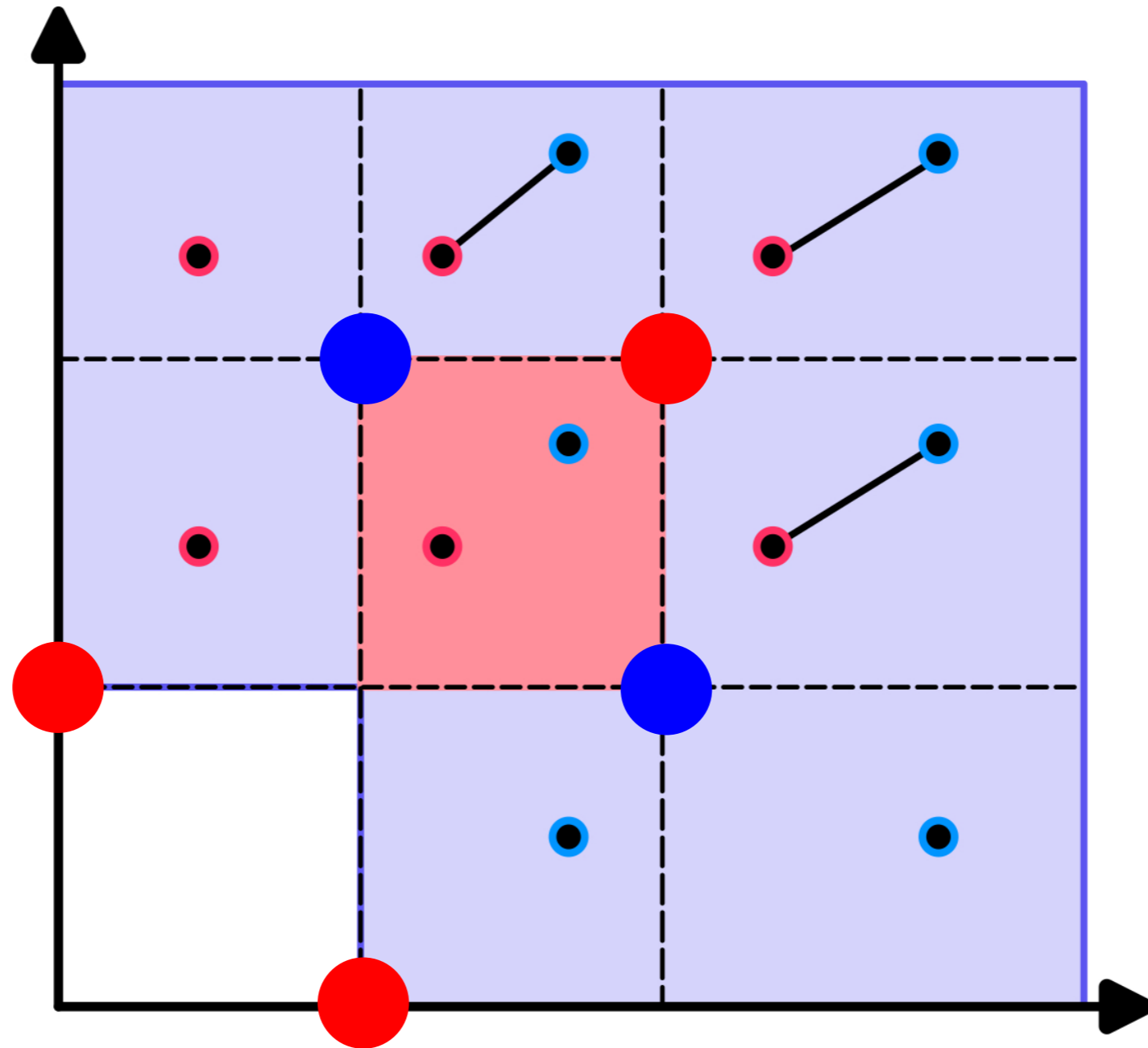
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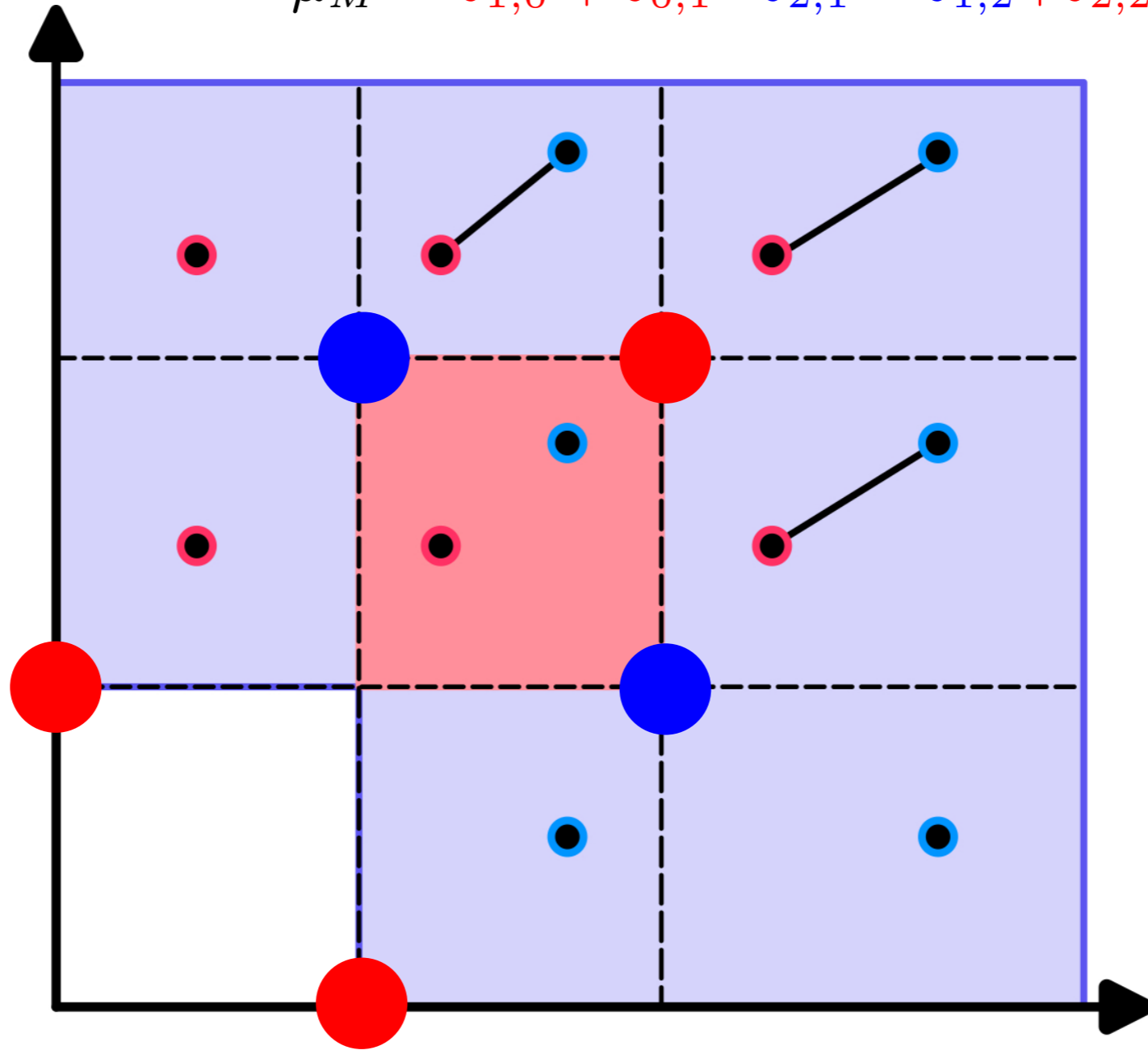


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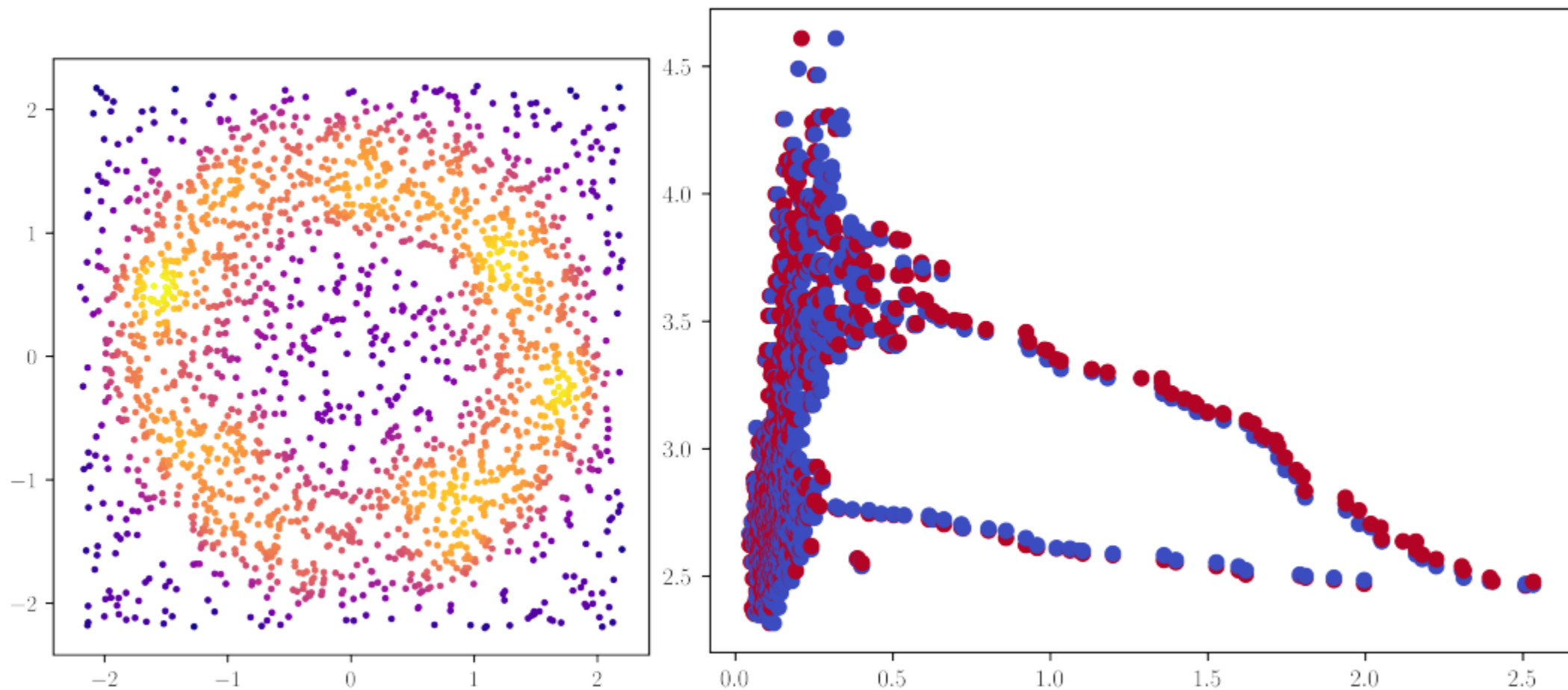
$$\mu_M = \delta_{1,0} + \delta_{0,1} - \delta_{2,1} - \delta_{1,2} + \delta_{2,2}$$



# Extension to the Multiparameter Case

**Prop:** For any finitely presentable multiparameter persistence module  $M$ , there exists a unique discrete Radon measure  $\mu_M$  such that:

$$\forall x \in \mathbb{R}^n, \dim(M_x) = \mu_M(\{y \in \mathbb{R}^n \mid y \leq x\}).$$

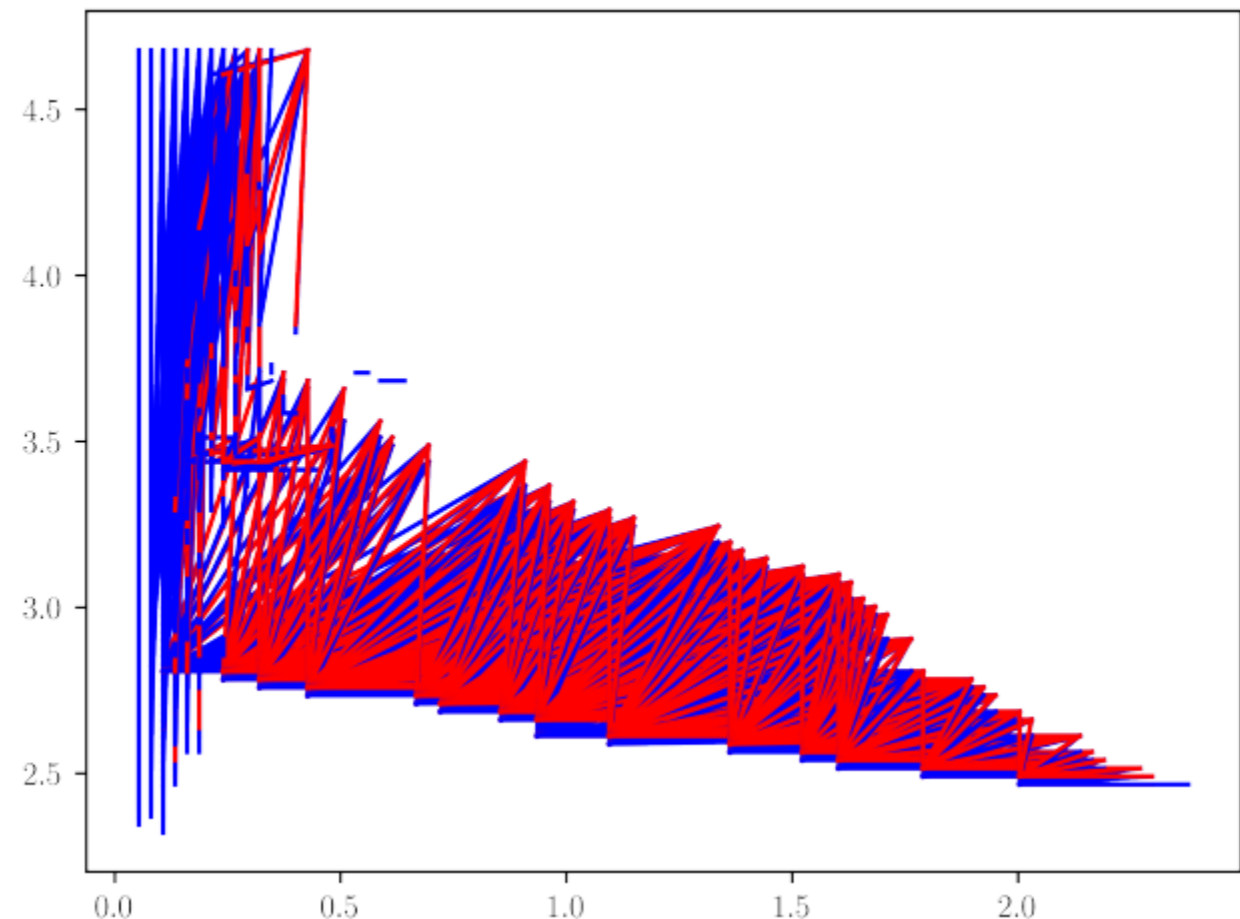
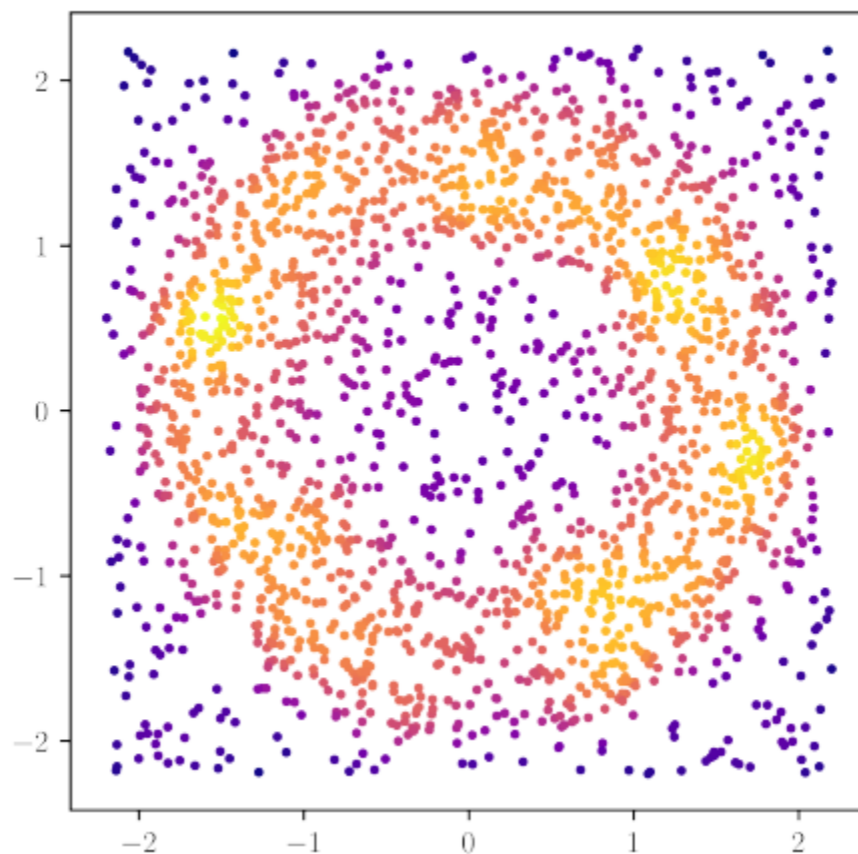


