

Sparsity Promoting Scale Mixture Priors Fit Large Imaging Datasets

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ICERM, BAYESIAN INVERSE PROBLEMS AND UQ (2026)





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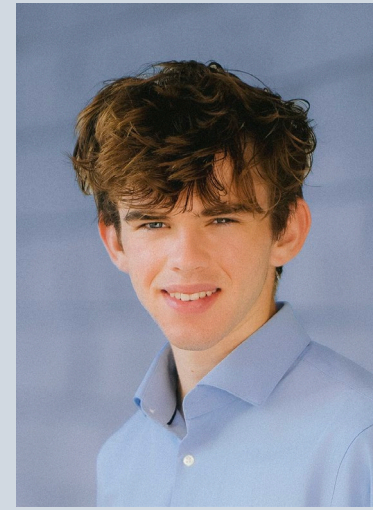
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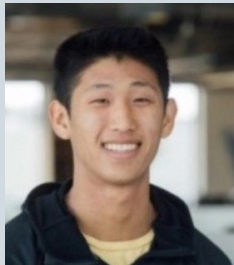
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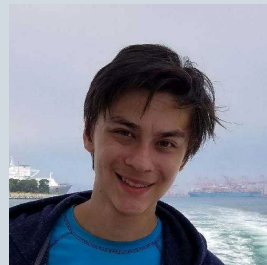
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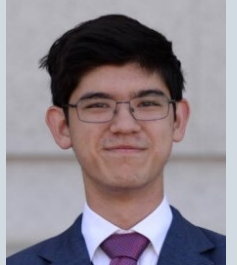
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Introduction

MODEL, PROPERTIES, MOTIVATION

Hierarchical Model

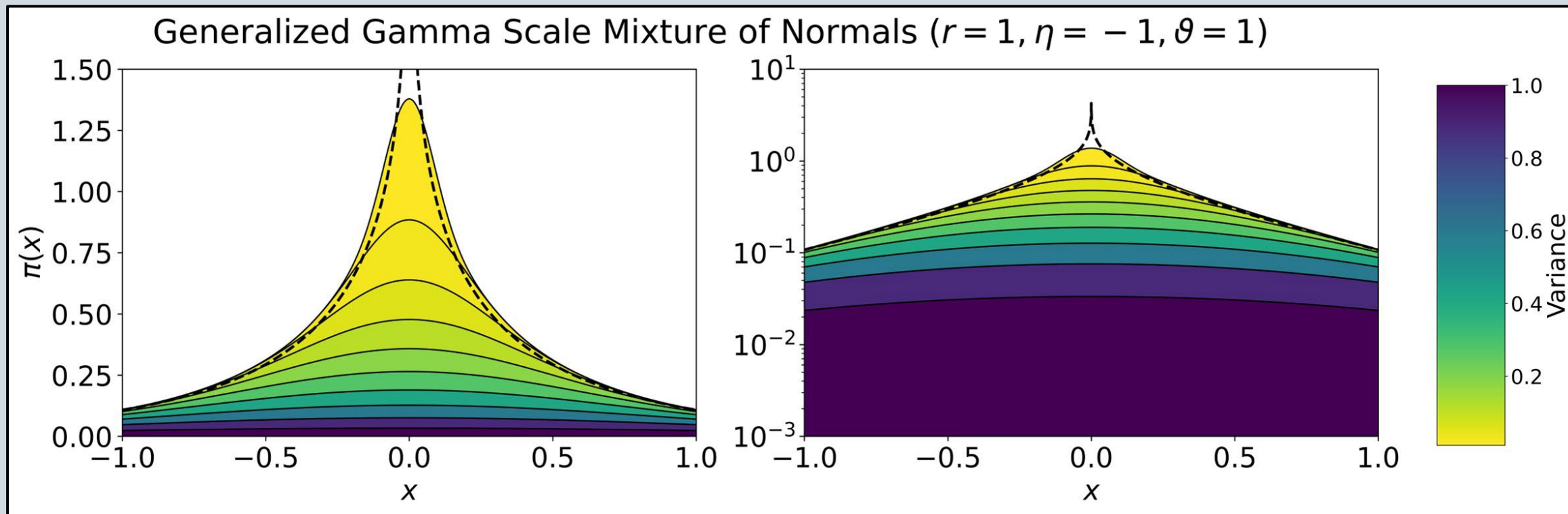
Bayesian inverse problems require a prior model.

We consider the **hierarchical model**:

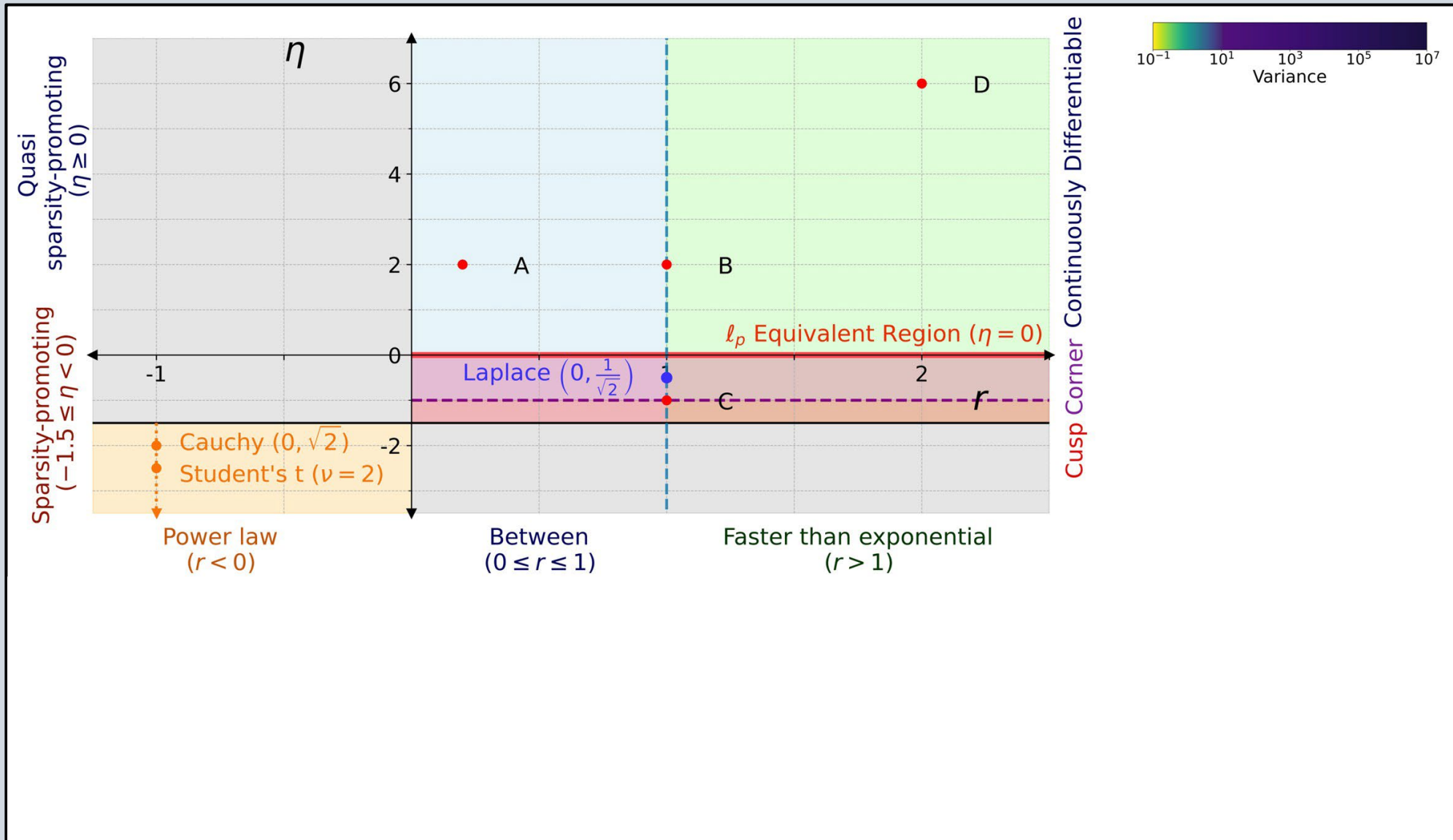
$$\textbf{(1)} \Theta_j \sim \text{Generalized Gamma}(r_j, \beta_j, \vartheta_j) \quad \rightarrow \quad \textbf{(2)} X_j | (\Theta_j = \theta) \sim \text{Normal}(0, \theta^2)$$

This model promotes sparsity when $\eta = r \beta - \frac{3}{2} \leq 0$.

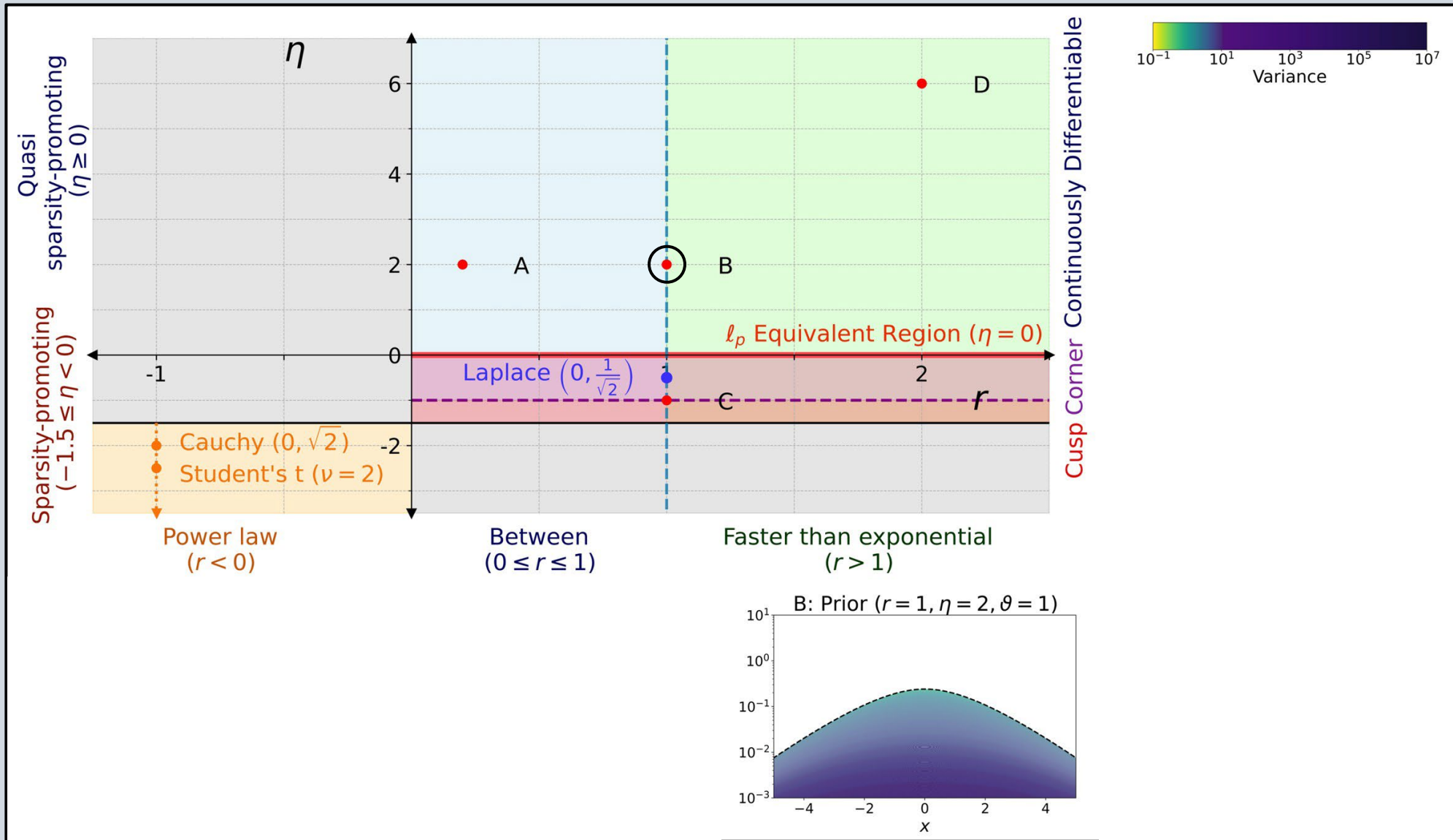
This model has **two shape parameters** (r, η) and **one scale parameter** (ϑ)