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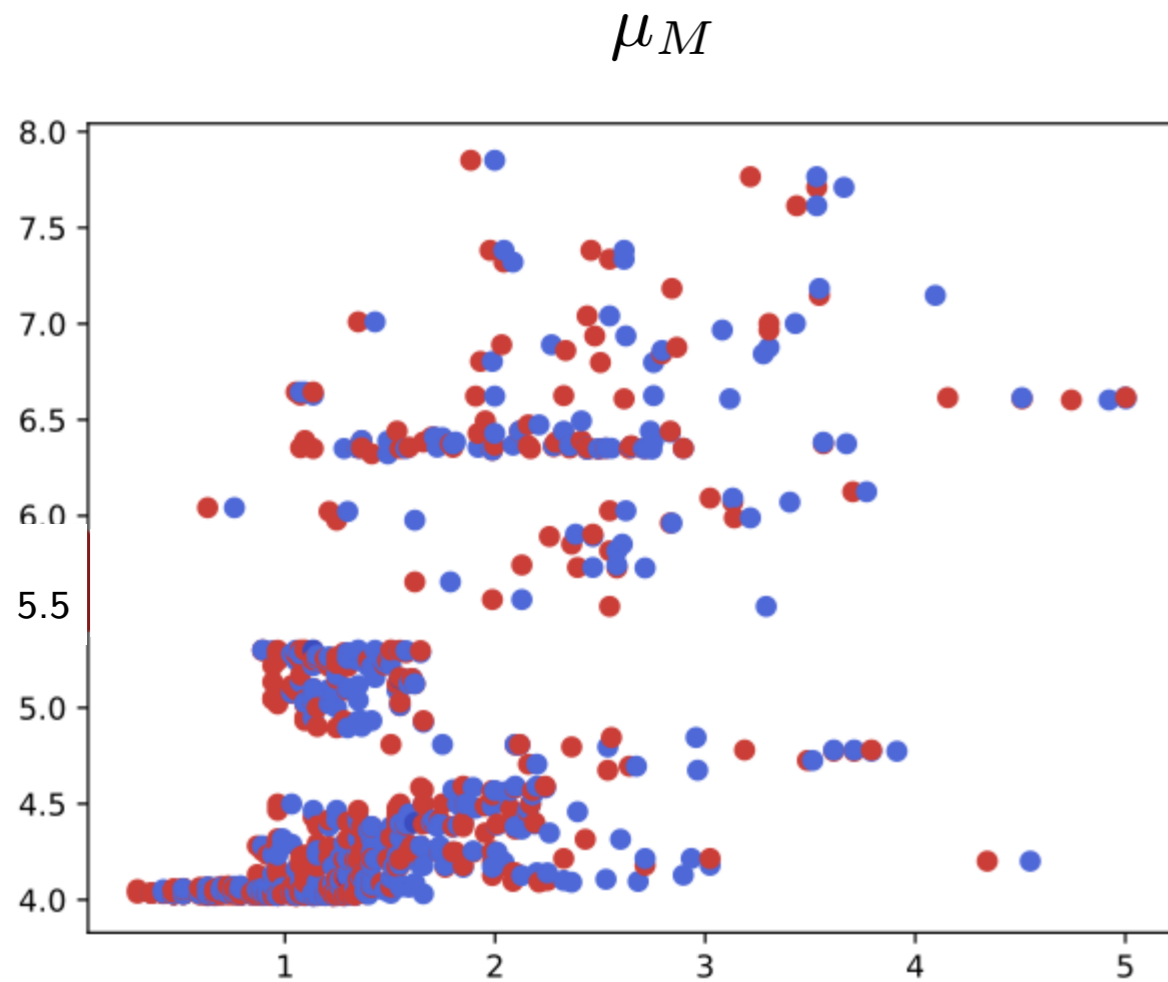
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This decomposition also works for the Euler characteristic and rank invariant!



# Lipschitz Embedding of Signed Measures

---



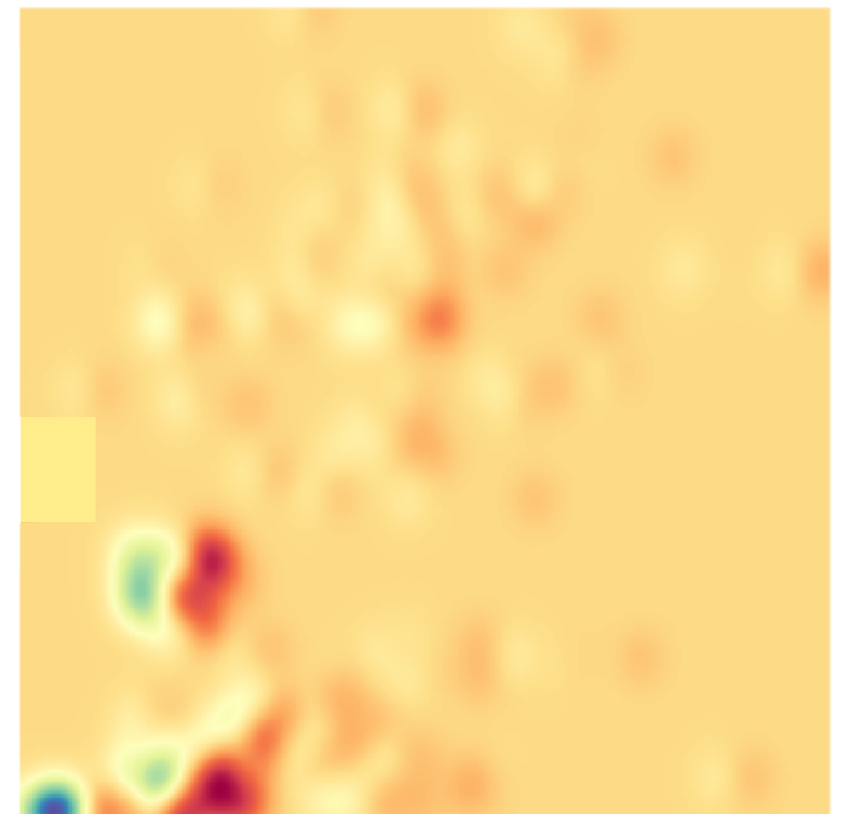
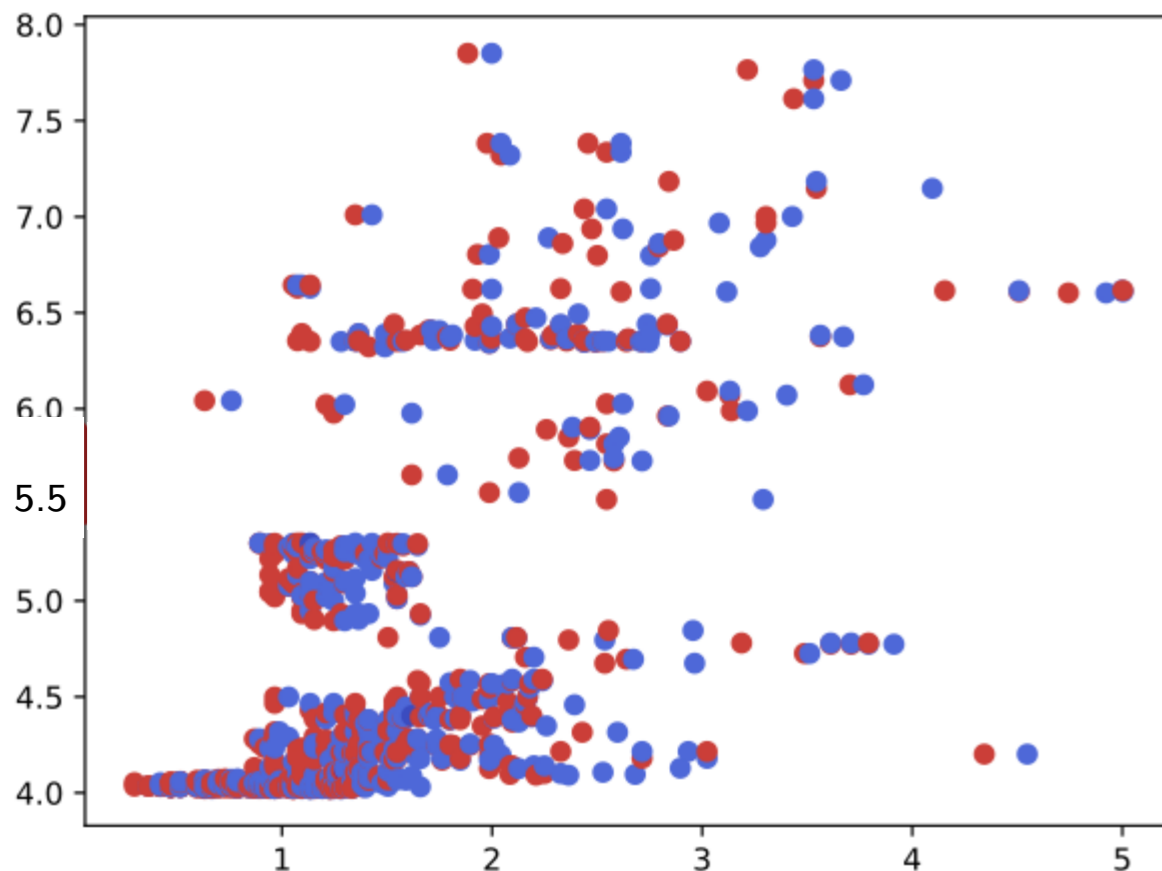
[Loiseaux et al. **Stable Vectorization of Multiparameter Persistent Homology using Signed Barcodes as Measures.** 2023]

# Lipschitz Embedding of Signed Measures

Efficient embedding can be done with *convolution* with a kernel  $k$ , e.g.,  
 $k(x, y) = \frac{1}{2\pi\sigma^2} \exp\left(-\frac{\|x-y\|_2^2}{2\sigma^2}\right)$ :

$$\Phi(M(f))(x) := \mu_M \star k(x) = \int_y k(x, y) d\mu_M(y)$$

$\mu_M$



# Lipschitz Embedding of these Signed Measures

**Def:** Decompose  $\mu_M$  into  $\mu_M = \mu_M^+ - \mu_M^-$ . Then:

$$\|\mu_M\|_p^K := W_p(\mu_M^+, \mu_M^-)$$

$$d_{K,p}(\mu_M, \mu_{M'}) := \|\mu_M - \mu_{M'}\|_p^K = W_p(\mu_M^+ + \mu_{M'}^-, \mu_M^- + \mu_{M'}^+)$$

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**Prop:** For any functions  $f, g : S \rightarrow \mathbb{R}^2$ , where  $S$  is a finite simplicial complex, one has  $d_{K,1}(\mu_{M(f)}, \mu_{M(g)}) = \|\mu_{M(f)} - \mu_{M(g)}\|_1^K \leq 2\|f - g\|_1$ .

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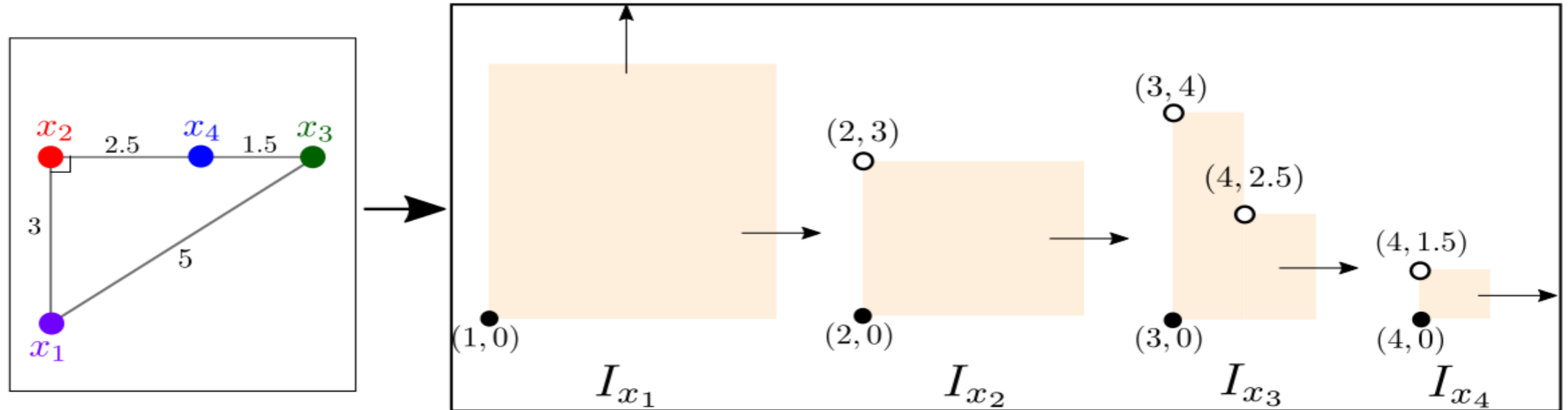
$$d_{K,p}(\mu_M, \mu_{M'}) := \|\mu_M - \mu_{M'}\|_p^K = W_p(\mu_M^+ + \mu_{M'}^-, \mu_M^- + \mu_{M'}^+)$$

**Prop:** For any functions  $f, g : S \rightarrow \mathbb{R}^2$ , where  $S$  is a finite simplicial complex, one has  $d_{K,1}(\mu_{M(f)}, \mu_{M(g)}) = \|\mu_{M(f)} - \mu_{M(g)}\|_1^K \leq 2\|f - g\|_1$ .

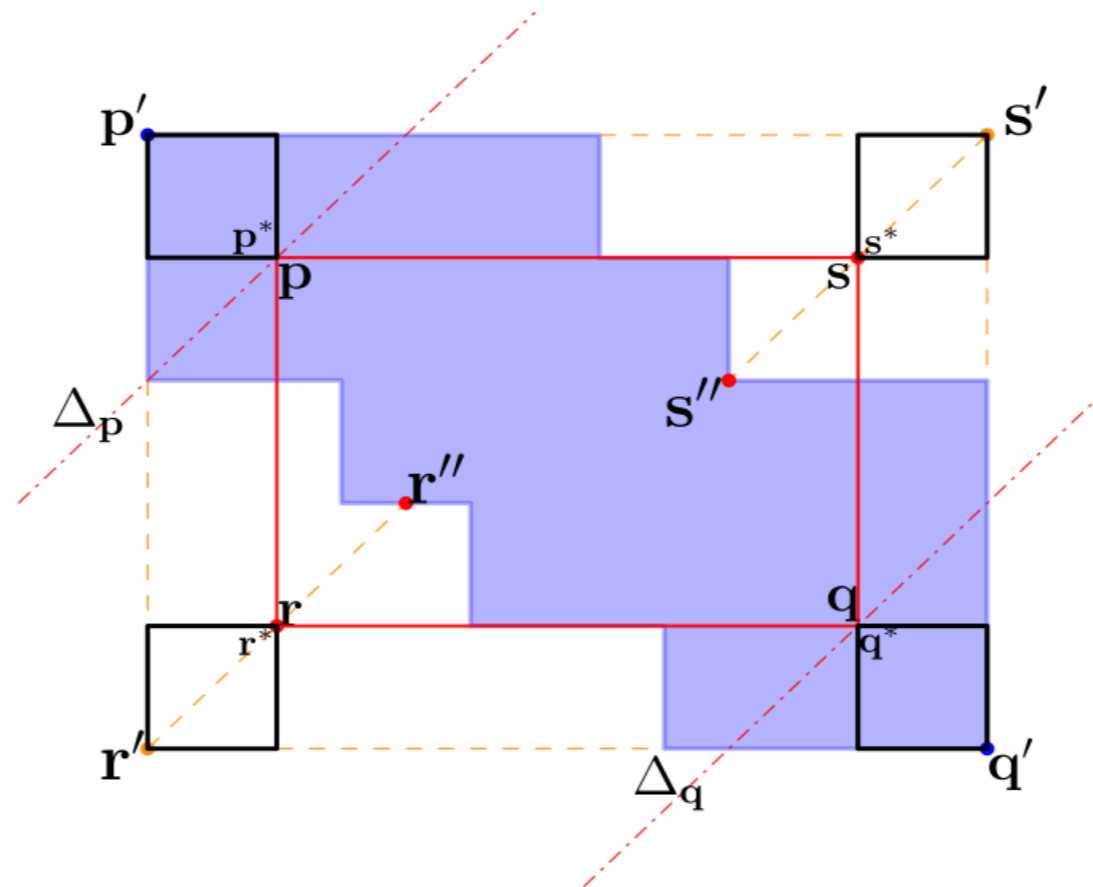
**Prop:** Let  $k$  be a kernel such that  $\|k(x, \cdot) - k(\cdot, y)\|_2 \leq C_k \cdot \|x - y\|_2$ . Then, one has  $\|k \star \mu - k \star \nu\|_2 \leq C'_k \|\mu - \nu\|_2^K \leq C'_k \|\mu - \nu\|_1^K$ .

# Other Decomposition Candidates

[Cai et al. Elder-Rule-Staircodes for Augmented Metric Spaces. 2020]



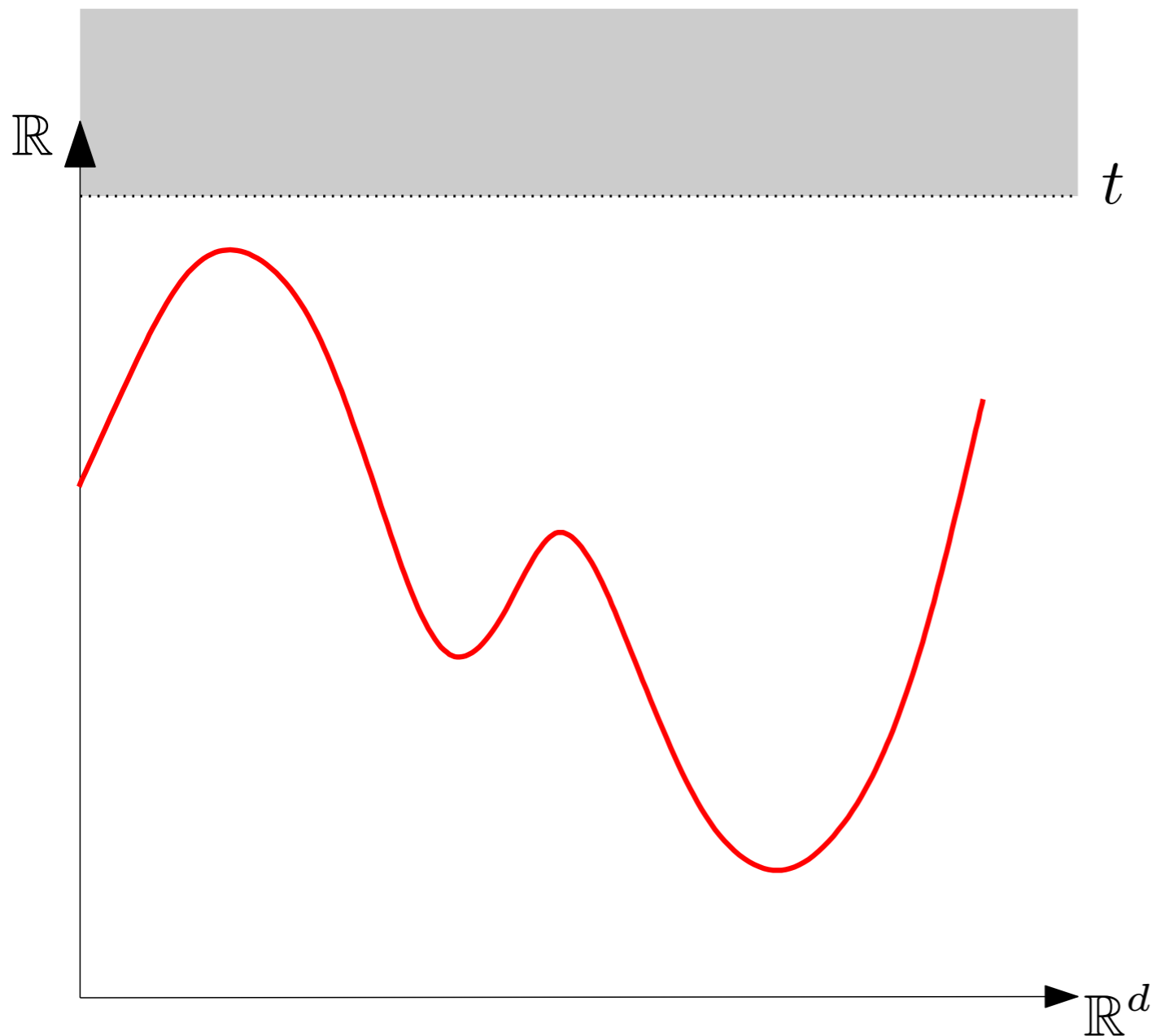
[Dey, Xin. Rectangular Approximation and Stability of 2-parameter Persistence Modules. 2021]



# Reminder: 0-dimensional PH of density

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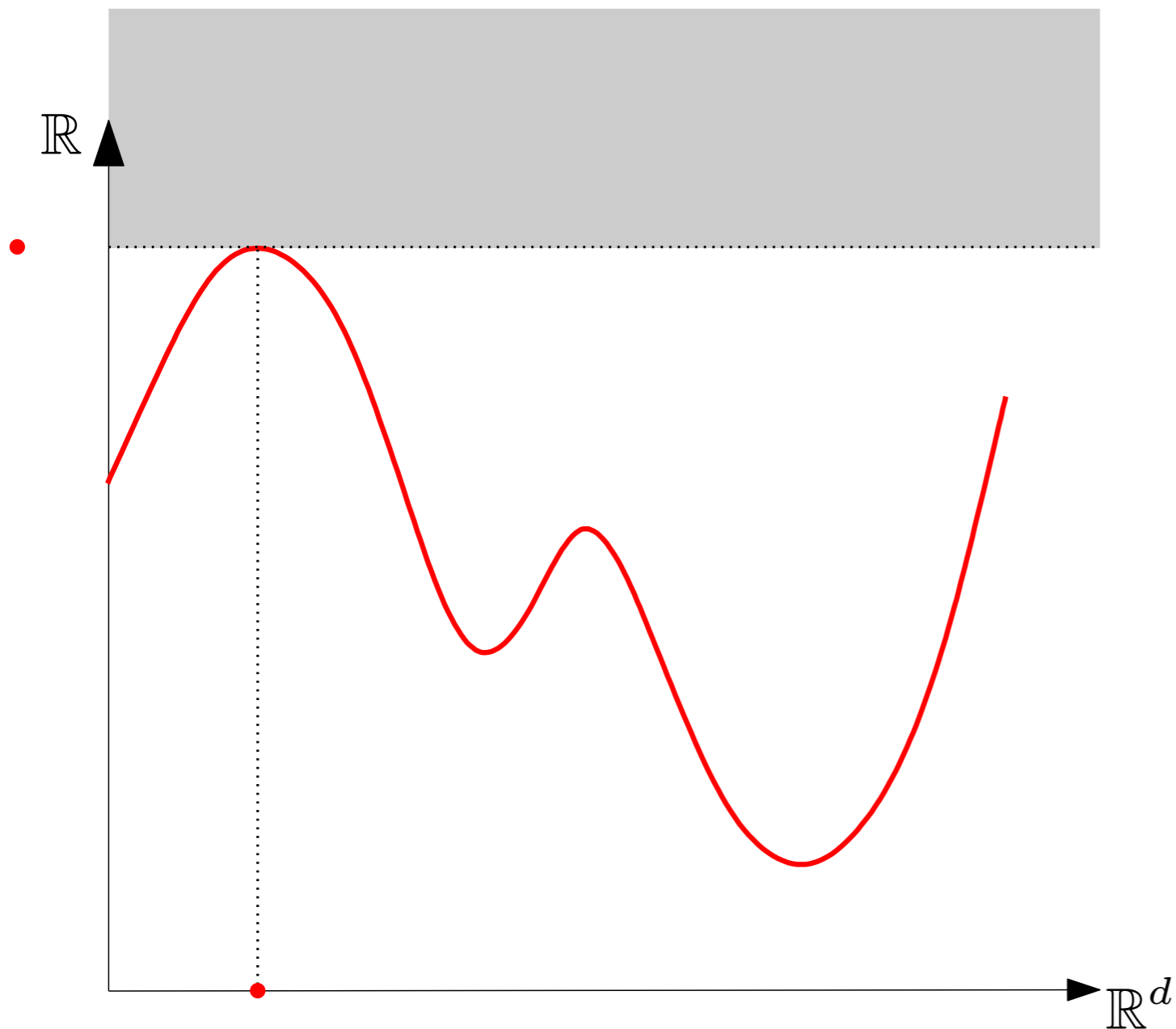
Given a probability density  $f$ , we will consider the superlevel-set filtration  $f^{-1}([t, +\infty))$  for  $t$  from  $+\infty$  to  $-\infty$ , instead of the sublevel-set filtration.