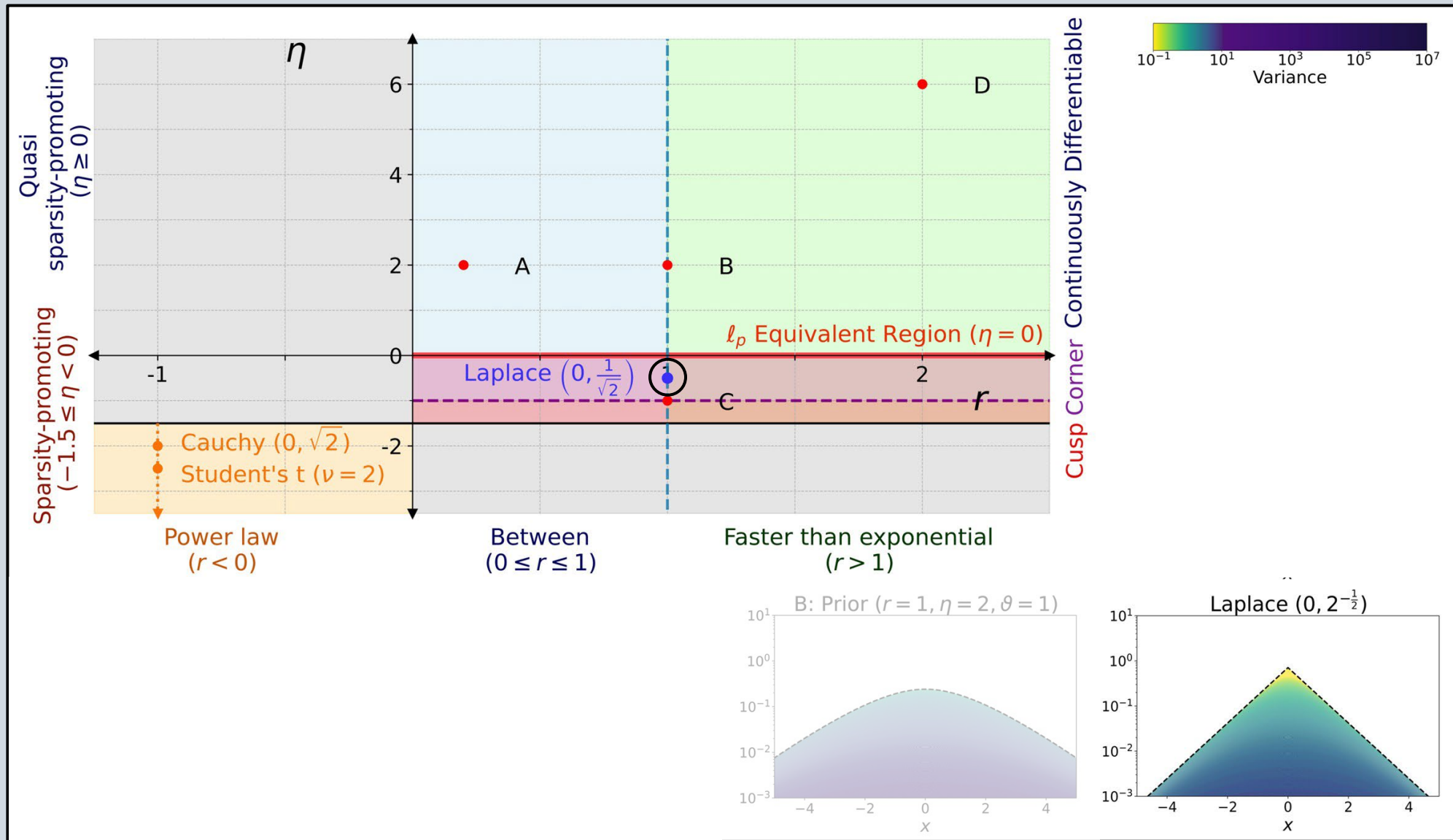
This model is a **generalized-gamma scale mixture of normals**.



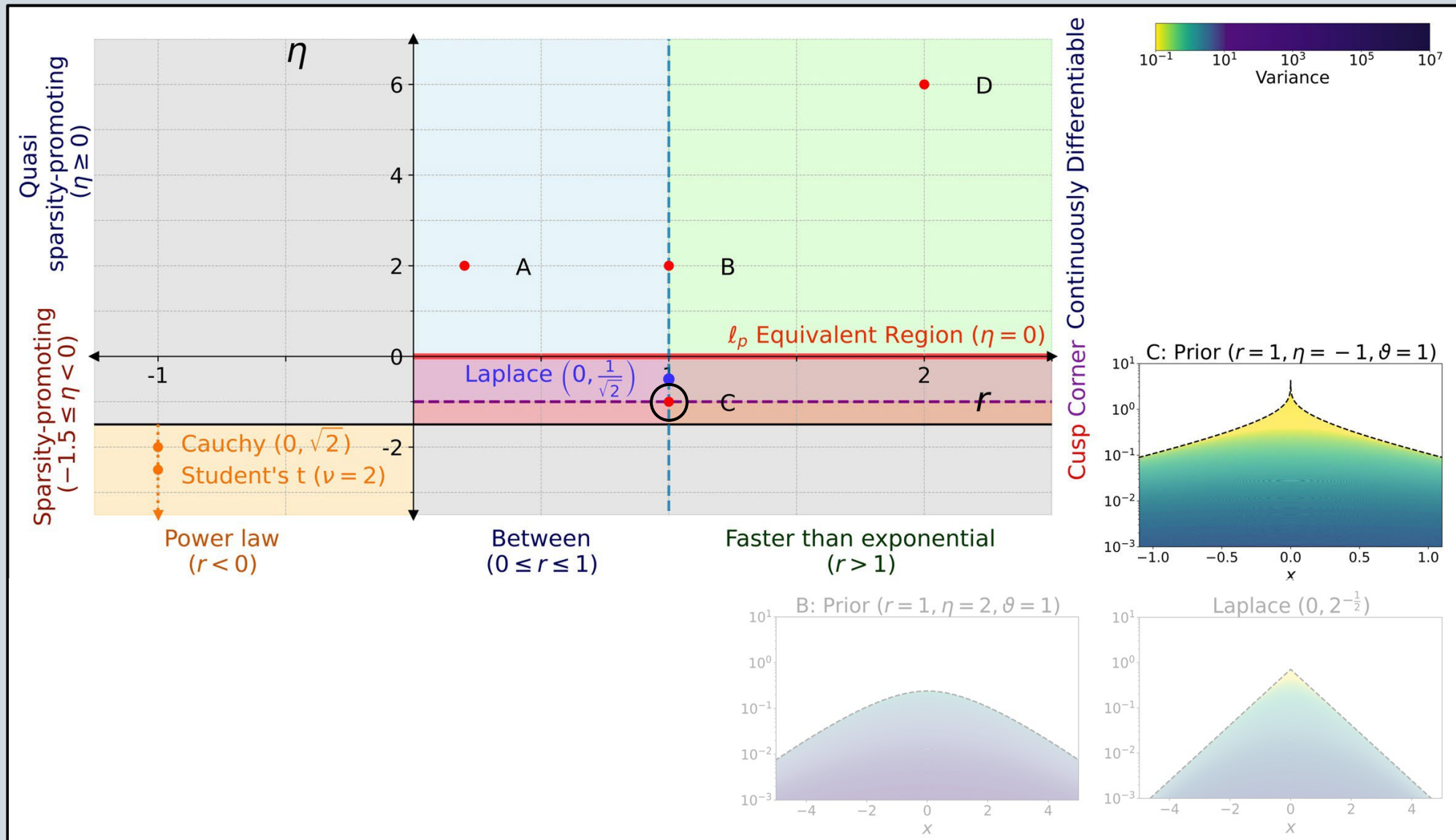
The shape parameters provide **separate control over the bulk (η)** and **tails (r)** of the prior.