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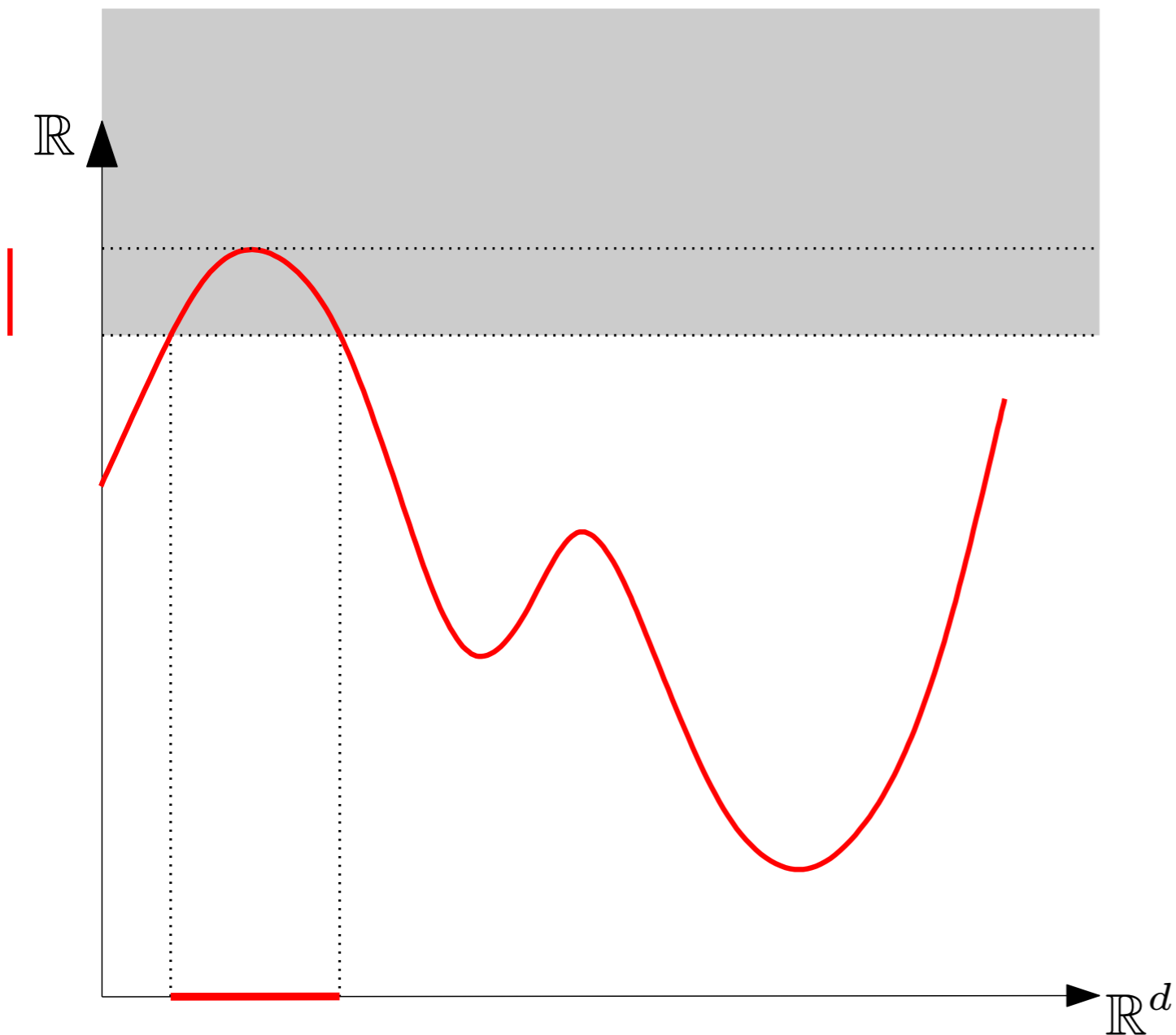
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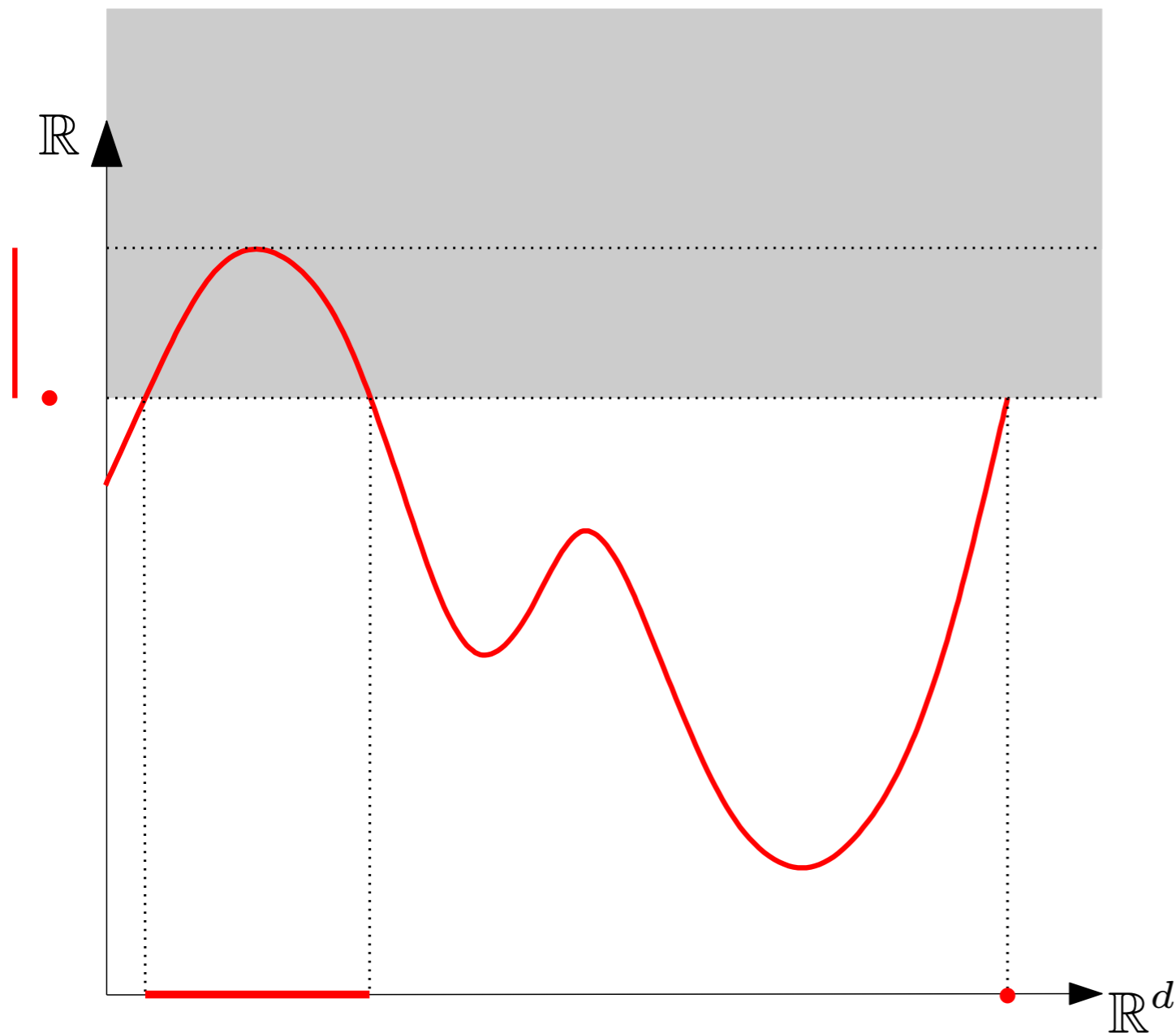
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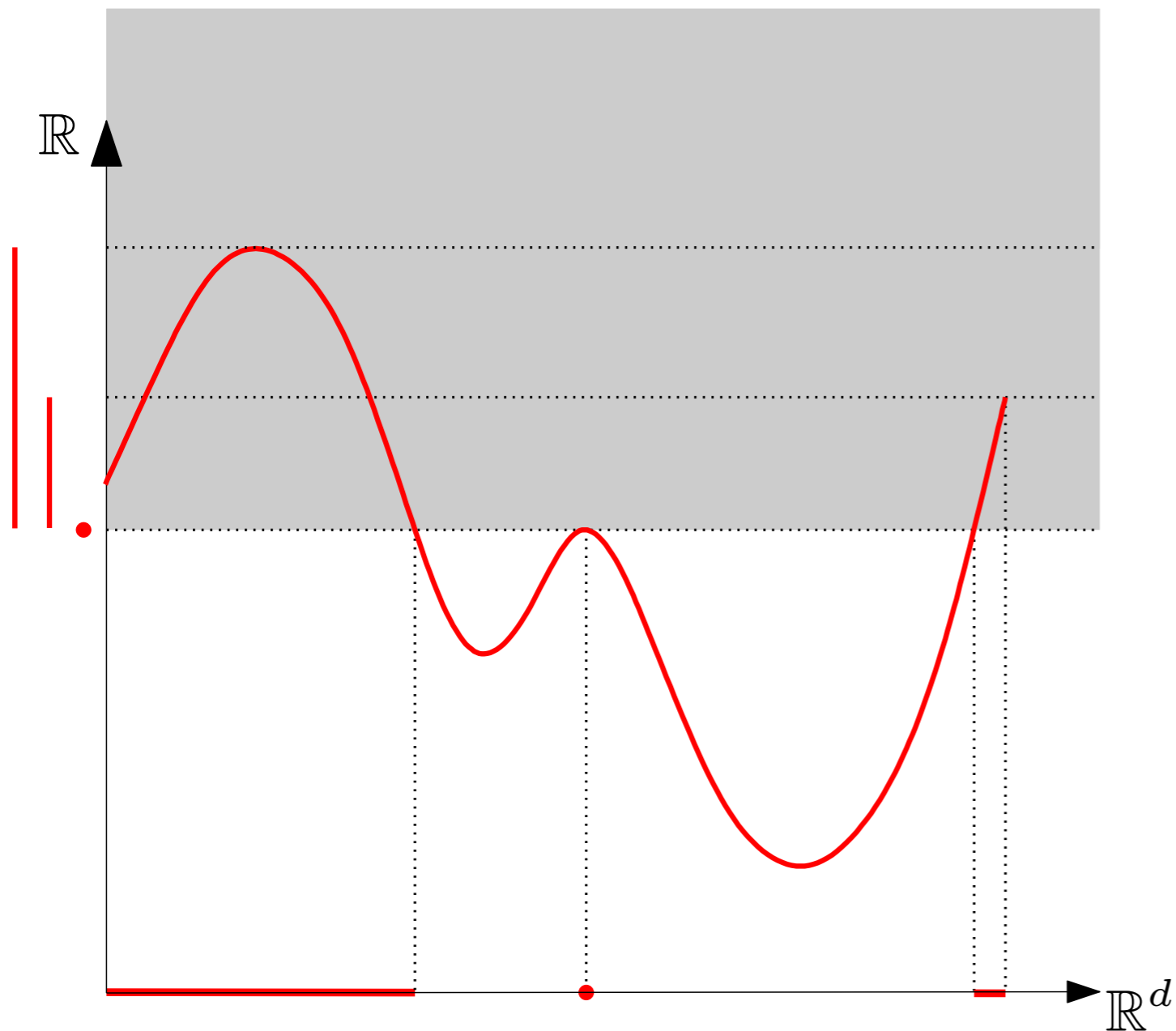
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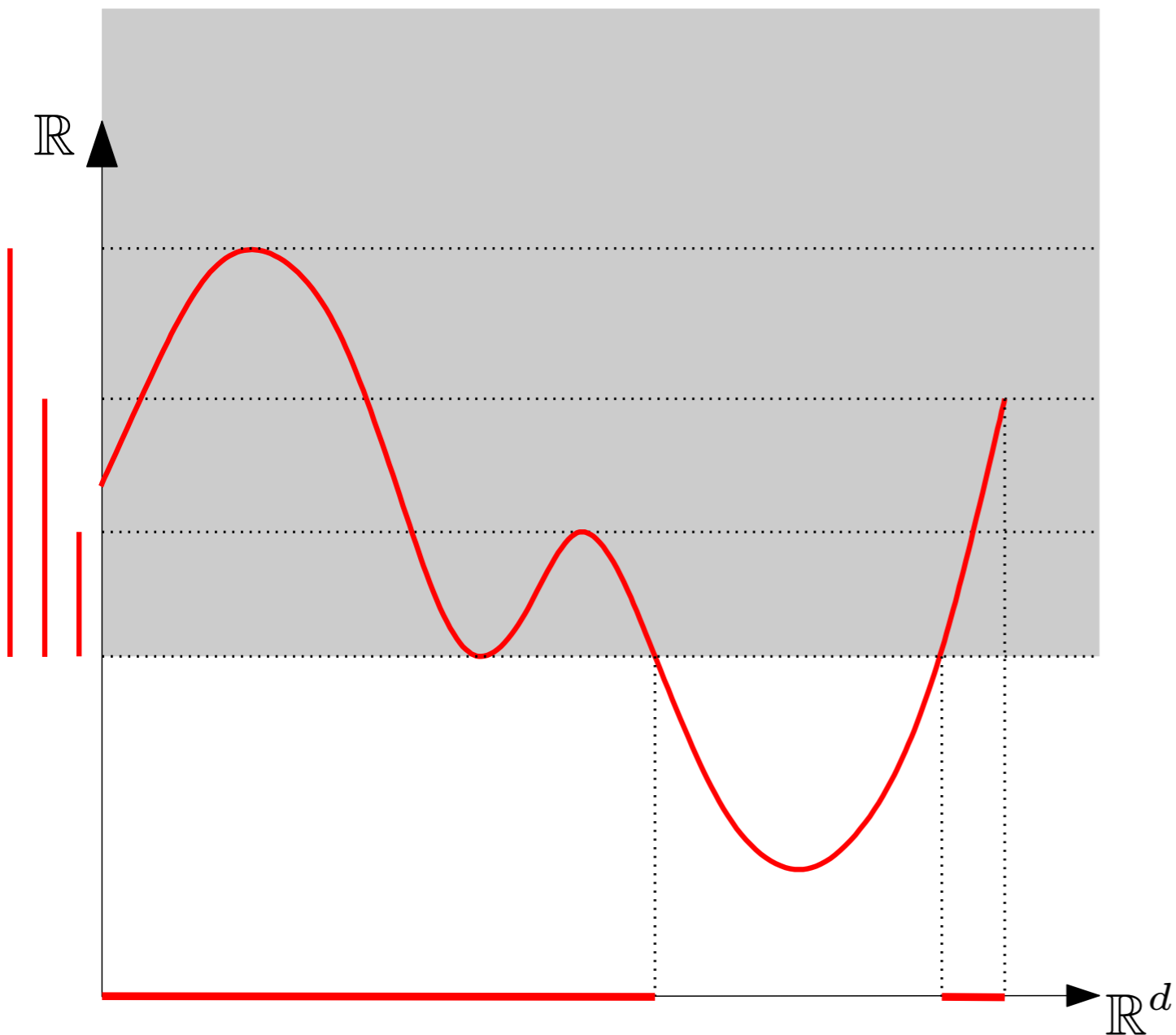
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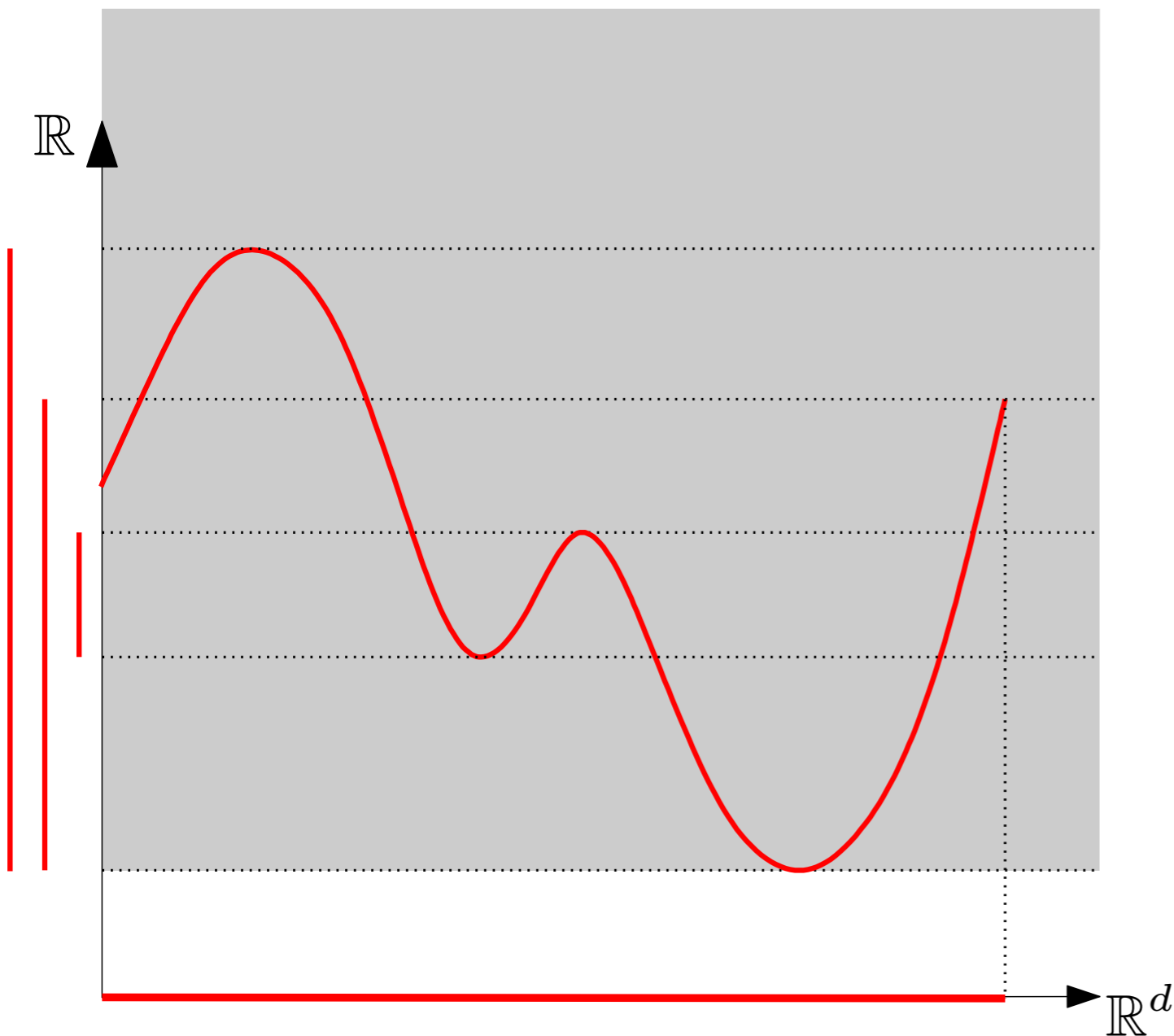
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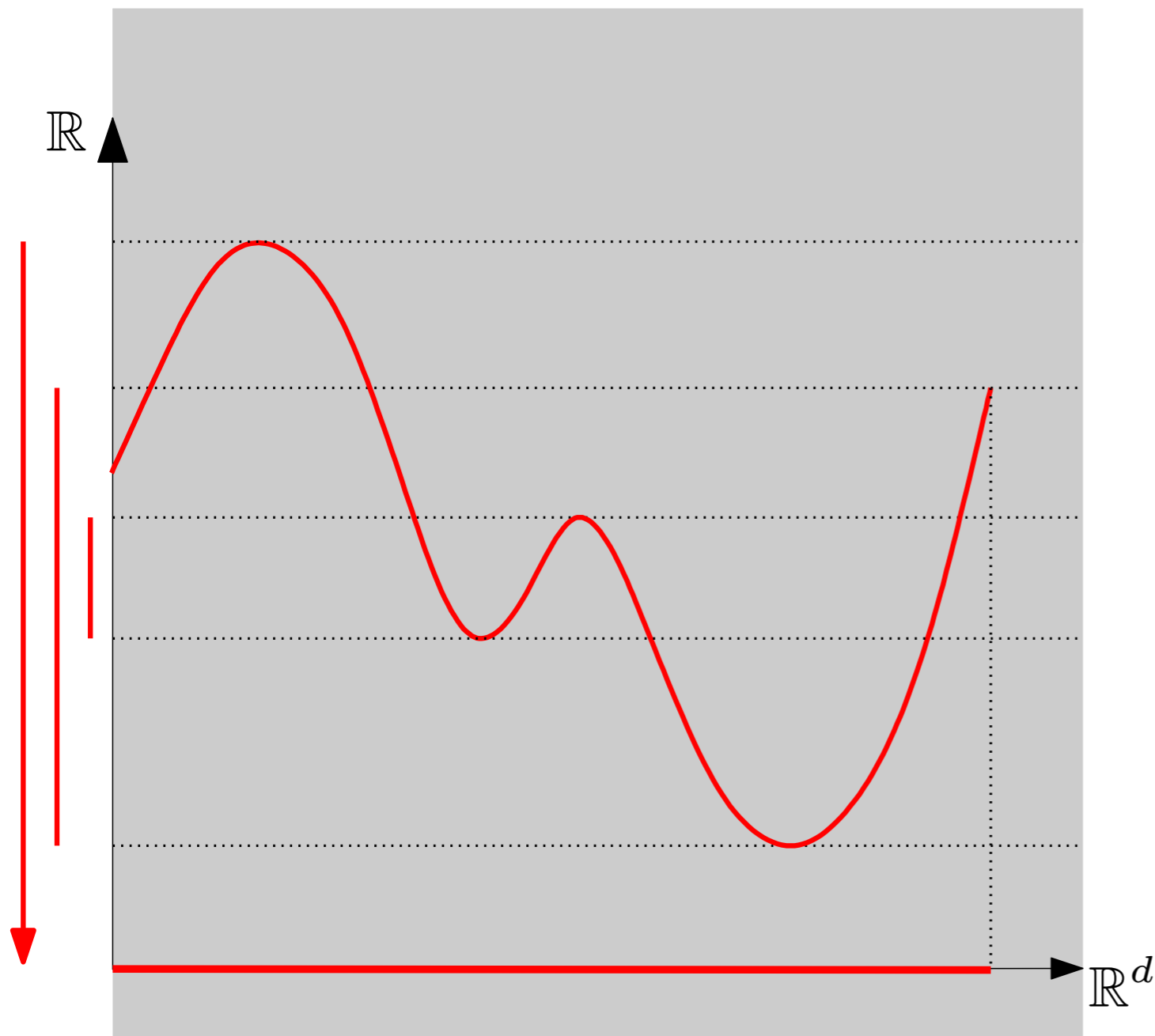
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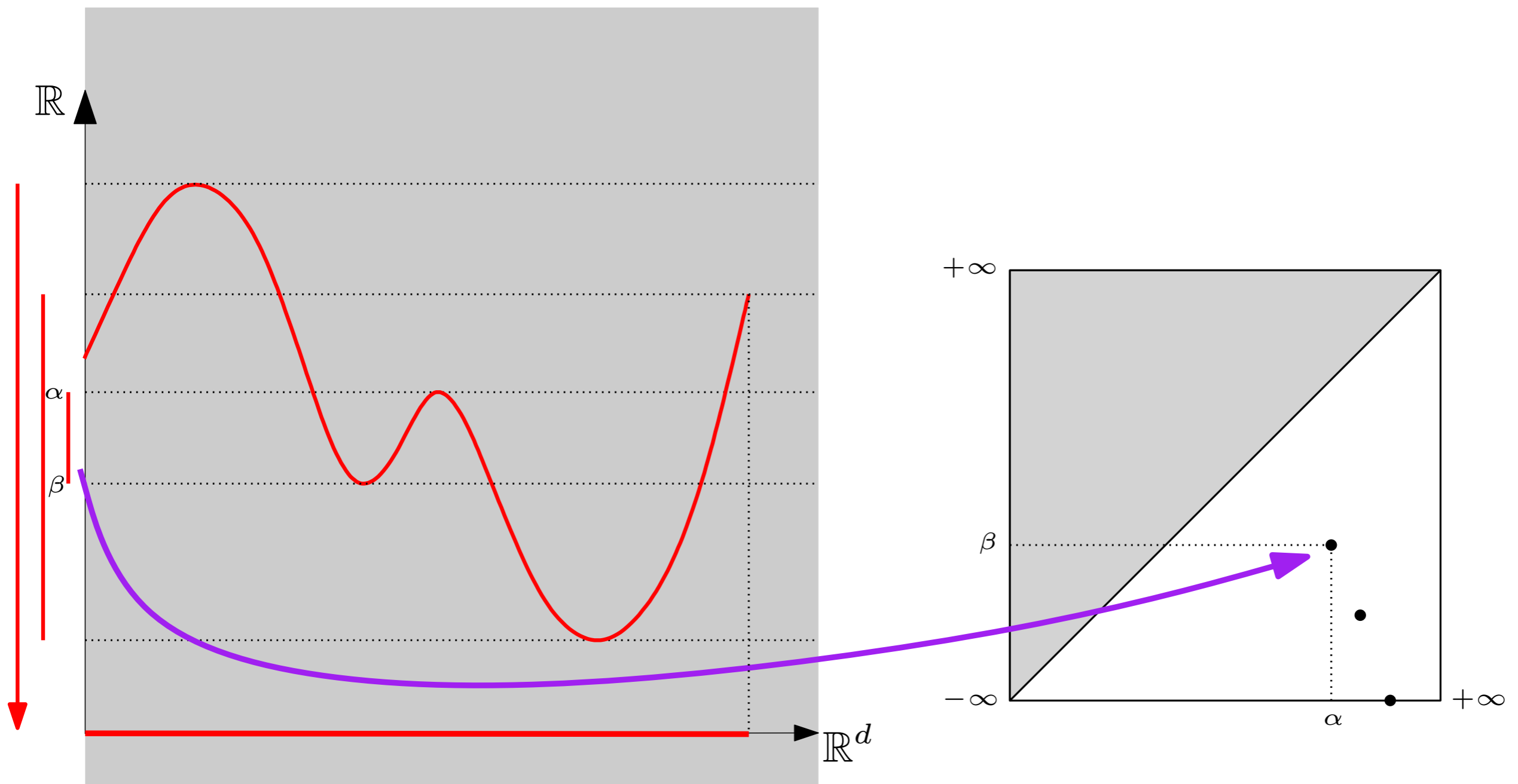
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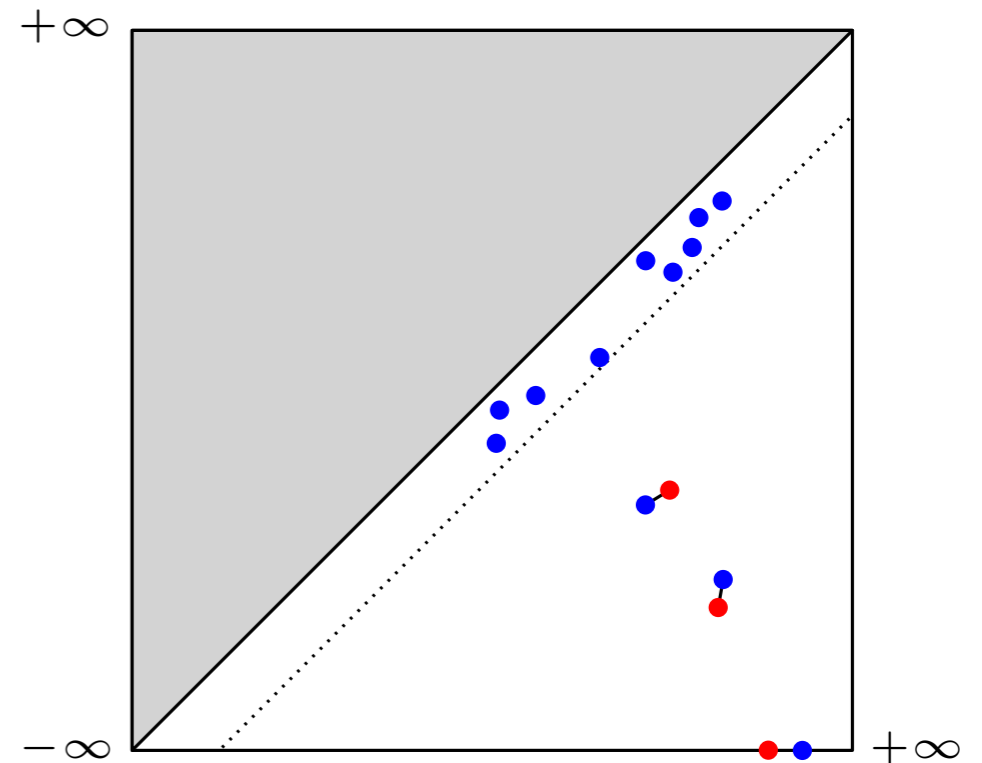
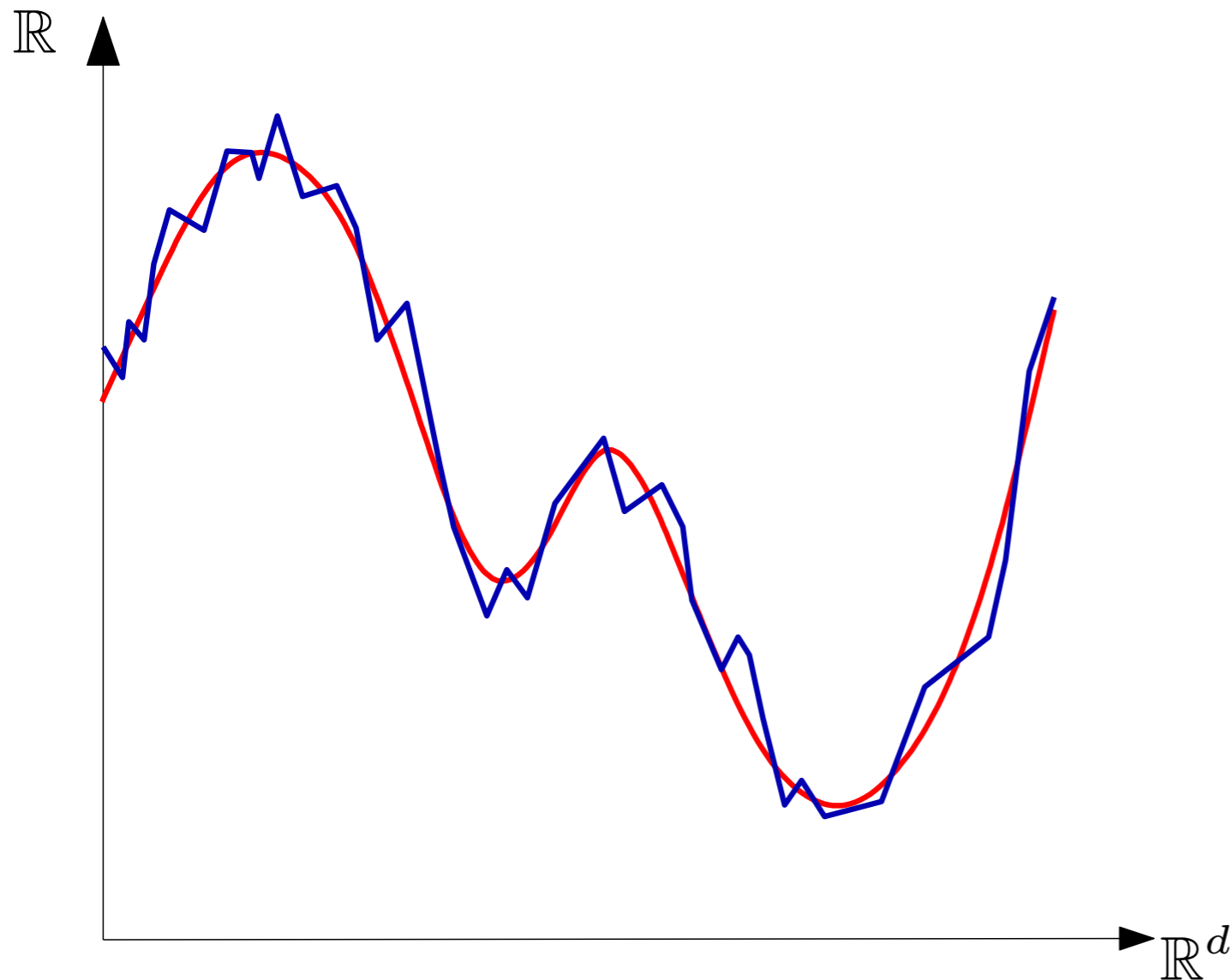
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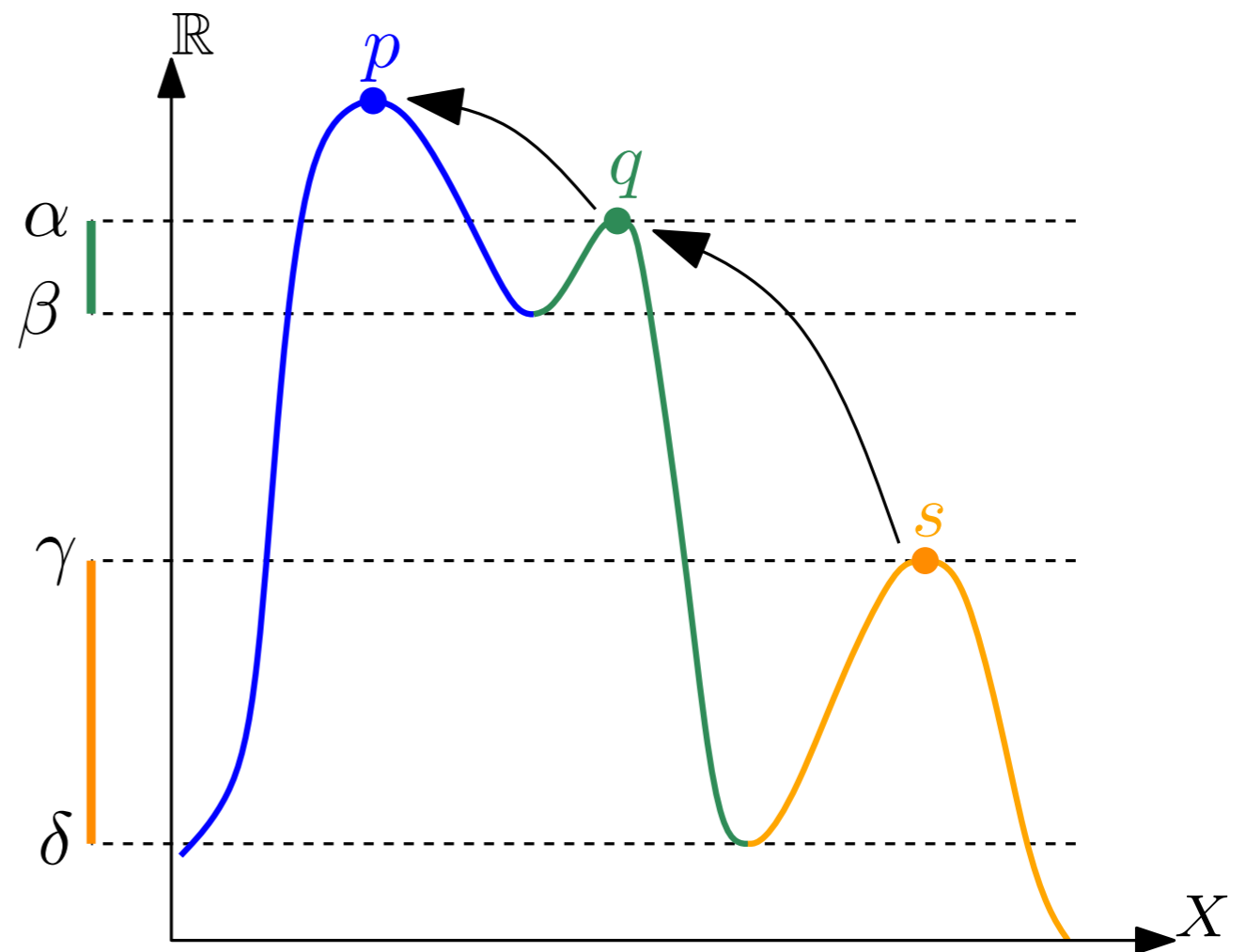
Moreover, the stability theorem ensures that, given an underlying true density  $f$ , and an estimator  $\hat{f}$  of it, one has:

$$d_b(D_f, D_{\hat{f}}) \leq \|f - \hat{f}\|_{\infty}.$$



# Building a hierarchy of cluster with 0-dimensional PH

In addition to being stable, 0-dimensional PH also remembers the connected components that were merged together during the filtration process and builds a hierarchy out of this information.

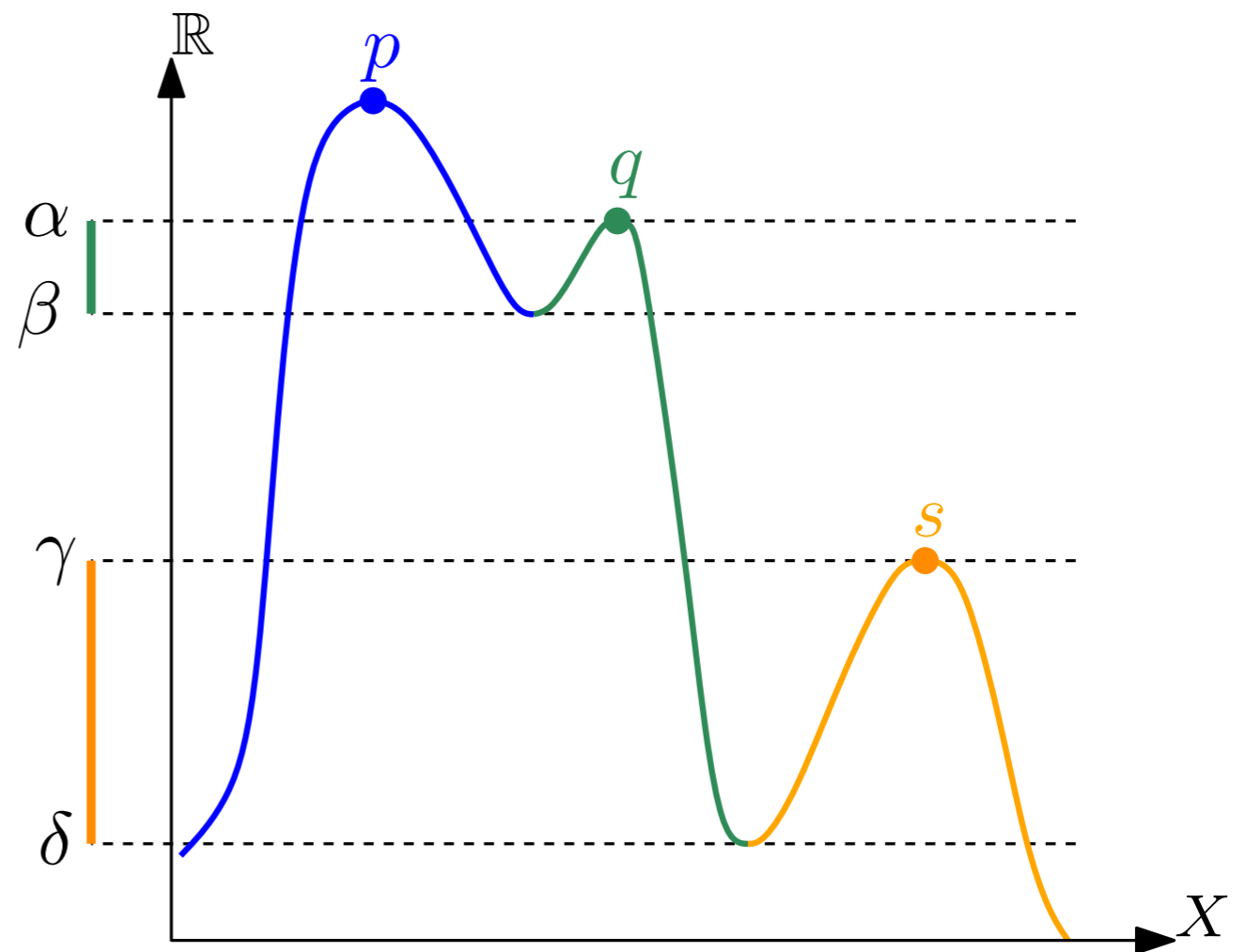


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In addition to being stable, 0-dimensional PH also remembers the connected components that were merged together during the filtration process and builds a hierarchy out of this information.

This means that, given a fixed threshold  $\tau \geq 0$ , one can even retrieve the clusters associated to all the bars of length (or prominence)  $> \tau$ !

$$0 \leq \tau \leq \alpha - \beta$$

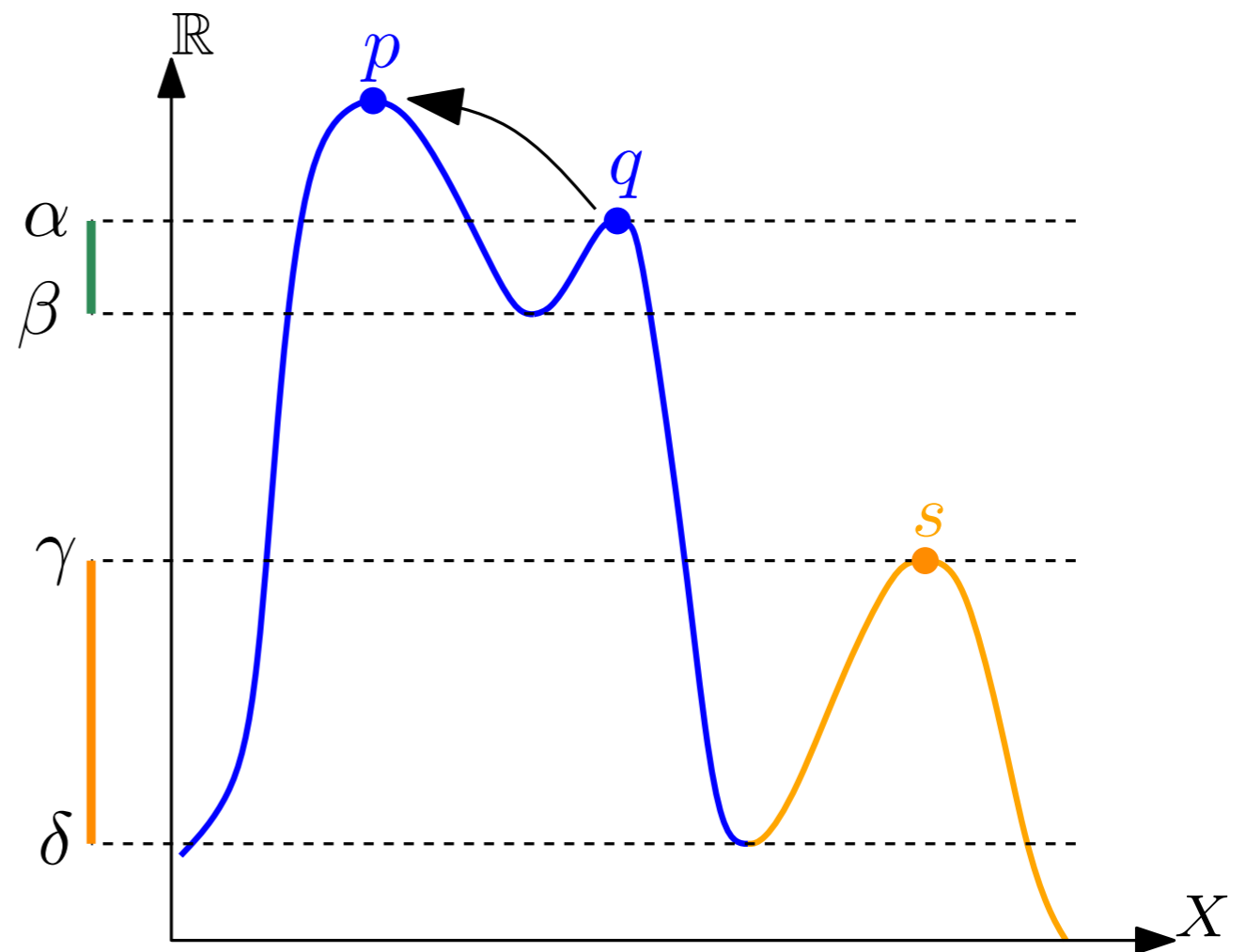


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$$\alpha - \beta < \tau \leq \gamma - \delta$$

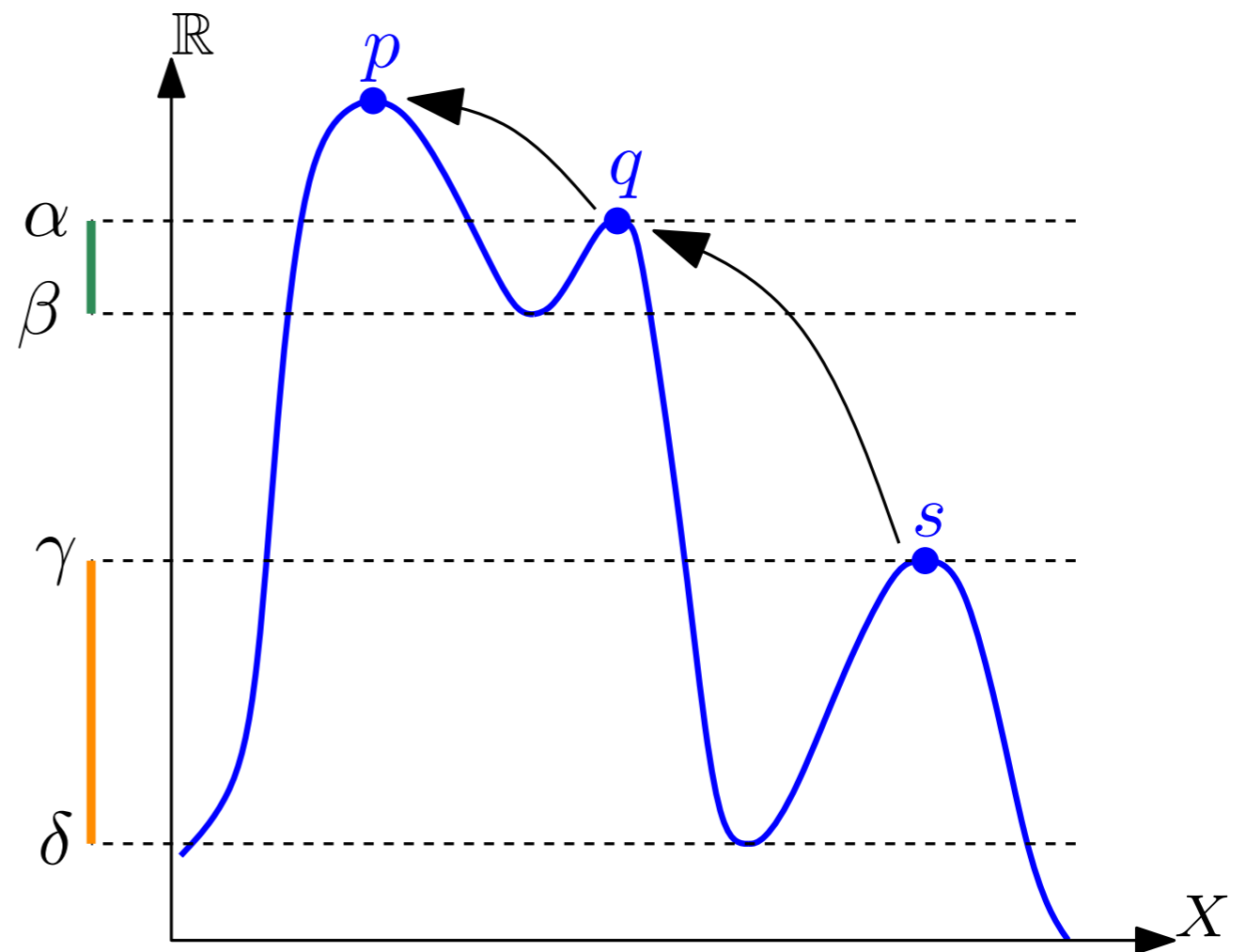


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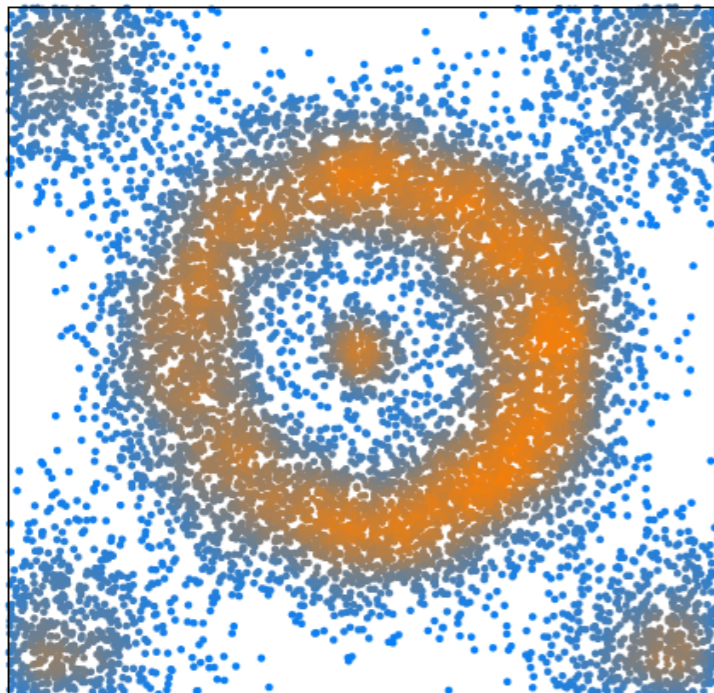