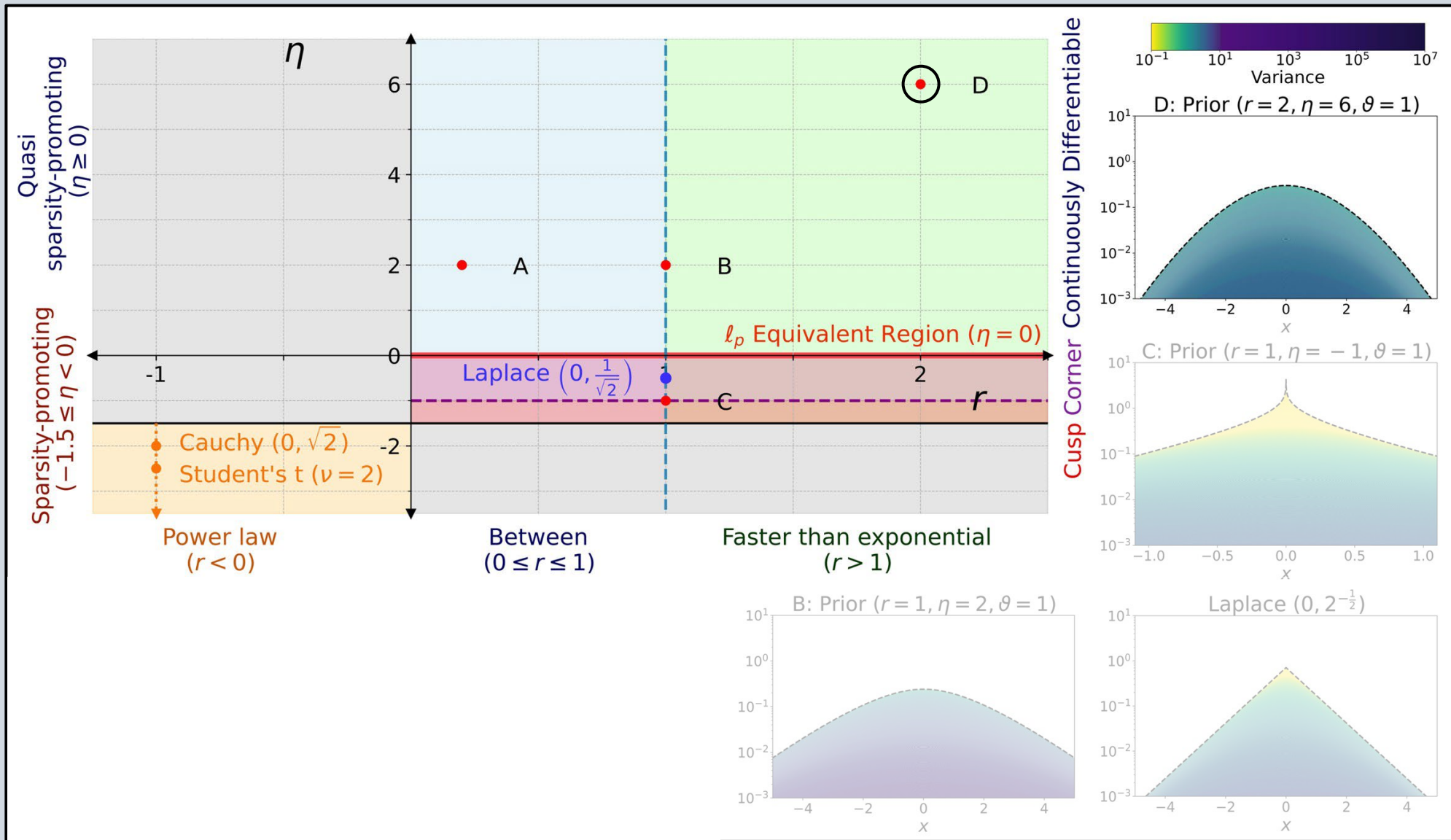
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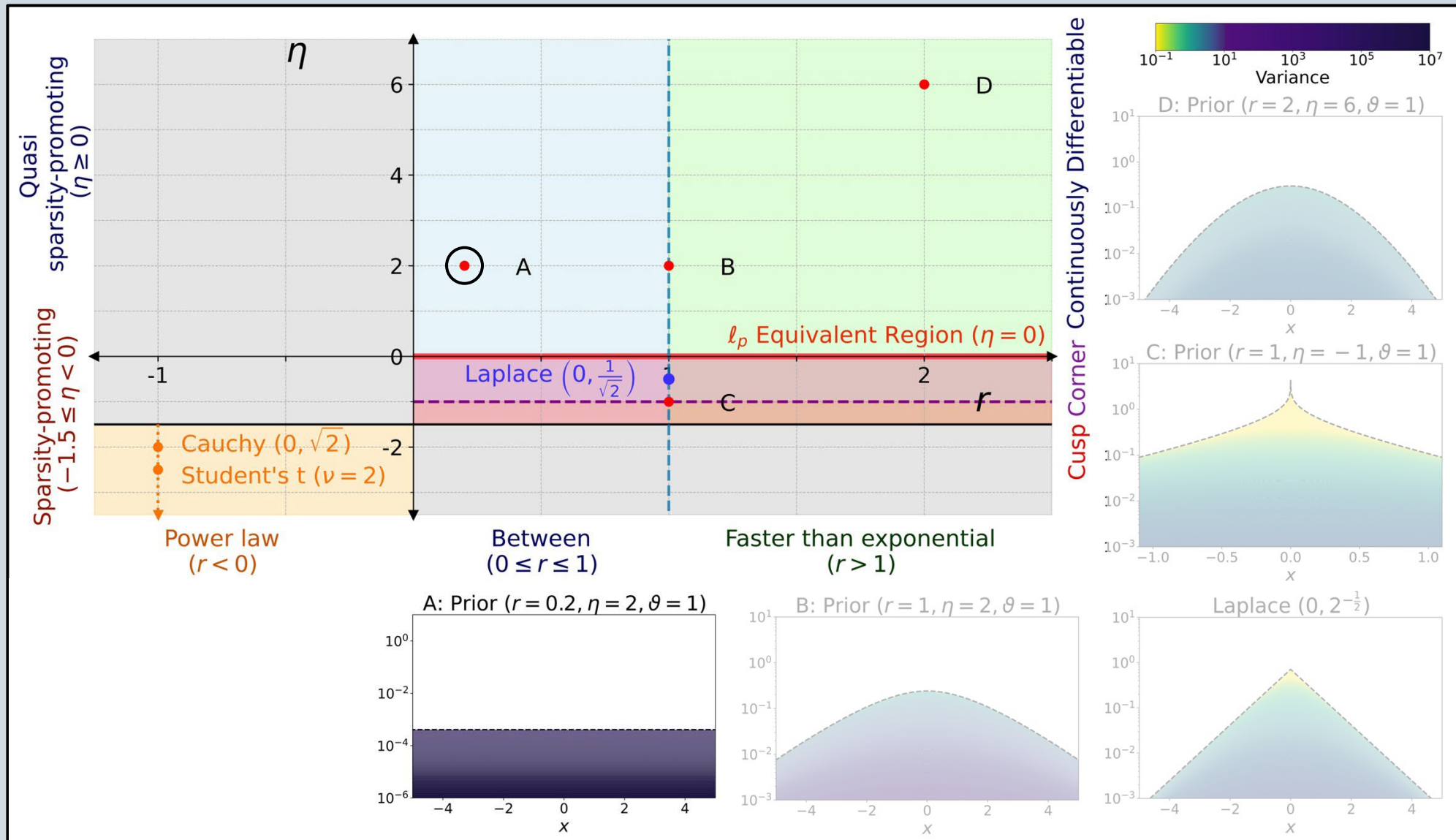
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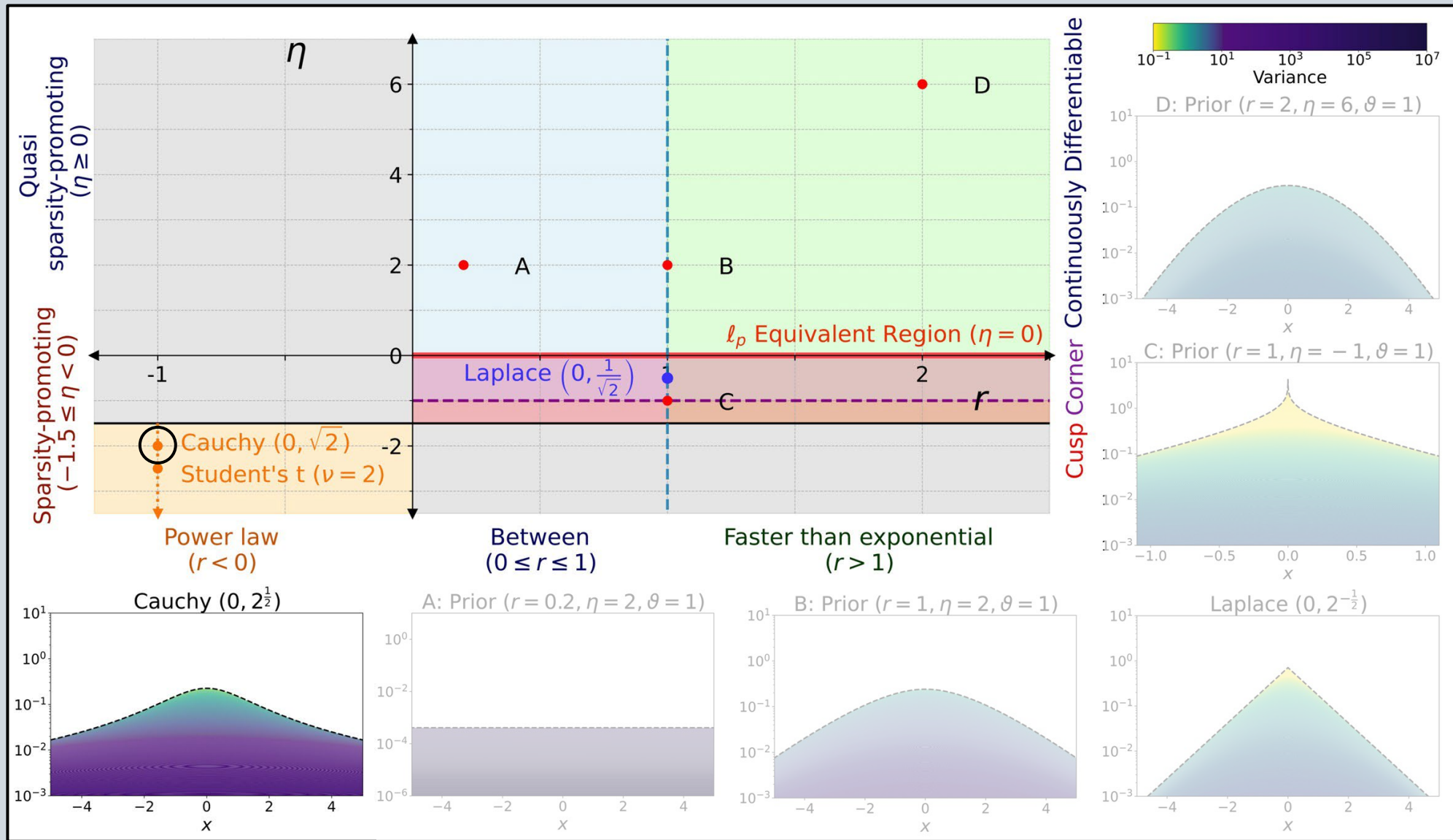
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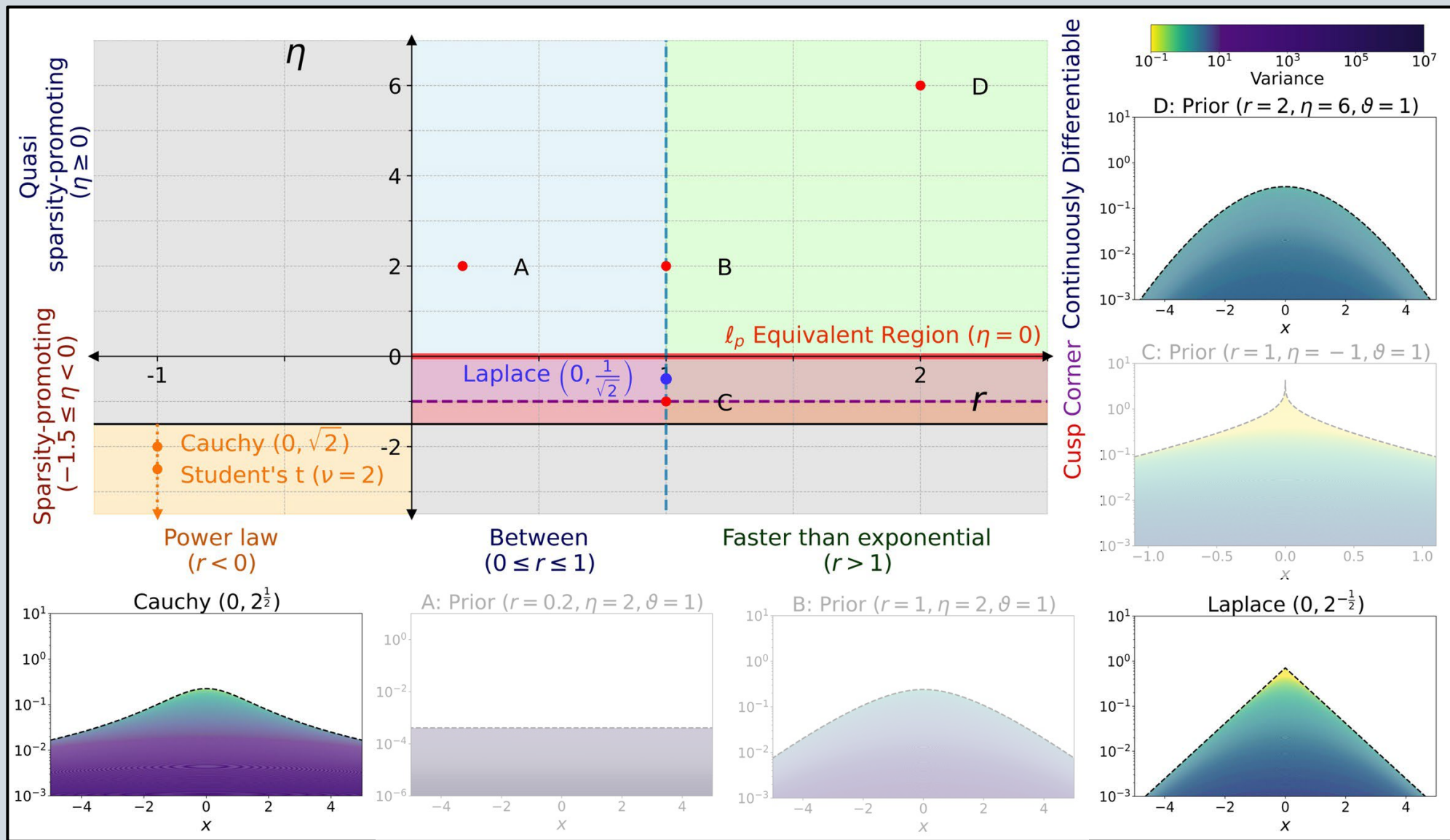
The shape parameters provide **separate control over the bulk (η) and tails (r)** of the prior.