# ToMATo: Topological Mode Analysis Tool

[*Persistence-Based Clustering in Riemannian Manifolds*,  
Chazal, Oudot, Skraba,  
Guibas, J. ACM, 2013]

1. Define an order on the point cloud with a density estimator  $\hat{f}$ .

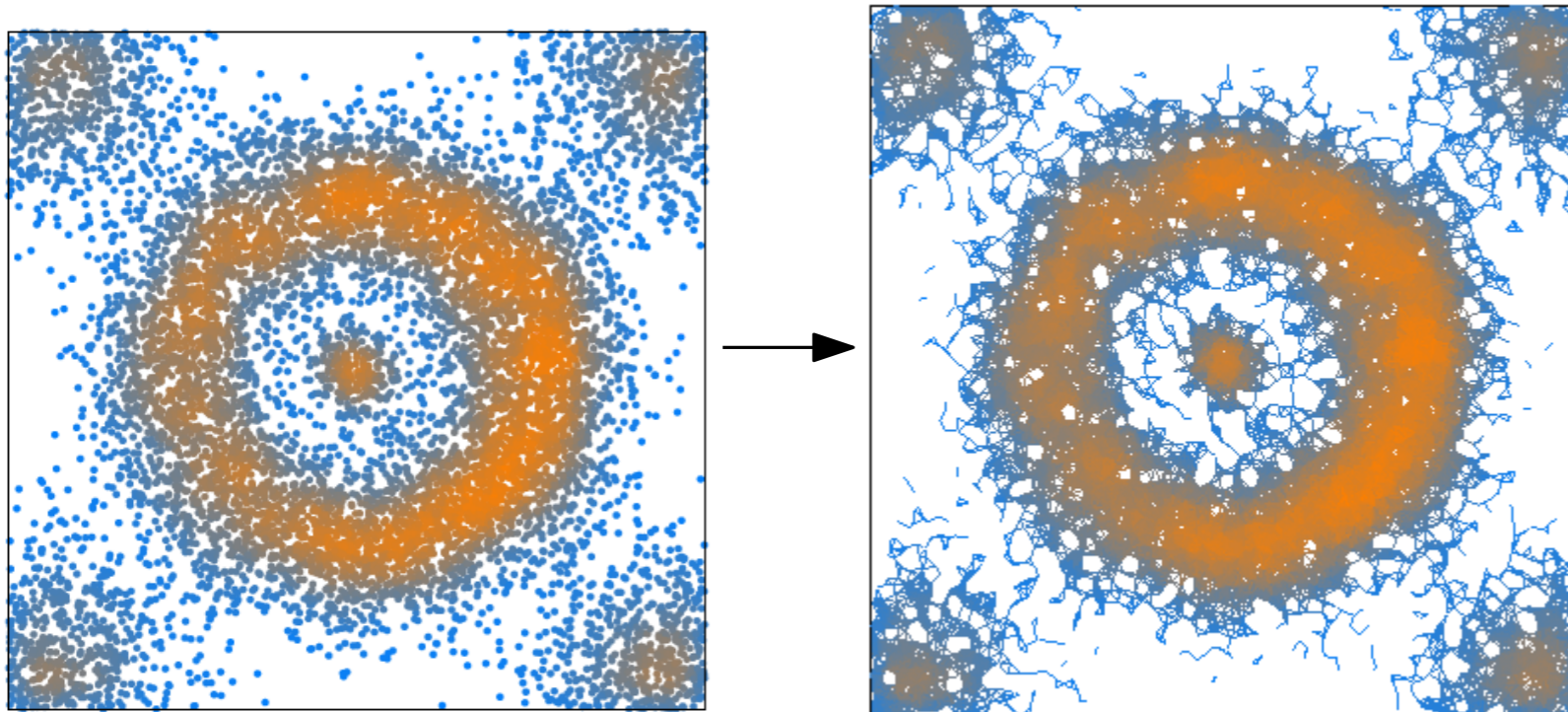
(sort data points by **decreasing** estimated density values)



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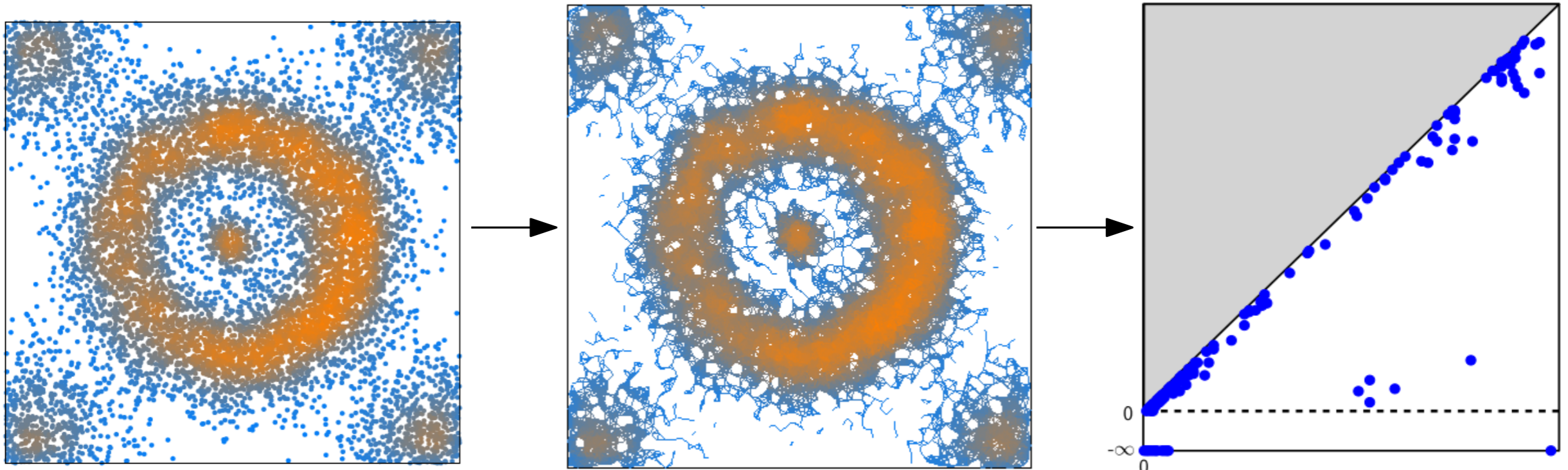
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( $\hat{f}([u, v]) = \min\{\hat{f}(u), \hat{f}(v)\}$ )



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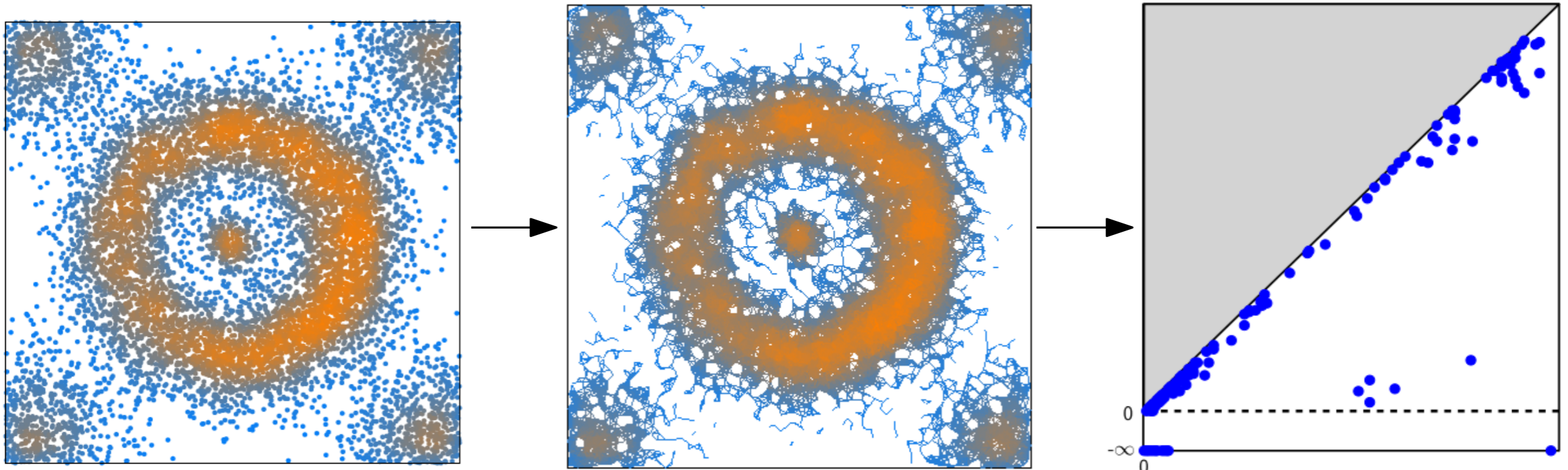
Given a neighborhood graph with  $n$  vertices and  $m$  edges:

1. the algorithm sorts the vertices by decreasing density values,
2. and then makes a single pass through the vertex set, merging clusters on the fly using a union-find data structure.