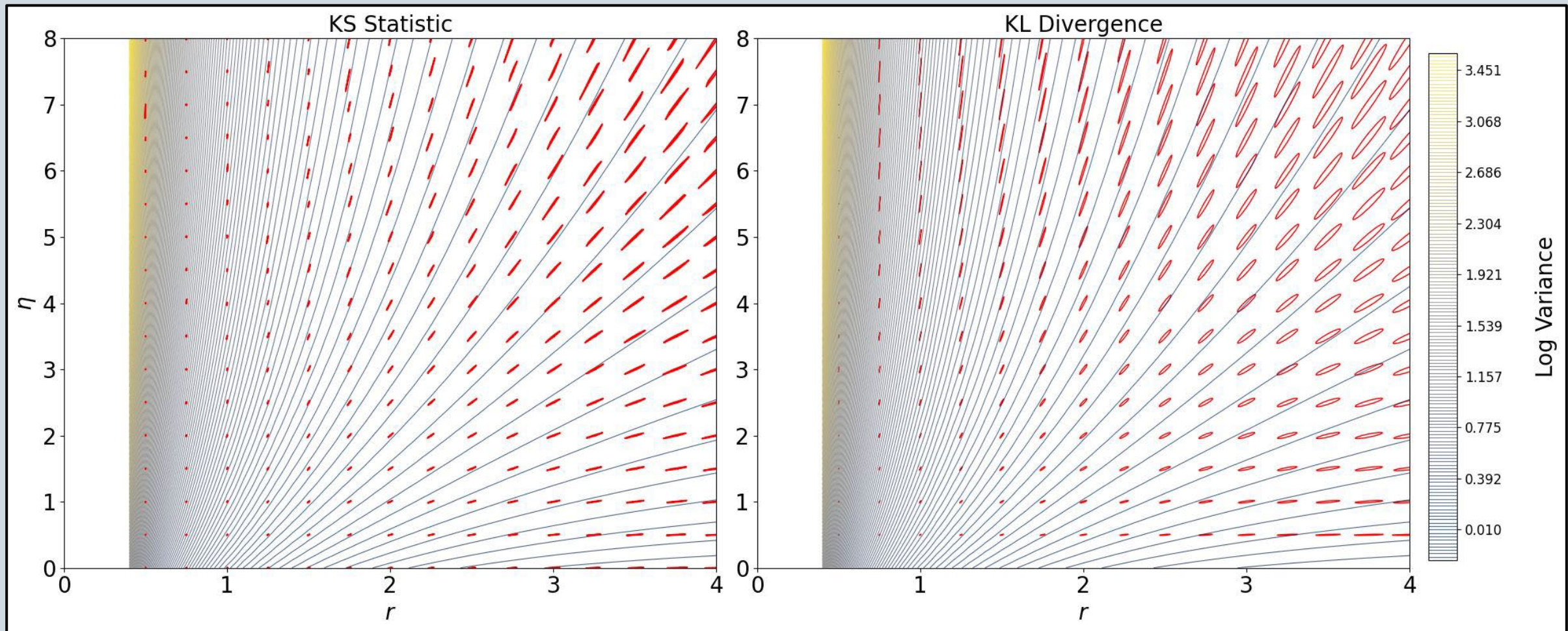
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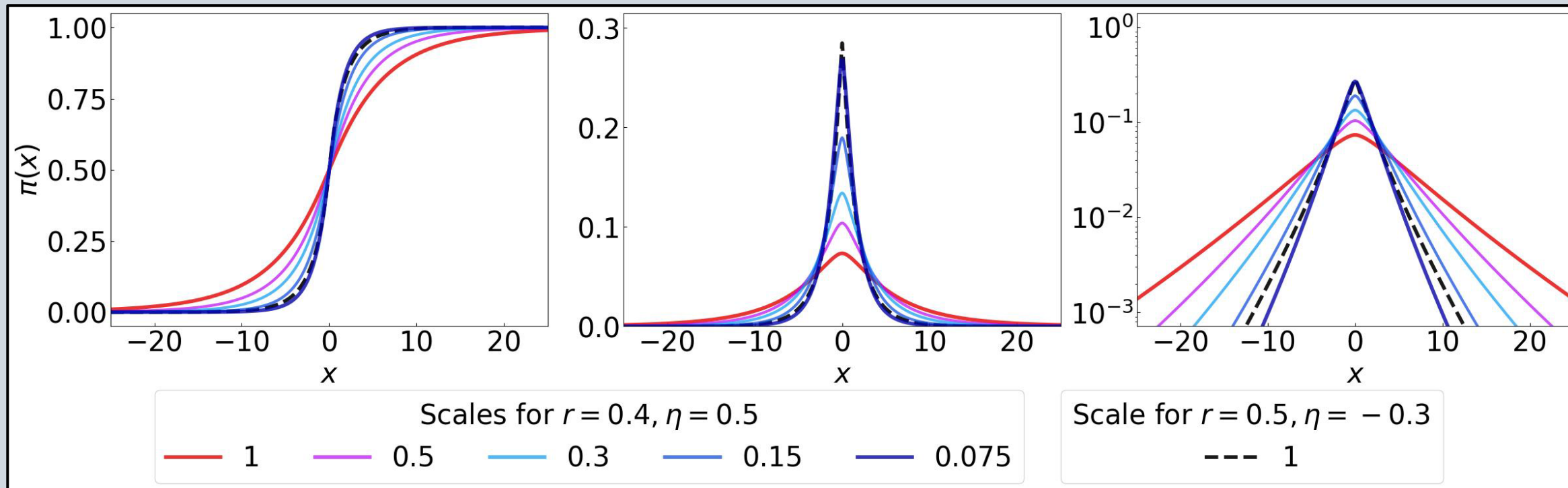


t-distributions, Laplace distributions (any ℓ_p), and Gaussian distributions are special cases.



Given fixed scale, the shape parameters are identifiable.

For fixed scale, the prior varies most (in KL or KS) along directions which change its variance.



Variations in scale can approximately account for changes in the shape parameters.

Collectively, r, η, ϑ are approximately unidentifiable

Title	Year	Examples	Motivation
Hypermodels in the Bayesian imaging framework [SM11]	2008	Synthetic	Computational
Conditionally Gaussian hypermodels for cerebral source localization [SM5]	2009	Synthetic	Application
Sparse Bayesian image Restoration [SM2]	2010	Classic	Application
A hierarchical Krylov–Bayes iterative inverse solver for MEG with physiological preconditioning [SM6]	2015	Synthetic	Application
Bayes meets Krylov: Statistically inspired preconditioners for CGLS [SM8]	2018	Synthetic	Computational
Brain activity mapping from MEG data via a hierarchical Bayesian algorithm with automatic depth weighting [SM7]	2019	Real and Synthetic	Application
Hierarchical Bayesian models and sparsity: ℓ^2 -magic [SM12]	2019	Synthetic	Computational
Sparse reconstructions from few noisy data: analysis of hierarchical Bayesian models with generalized gamma hyperpriors [SM10]	2020	Synthetic	Computational
Sparsity promoting hybrid solvers for hierarchical Bayesian inverse problems [SM9]	2020	Synthetic	Computational

Overcomplete representation in a hierarchical Bayesian framework [SM20]	2020	Synthetic	Computational
A variational inference approach to inverse problems with gamma hyperpriors [SM1]	2022	Synthetic	Computational
Hierarchical ensemble Kalman methods with sparsity-promoting generalized Gamma hyperpriors [SM17]	2022	Synthetic	Computational
Hierarchical Ensemble Kalman Methods with Sparsity-Promoting Generalized Gamma Hyperpriors [SM17]	2022	Synthetic	Computational
Sparsity promoting reconstructions via hierarchical prior models in diffuse optical tomography [SM19]	2023	Synthetic	Computational
Sequential image recovery using joint hierarchical Bayesian learning [SM23]	2023	Real and Synthetic	Computational
Leveraging joint sparsity in hierarchical Bayesian learning [SM14]	2024	Synthetic	Computational
Efficient sampling for sparse Bayesian learning using hierarchical prior normalization [SM15]	2025	Synthetic	Computational
Efficient sparsity-promoting MAP estimation for Bayesian linear inverse problems [SM18]	2025	Classic	Computational

Despite a growing literature, **there is limited empirical validation** of the prior model.

Validation has often been limited to small sets of classical or synthetic examples. Examples using real-world data have validated a full Bayesian pipeline.

Direct validation of the prior in isolation of an inverse solver/likelihood is missing.

Motivating Question

Does the mixture model fit real-world imaging datasets?

1. If so, under what representations?
2. And, for what range of parameter values?

To adopt the prior model in absence of a first-principles justification we should trust that:

1. It fits large, real-world imaging datasets that vary in source, subject, and representation
2. It provides substantially better fits than simpler standard models
3. It's parameters can be identified accurately via empirical Bayes or the inferential process is robust to misspecification errors.

Data

SOURCES, REPRESENTATIONS, DATA TREATMENT

Data Sets

1. Satellite Images
2. Natural Images
3. Brain MRI (synthetic)

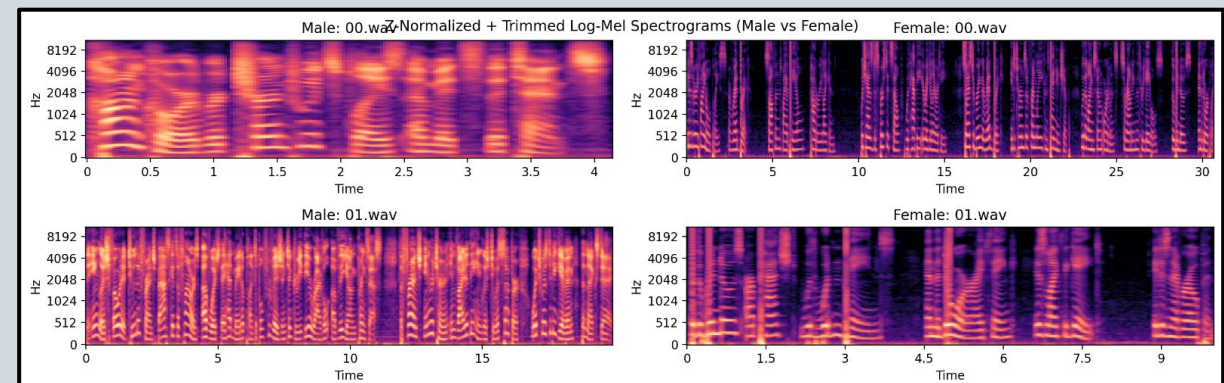
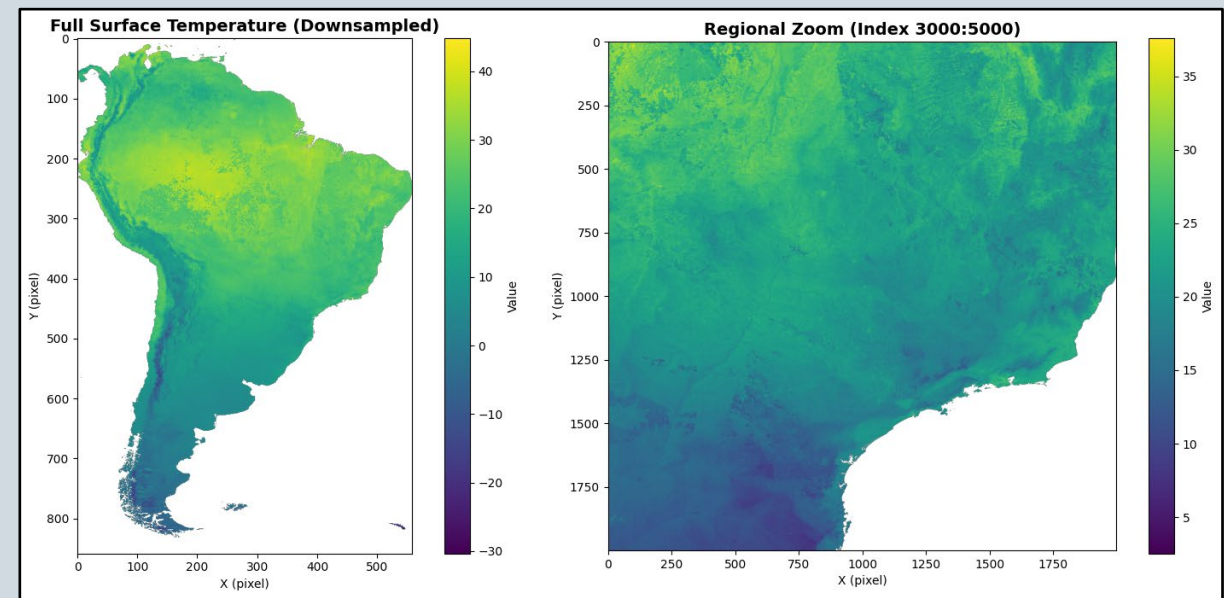
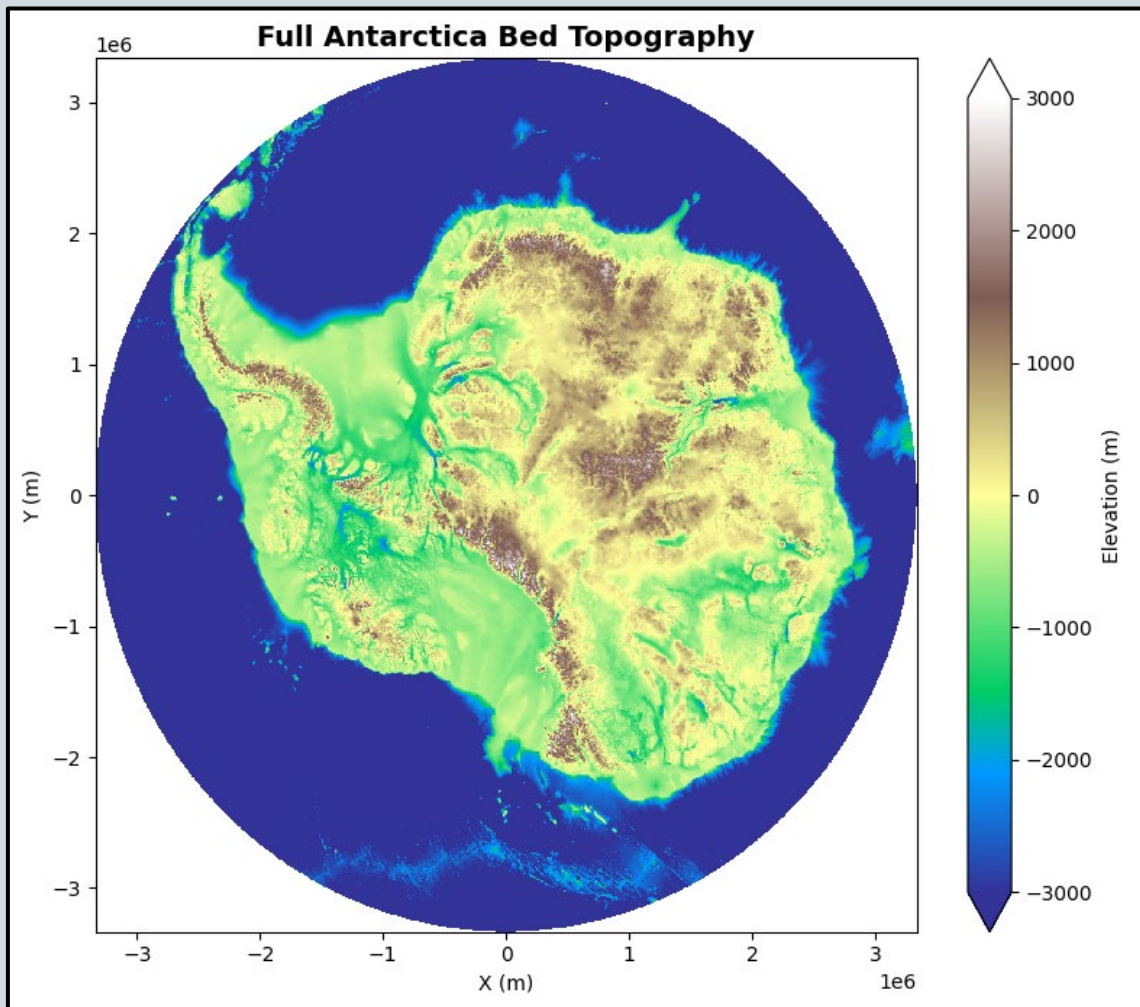
Contrast to classical image dataset.



Name	# Images	Description
agriVision	4500	Agricultural Vision, central US farmlands (256×256) [17]
pastis	1590	Panoptic Agricultural Satellite Time Series, farm fields in France (128×128) [46]
spaceNet	3401	Multi-Sensor All Weather Mapping Dataset, centered in Rotterdam (400×400) [41]
coco	4050	Common Objects in Context, split into indoor/outdoor subsets (256×256) [31]
segmentAnything	7072	Natural image dataset, compiled for training segmentation models (512×512) [30]
syntheticMRI2D	3000	2D synthetic MRI brain images, split into axial (333×234), coronal (244×234), and sagittal slices (174×234) [39]
syntheticMRI3D	100	3D synthetic MRI brain images ($160 \times 224 \times 160$) [39]

Ongoing study of geospatial data (Antarctic bedmap, surface temperature, magnetic anomalies) and audio (speech).





Example geospatial and audio data.

Work on these datasets is ongoing. **Preliminary results are consistent with the completed studies.**

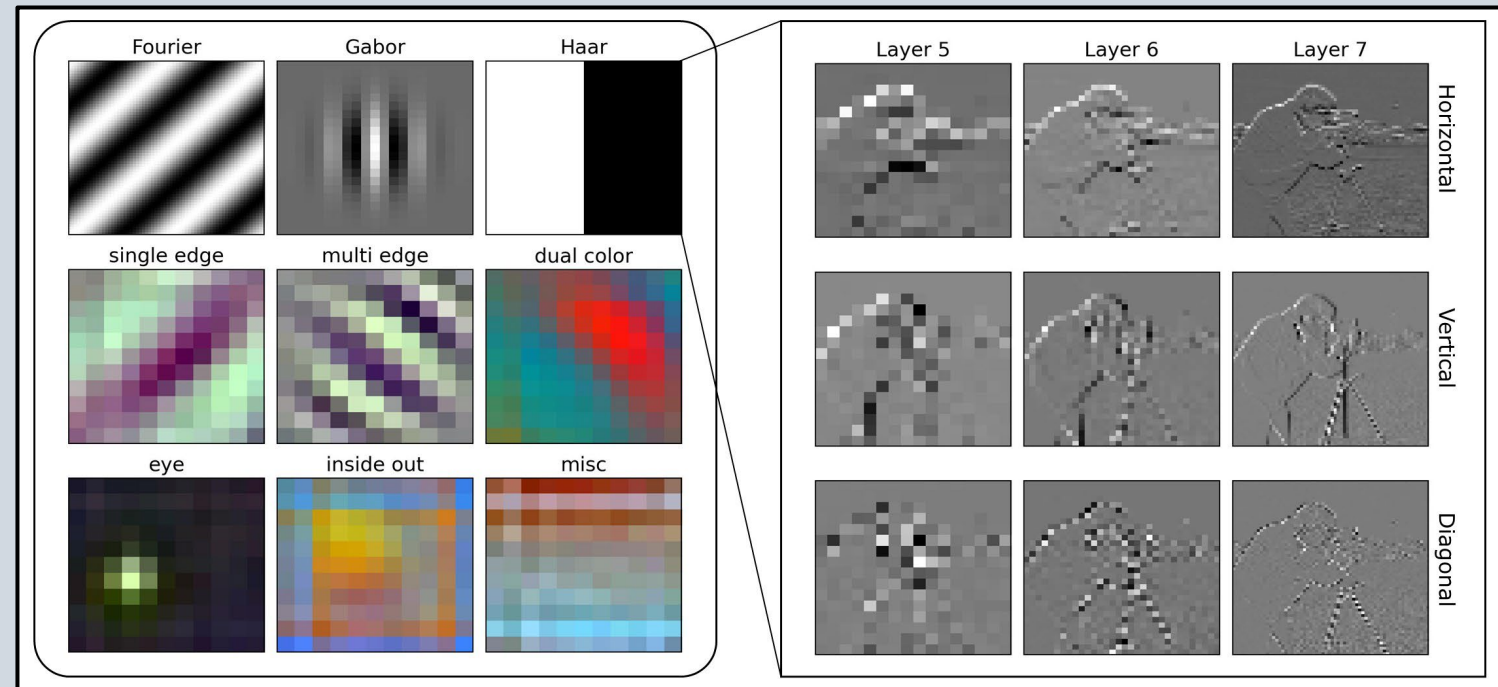
Representations

Images:

1. Fourier
2. Gabor Wavelet
3. Haar Wavelet
4. AlexNet Filter Bank

Audio:

1. Fourier
2. Short-time Fourier
3. Continuous Wavelet
4. Erblet

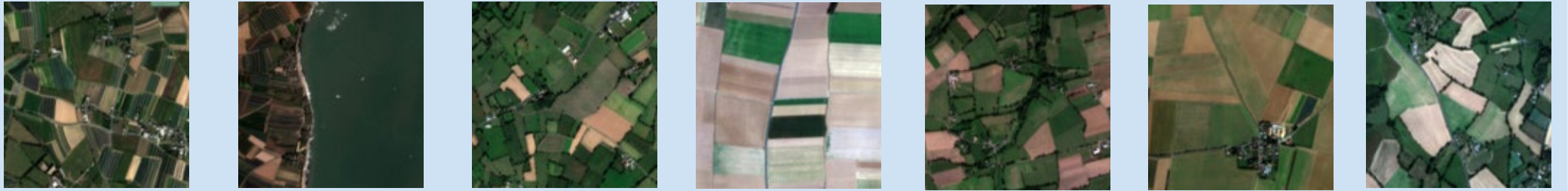


Data Treatment

1. Standardize (center, scale) and symmetrize (augment with reflections)
2. Transform by convolving with a filter bank (change representation)
3. Group the resulting coefficients and assign all coefficients within a group the same prior parameters.

Step (3.) treats all coefficients assigned to a group as if identically distributed.

Original:



Augmented:



Grouping coefficients is equivalent to **augmenting the dataset**, where all coefficients assigned to a group are randomly exchanged.

Some coefficients are **approximately exchangeable** (e.g. waves of similar wavelength, coefficients that can be exchanged by rotations or reflections), so modeling the augmented data introduces **negligible** misspecification errors.

Otherwise, **augmentations introduce misspecification errors.**

We accept an augmentation if those errors could:

1. Be corrected by a likelihood,
2. Produce artifacts that could be corrected post-hoc,
3. Produce artifacts that do not interfere with the user objectives.

And, if grouping:

1. Combines coefficients that would plausibly be modeled as identical, and
2. Significantly reduces the number of separate coefficients to model.

Image Augmentation	Transform	Coefficient Augmentation	Types of Misspecification Error
Translation	Fourier	Group real and imaginary parts	Negligible error due to approximate exchangeability.
Spatial Permutation	Haar	Group by orientation per layer	Likelihood constrained misspecification due to collaging effect resolved by data.
	Gabor	Group by filter	
	Learned		
Rotation (90°)	Haar	Group horizontal and vertical details	Negligible error due to approximate exchangeability.
Rotation (Arbitrary)	Fourier	Group by frequency components	Arbitrary rotations are Irrelevant Artifacts.
	Gabor	Group over orientation per filter	
Scaling	Fourier	Group similar frequency components	Negligible error due to approximate exchangeability.
Symmetrization	Haar	Append negated coefficients	Recoverable Artifacts after inspection
	Gabor		

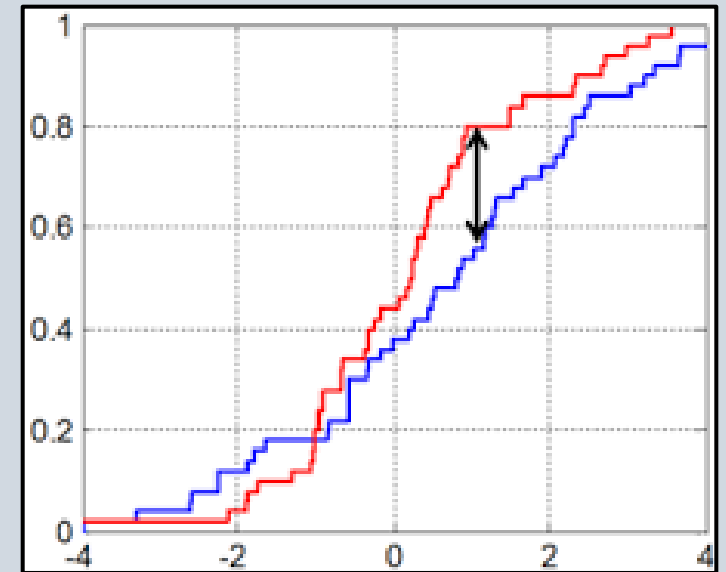
Methods and Results

INDEPENDENCE, HYPOTHESIS TESTING (KS), FIT EVALUATION

Test Procedure

For each coefficient group we:

1. **Sweep over outlier rejection thresholds** and estimate empirical variance, then standardize the data to each empirical variance. This is equivalent to selecting a series of **scale parameters**.
2. Run a grid **search over the shape parameters for each choice of scale parameter**
3. **Evaluate fit** using the one-sample **Kolmogorov-Smirnov (KS) distance (practical significance)**
4. **Test the statistical significance** of observed discrepancies using a **KS test**
5. Return the regions of shape and scale parameters that pass (3) or pass (4)



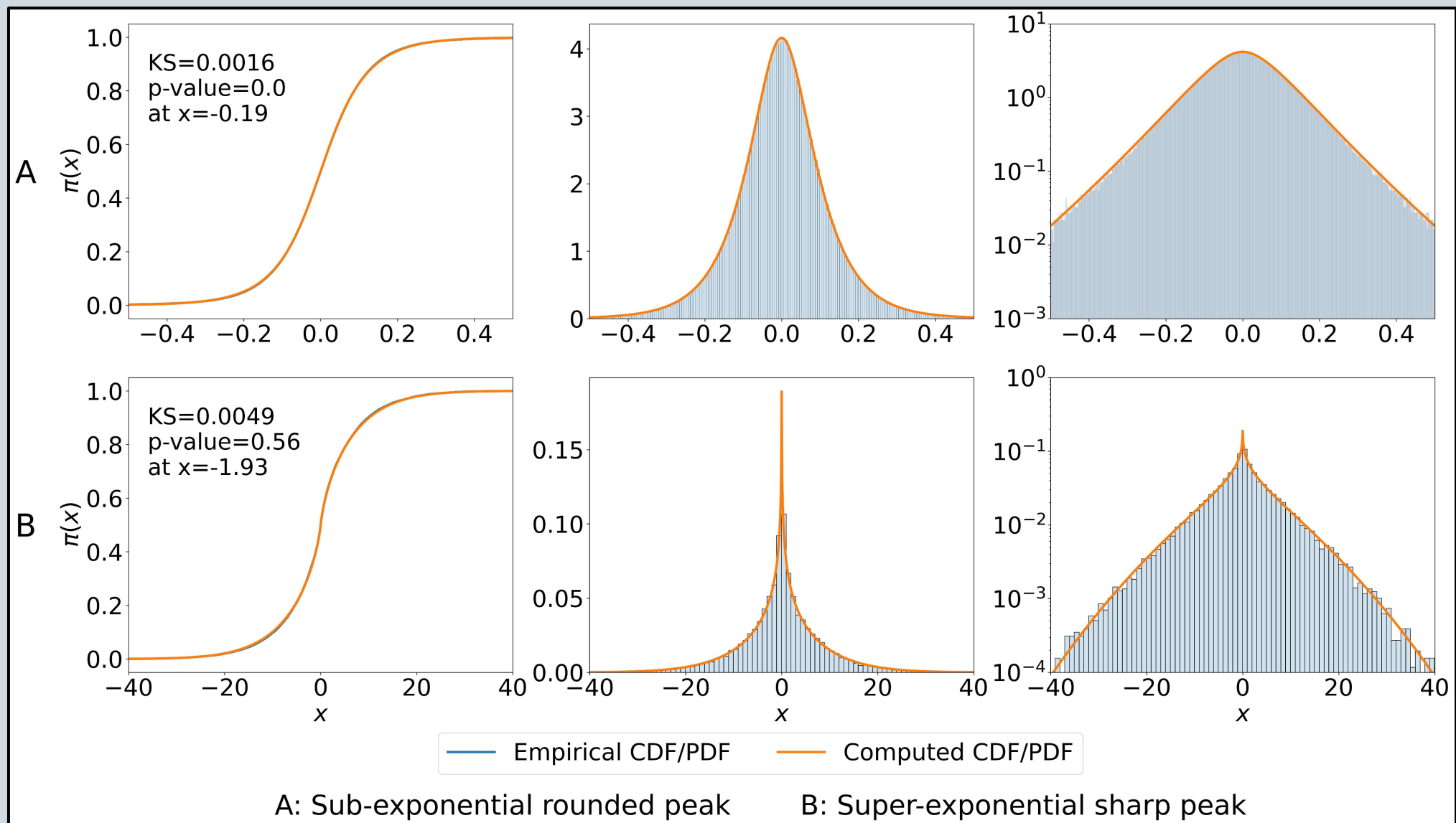
Test Procedure

We **do not apply any multiple testing correction** since we don't believe any data actually comes from our model.