→ Running time:  $O(n \log n + (n + m)\alpha(n))$

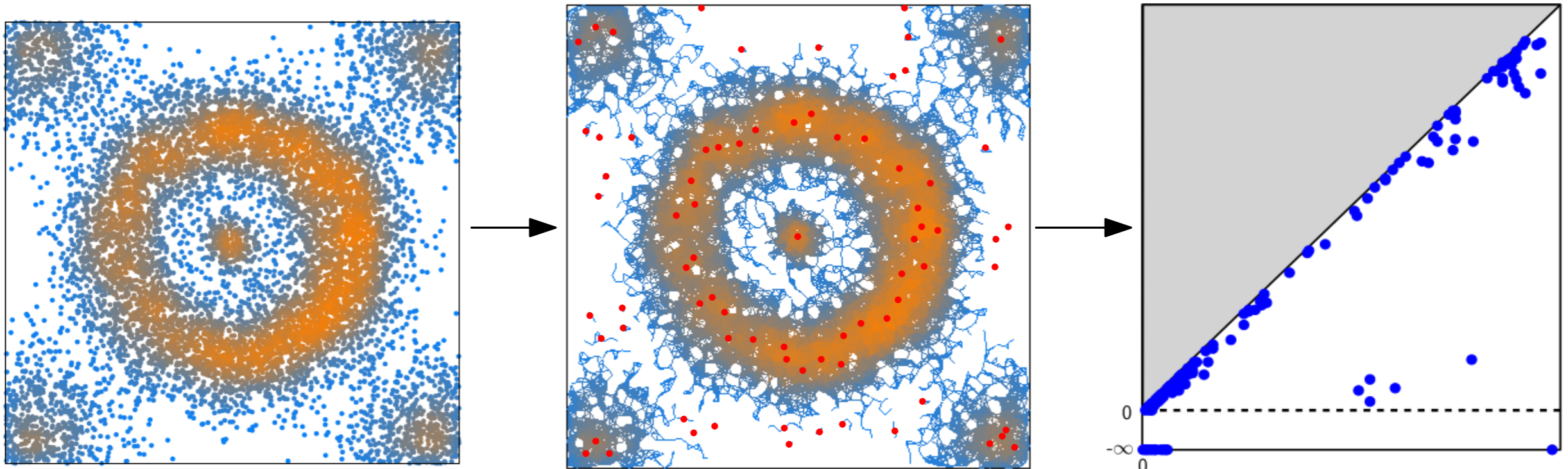
→ Space complexity:  $O(n + m)$

→ Main memory usage:  $O(n)$



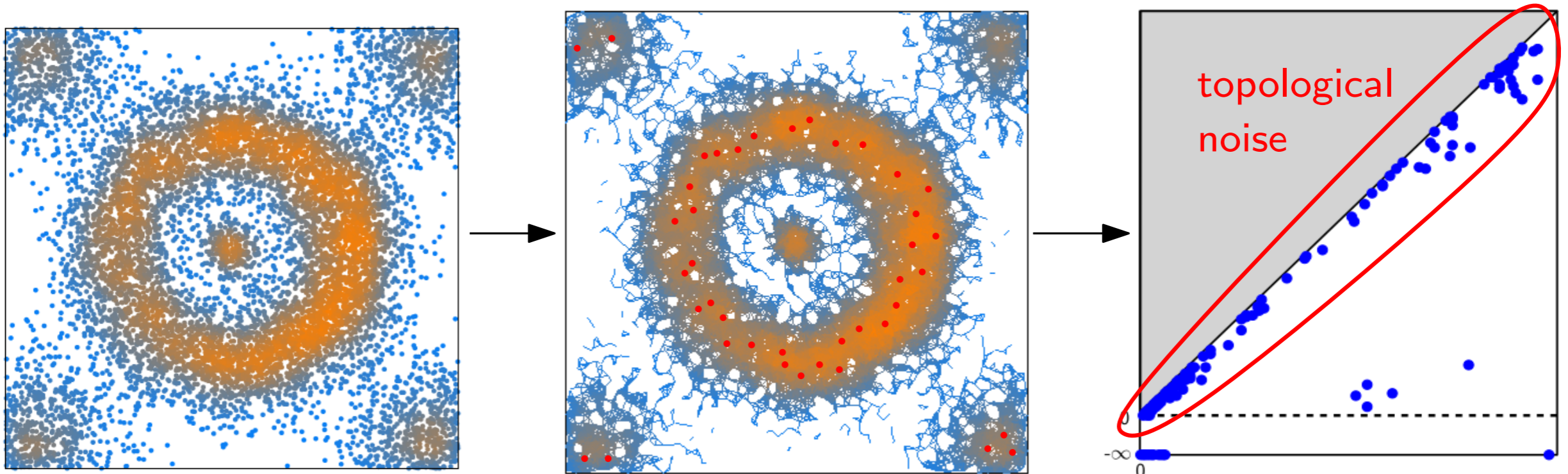
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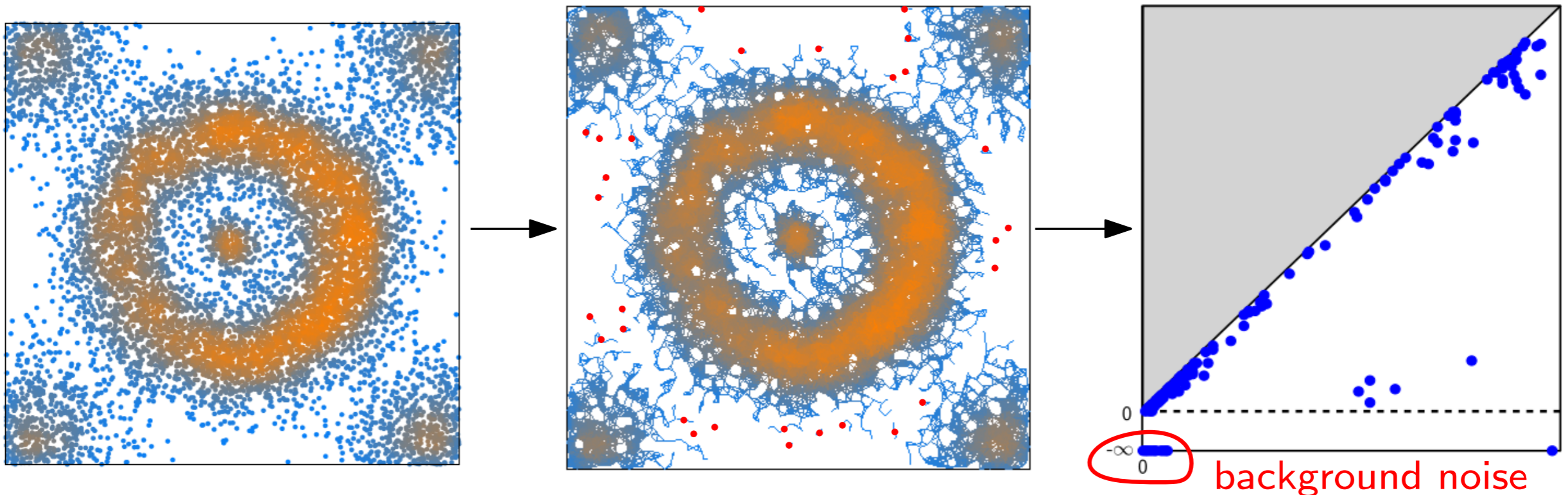
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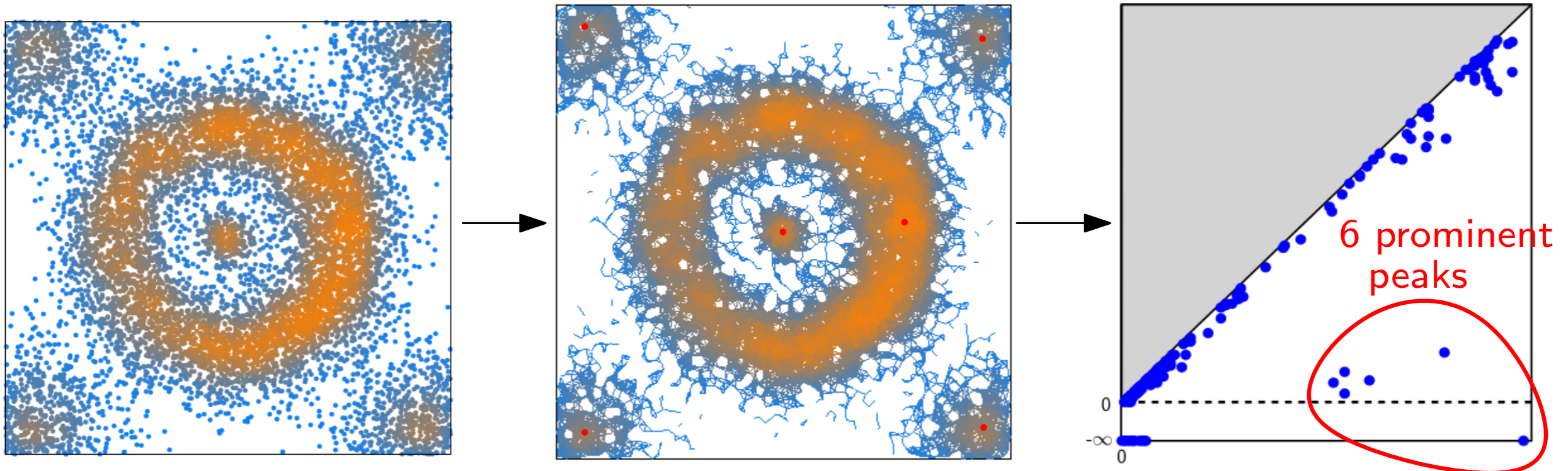
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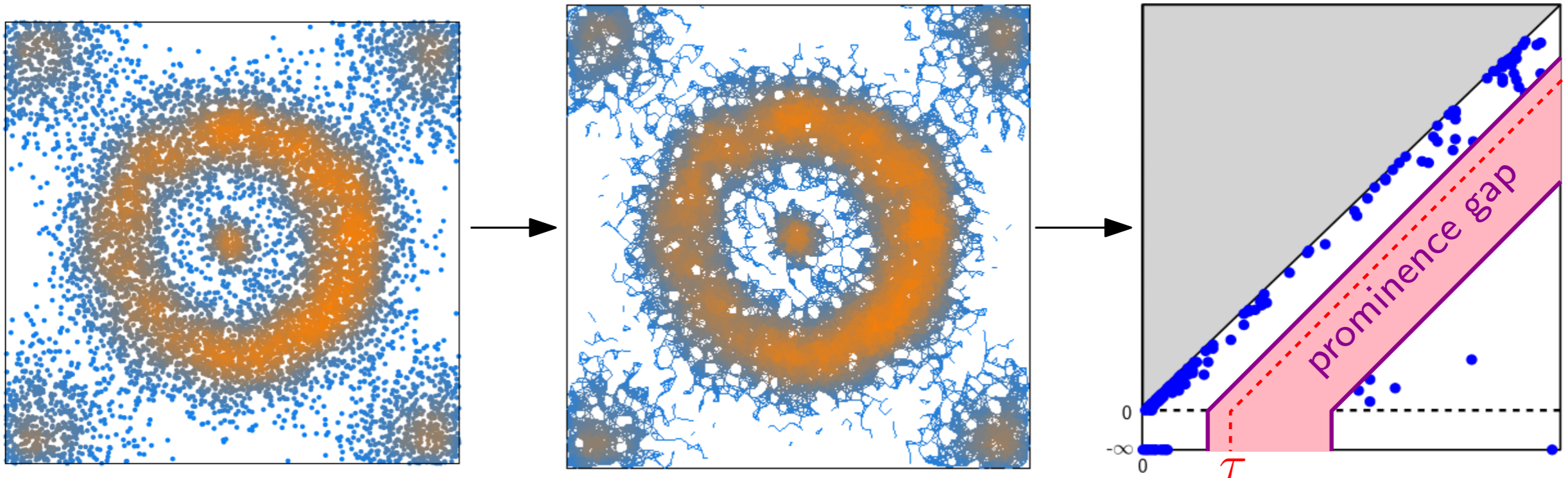
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## Hypotheses:

- $f : \mathbb{R}^d \rightarrow \mathbb{R}$  a  $c$ -Lipschitz probability density function,
- $P \subset \mathbb{R}^d$  a finite set of  $n$  points sampled i.i.d. according to  $f$ ,
- $\hat{f} : P \rightarrow \mathbb{R}$  a density estimator s.t.  $\eta := \max_{p \in P} |\hat{f}(p) - f(p)| < \Pi/5$ ,
- $G = (P, E)$  the  $\delta$ -neighborhood graph for some positive  $\delta < \frac{\Pi - 5\eta}{5c}$ .

Note:  $\Pi$  is the prominence of the least prominent peak of  $f$

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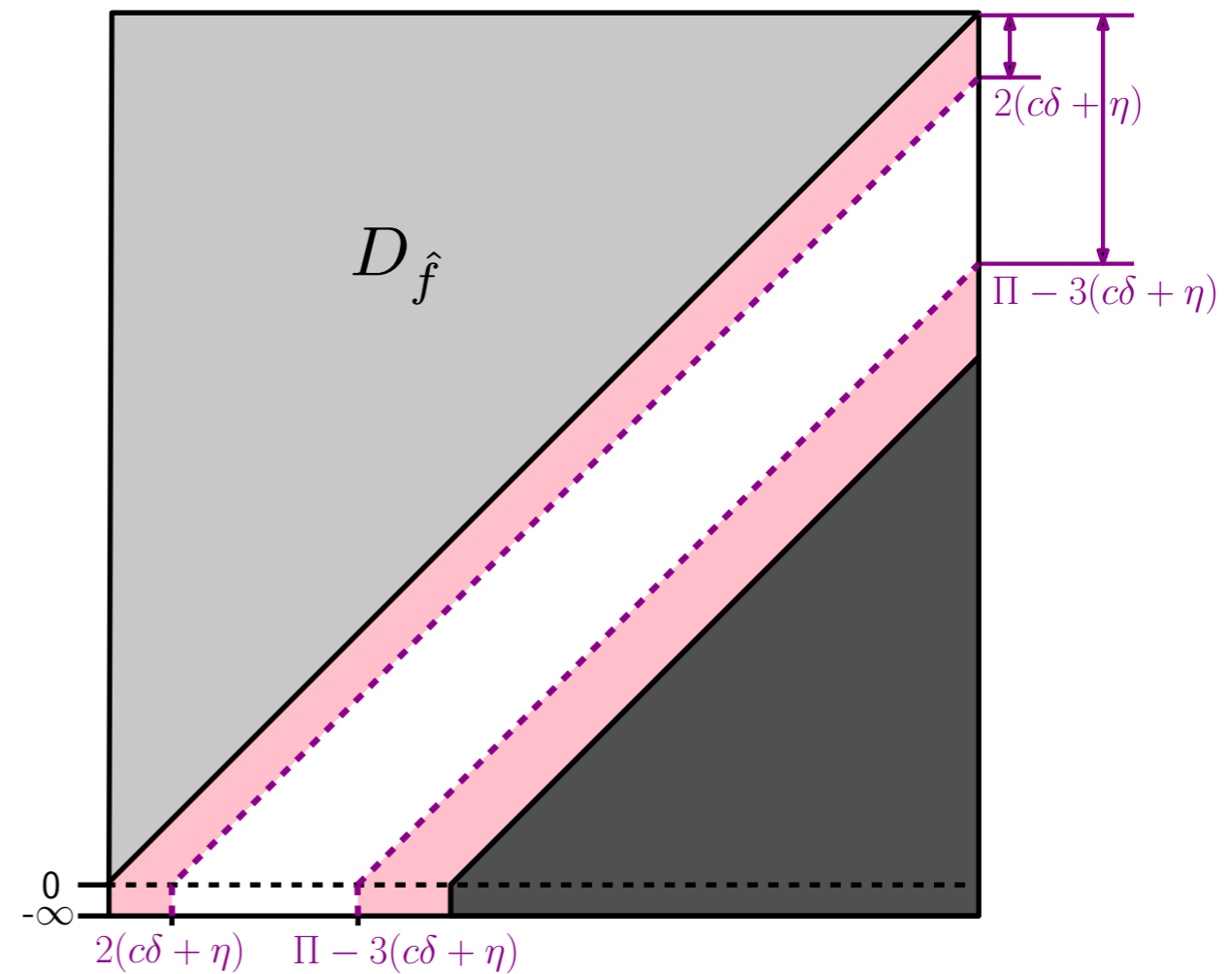
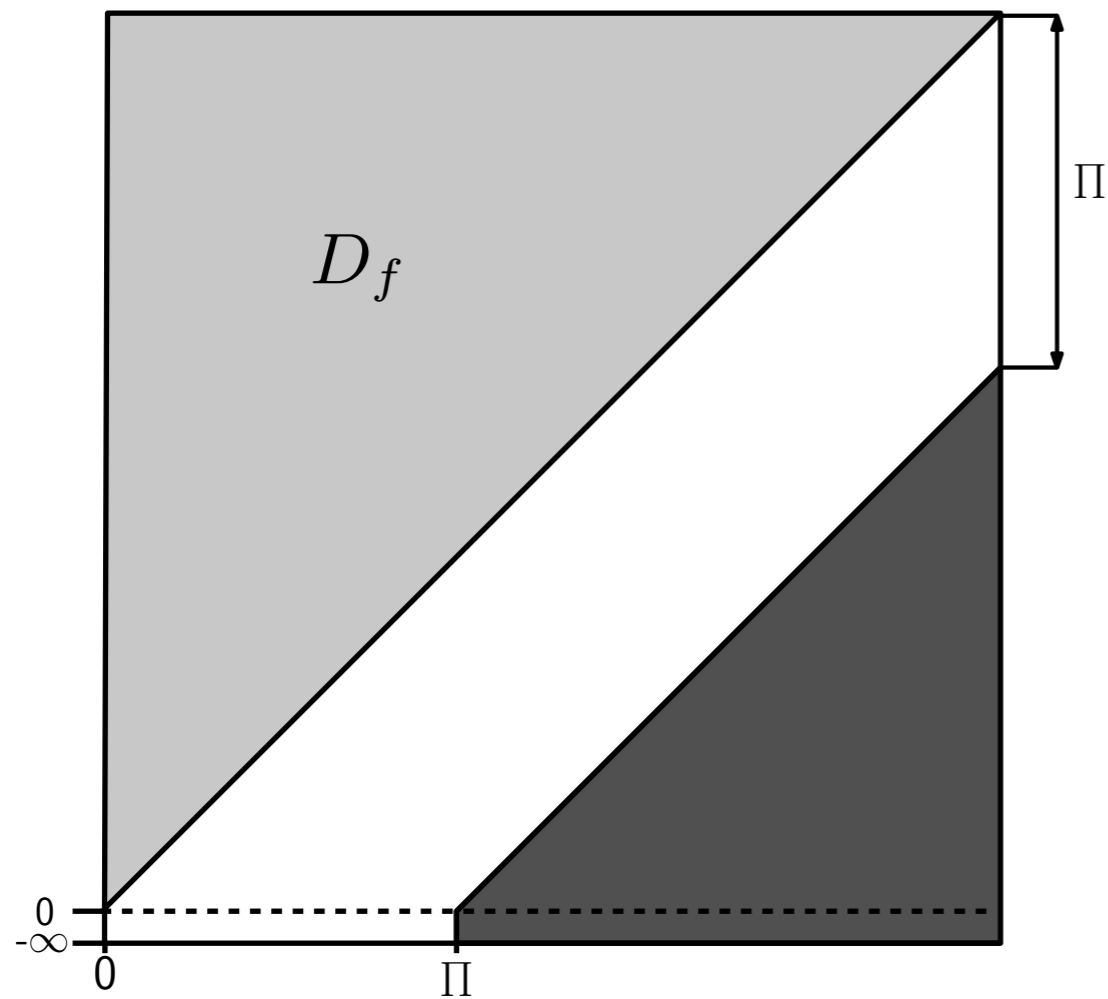
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**Th:** For any choice of  $\tau$  such that  $2(c\delta + \eta) < \tau < \Pi - 3(c\delta + \eta)$ , the number of clusters computed by the algorithm is equal to the number of peaks of  $f$  with probability at least  $1 - e^{-\Omega(n)}$ . (the  $\Omega$  notation hides factors depending on  $c, \delta$ )

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