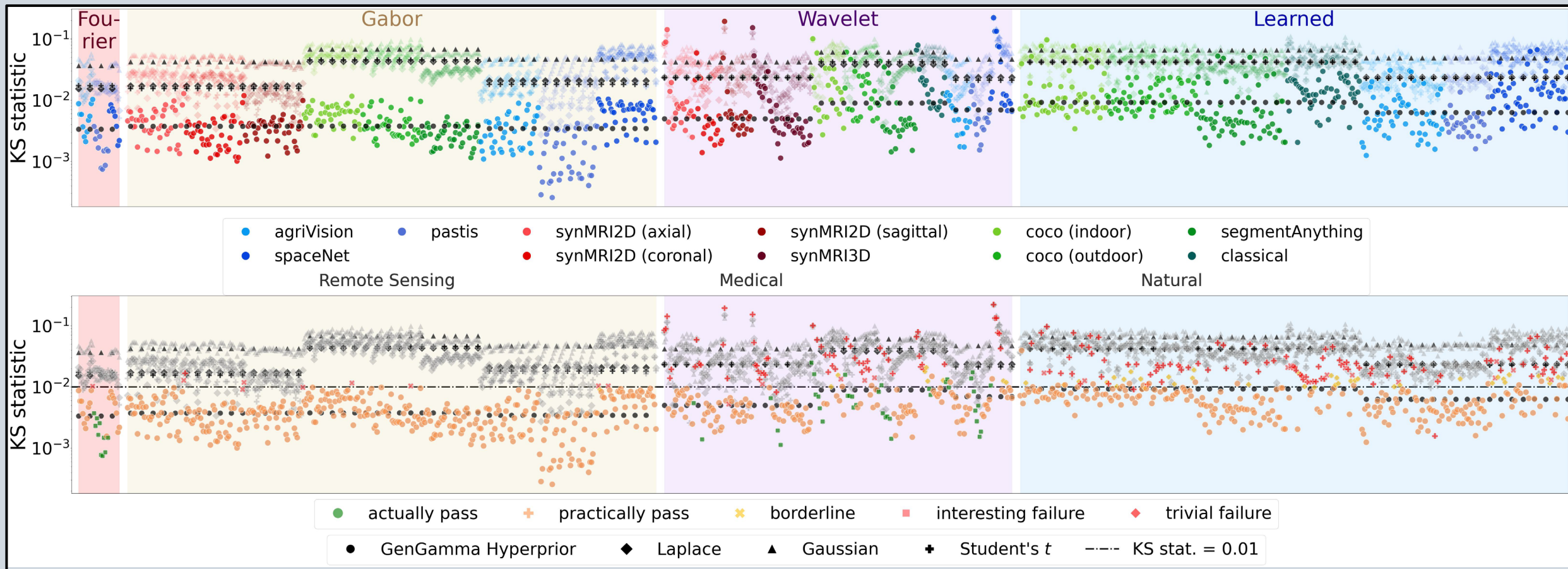
- ☐ When the fit passes step (4) we interpret it as an example where the discrepancy between the model and the data is too small to falsify the model.
- ☐ If the statistical standard is stringent, then discrepancies that are too small to falsify the model are likely too small to produce inferential errors.

We check all borderline cases by eye **to classify model failures** and to ensure our fit standards are conservative.

- ☐ Statistical Pass = p-value greater than 0.05, more than 100 samples
- ☐ Practical Pass = KS statistic smaller than 0.01, corroborated by eye

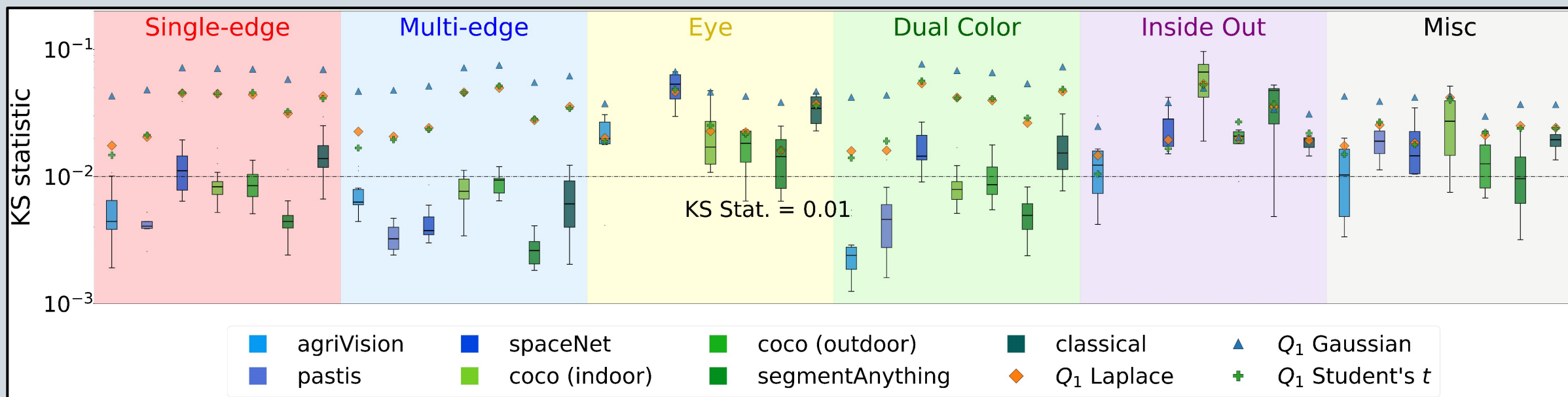


The hierarchical **prior** can achieve **high fidelity fits** for **non-standard distributions**.



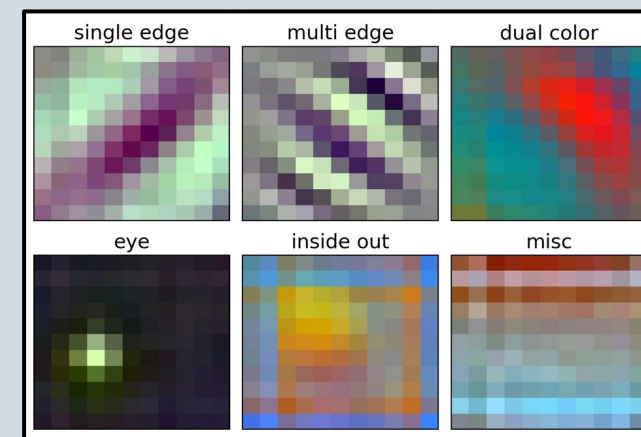
The KS statistic is often small (< 0.02), and in almost all cases an order of magnitude smaller than for standard models.

In most cases, discrepancies are statistically significant, but small.



Tend to see better fits for filters that are:

1. **wavelet like** (edge detectors),
2. **smooth** (Gabor > Haar),
3. **higher frequency** (though trends vary by dataset and filter).

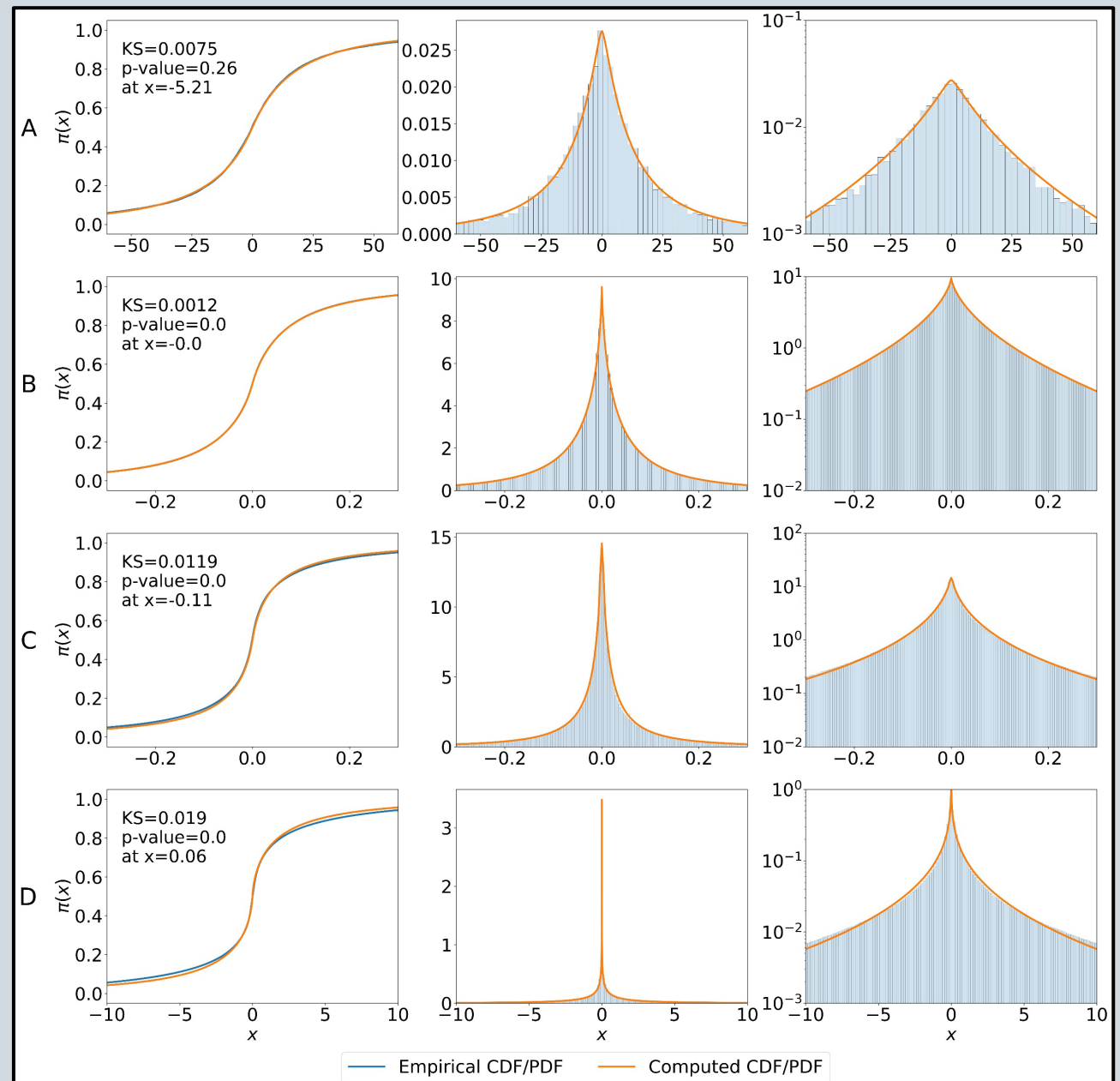


Example Fit Outcomes:

- **A:** statistically pass
- **B:** practically pass
- **C:** borderline case (rejected)
- **D:** Interesting failure (rejected)

In many cases (e.g. C, D) we **rejected fits that would be unlikely to produce inferential errors.**

Categorized borderline cases by hand to ensure thresholds for acceptance were defined conservatively.

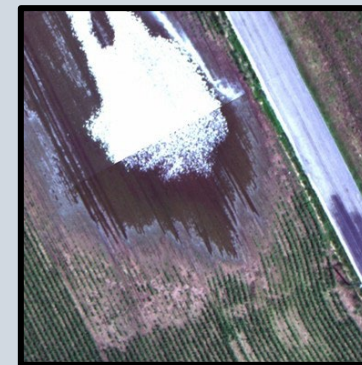
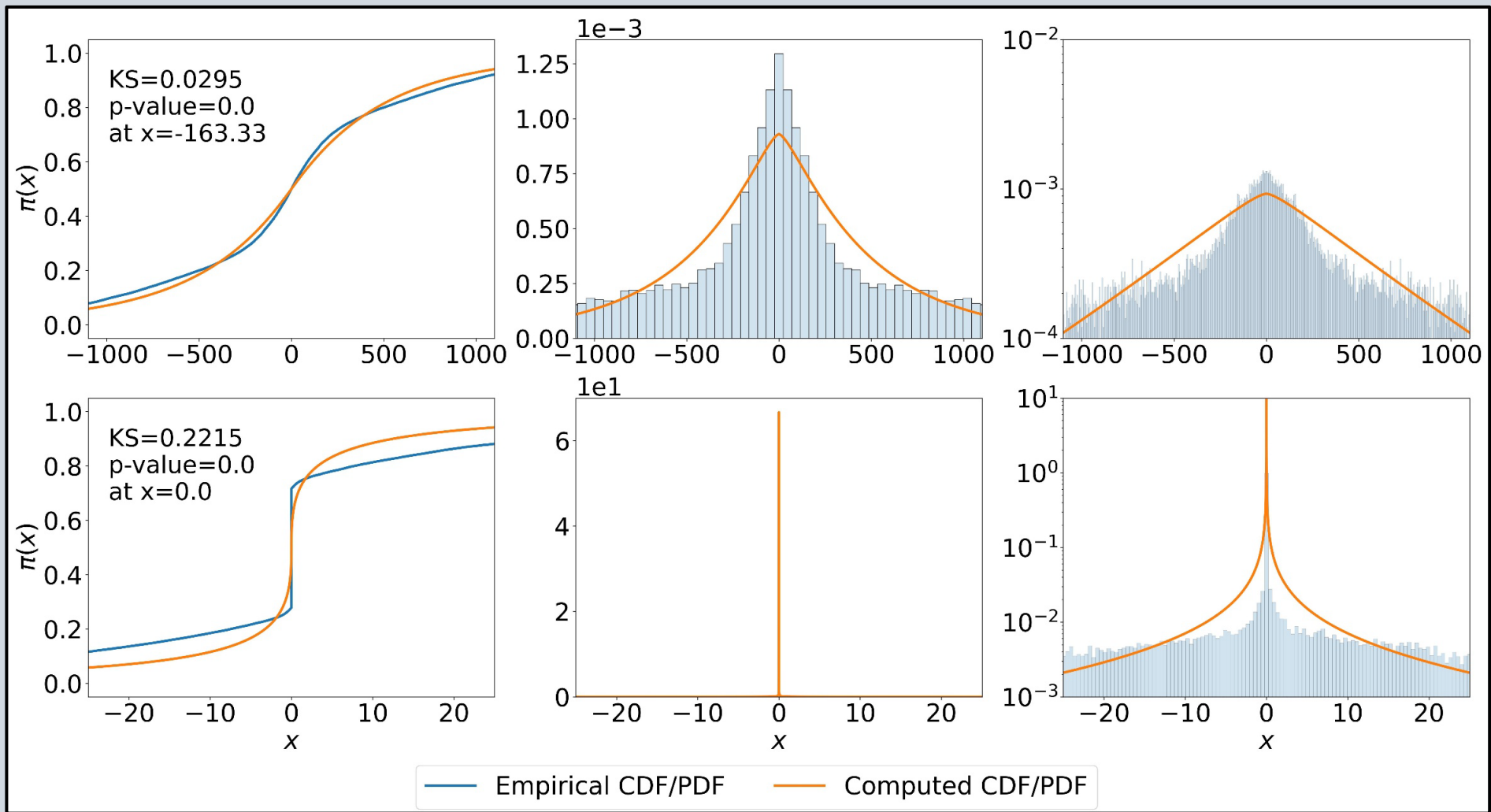


Transform	Dataset	Median Samples	Median KS Stat.	Stat. Pass $\alpha = 0.05$ (%)	Combined Pass (%)
Fourier	agriVision	2.6e6	0.005	2.3	95.5
	pastis	2.6e5	0.002	90.9	100.0
	spaceNet	1.8e6	0.005	0.0	100.0
	Remote Sensing	5.5e5	0.003	34.2	98.4
Gabor	synMRI2D (axial)	1.8e8	0.005	0.0	95.2
	synMRI2D (coronal)	1.4e8	0.003	0.0	95.2
	synMRI2D (sagittal)	9.7e7	0.004	0.0	97.6
	Medical	1.4e8	0.004	0.0	96.0
	coco (indoor)	6.6e7	0.006	0.0	97.0
	coco (outdoor)	6.6e7	0.004	0.0	95.8
	segmentAnything	2.6e8	0.003	0.0	100.0
	standardTesting	2.4e6	0.008	0.0	57.1
	Natural	6.6e7	0.004	0.0	94.5
	agriVision	2.6e8	0.003	0.0	100.0
	pastis	1.6e7	0.001	0.6	100.0
	spaceNet	1.6e8	0.007	0.0	92.9
	Remote Sensing	1.6e8	0.003	0.2	97.6

Headline Numbers:

- Median KS = **0.005**,
- % Statistically Pass = **7.3%** for median sample size 60 million
- % Practically Pass = **83.5%** at KS < 0.01 standard

Haar	synMRI2D (axial)	4.2e6	0.007	0.0	76.2
	synMRI2D (coronal)	3.7e6	0.004	9.5	80.9
	synMRI2D (sagittal)	2.4e6	0.005	0.0	81.0
	synMRI3D	1.6e6	0.005	7.1	69.0
	Medical	2.9e6	0.005	4.8	75.3
	coco (indoor)	2.6e5	0.013	25.0	50.0
	coco (outdoor)	3.9e5	0.011	25.0	53.1
	segmentAnything	1.8e6	0.004	25.0	85.2
	standardTesting	9.2e3	0.013	9.5	47.6
	Natural	4.1e5	0.008	24.0	62.6
	agriVision	1.7e6	0.005	15.3	100.0
	pastis	1.5e5	0.004	57.1	100.0
	spaceNet	1.6e6	0.012	4.7	53.1
	Remote Sensing	7.0e5	0.007	24.0	84.4
Learned	coco (indoor)	2.0e8	0.009	0.0	64.5
	coco (outdoor)	2.0e8	0.010	0.0	57.8
	segmentAnything	7.9e8	0.005	0.0	81.2
	standardTesting	7.1e6	0.014	0.0	24.1
	Natural	2.0e8	0.009	0.0	58.2
	agriVision	7.9e8	0.005	0.0	73.3
	pastis	4.9e7	0.004	0.0	93.8
	spaceNet	4.8e8	0.013	0.0	42.9
	Remote Sensing	4.8e8	0.006	0.0	66.2

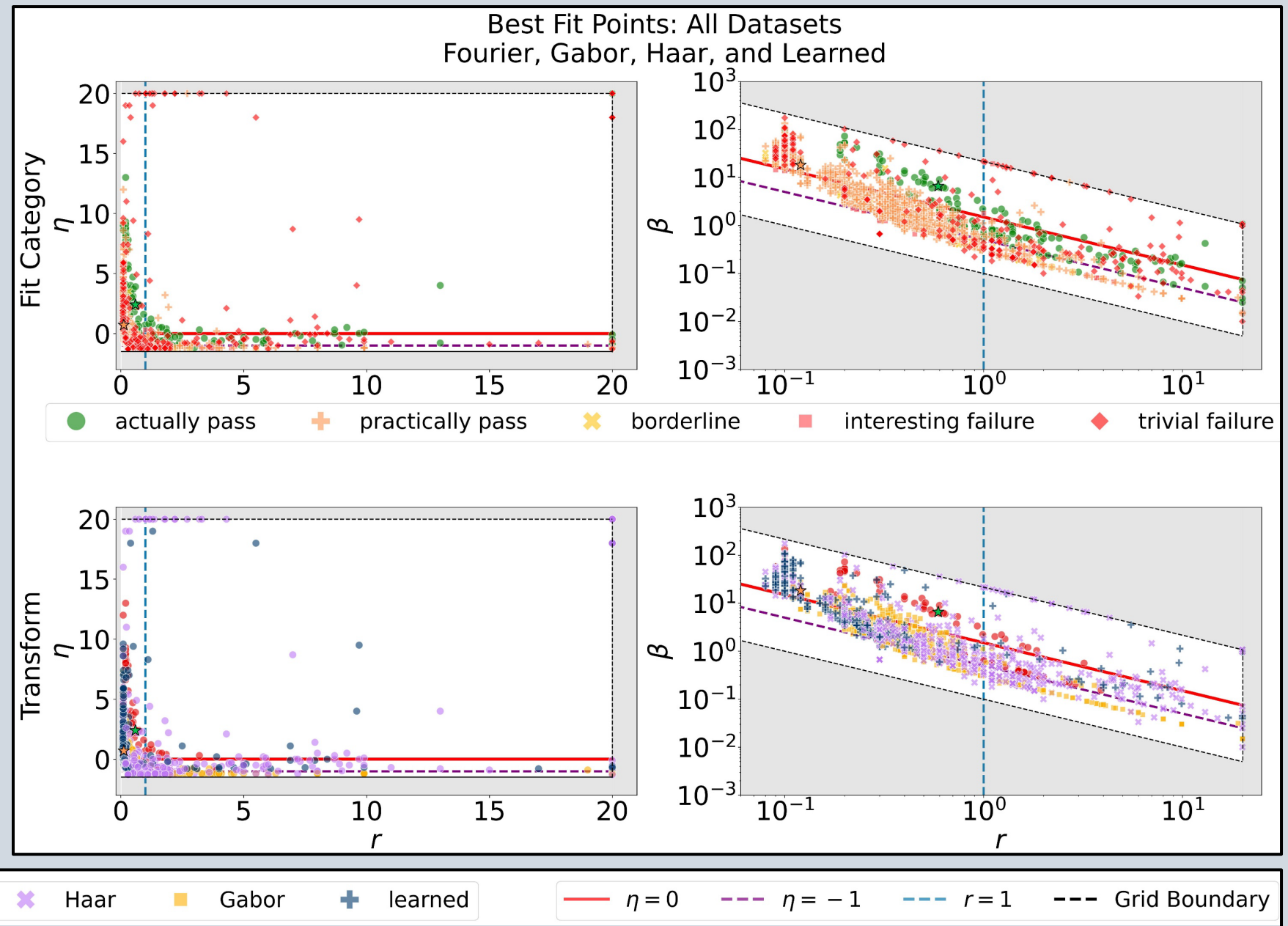


Not all examples fit.

Best fit shape parameters vary widely.

Are **not** limited to small η (e.g. ℓ_p priors).

Shape parameters are poorly identified if scale can vary.



Discussion

LIMITATIONS, FUTURE/ONGOING WORK, PREPRINT

Limitations and Future Work

1. The KS statistic is relatively insensitive to tail behavior, cannot precisely resolve r
 - Run an intersection test using KS and Anderson-Darling
2. Expand to study other image data sets (geospatial) and signals (audio)

Thank you for your attention and for the invitation to attend!

Preprint (repository and bibliography):

Do Generalized Gamma Scale Mixtures of Normals Fit Large Image Datasets?

Brandon Marks, Yash Dave, Zixun Wang, Hannah Chung, Riya Patwa, Simon Cha, Michael Murphy, and Alexander Strang. (2025).

<https://arxiv.org/abs/2512.17038>



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