

# Measuring the Importance of Facets of Cyclic Group Polyhedra Using Solid Angles

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Joint work with Allison Fitisone

# Overview

- ① Cyclic group relaxation of IP
- ② Measure relative sizes of the facets
- ③ Compute solid angle measure in  $\mathbb{R}^n$

## General purpose cutting planes

Many widely used general-purpose cuts are derived from a **single row** of the optimal simplex tableau:

$$\mathbf{x}_B = A_B^{-1}\mathbf{b} + (-A_B^{-1}A_N)\mathbf{x}_N, \quad \mathbf{x}_B \in \mathbb{Z}_+^B, \quad \mathbf{x}_N \in \mathbb{Z}_+^N.$$

Gomory Mixed Integer Cut Example:

- Tableau row:

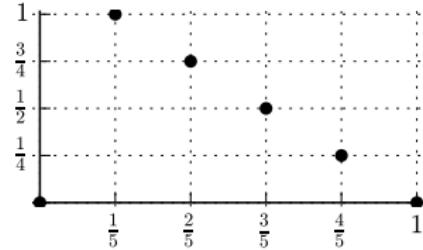
$$x = -\left(-\frac{4}{5}\right) + \frac{2}{5}x_1 - \frac{1}{5}x_2 + \frac{11}{5}x_3,$$

where  $x, x_1, x_2, x_3 \in \mathbb{Z}_+$ .

- Determine the cut:

$$?x_1 + ?x_2 + ?x_3 \geq 1.$$

- Cyclic group order  $q = 5$
- $\left(-\frac{4}{5}\right) \equiv \frac{1}{5} \pmod{1}$
- GMIC function  $\pi_{\text{mic}}$



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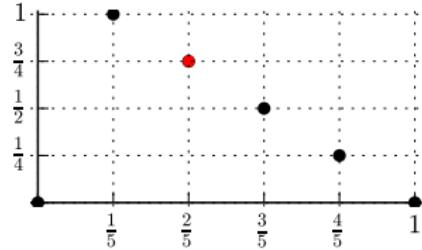
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where  $x, x_1, x_2, x_3 \in \mathbb{Z}_+$ .

- Determine the cut:

$$\frac{3}{4}x_1 + \frac{1}{4}x_2 + 1x_3 \geq 1.$$

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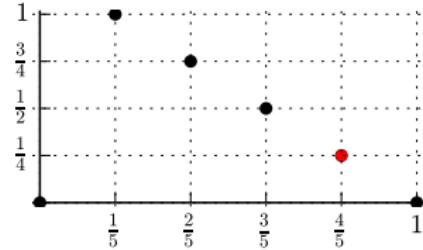
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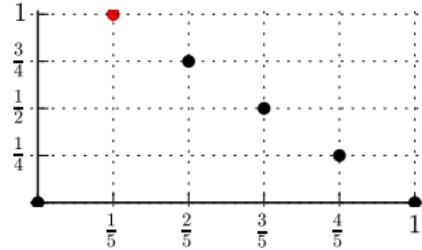
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# Cyclic group relaxation

- Tableau row:  $x = -\left(-\frac{4}{5}\right) + \frac{2}{5}x_1 - \frac{1}{5}x_2 + \frac{11}{5}x_3, \quad x, x_1, x_2, x_3 \in \mathbb{Z}_+$ .
  - ▶ Relax  $x$  from  $\mathbb{Z}_+$  to  $\mathbb{Z}$ :

$$0 \equiv -\frac{1}{5} + \frac{2}{5}x_1 + \frac{4}{5}x_2 + \frac{1}{5}x_3 \pmod{1}$$

- ▶ Introduce  $\mathbf{z} \in \mathbb{Z}_+^{q-1}$ :

$$\frac{1}{5} \equiv \frac{1}{5}z_1 + \frac{2}{5}z_2 + \frac{3}{5}z_3 + \frac{4}{5}z_4 \pmod{1}$$

- ▶  $q = 5$  and  $f = 1$

- Master cyclic group polyhedron

$$P(q, f) := \text{conv} \left\{ \mathbf{z} \in \mathbb{Z}_+^{q-1} \mid \sum_{i=1}^{q-1} \left( \frac{i}{q} \right) z_i \equiv \frac{f}{q} \pmod{1} \right\}$$

- We are interested in  $\pi \in \mathbb{R}_+^{q-1}$  s.t.  $\pi \cdot \mathbf{z} \geq 1$  for all  $\mathbf{z} \in P(q, f)$ , and in particular, the facet-defining ones.

# Master cyclic group polyhedron and Group-facet polytope

- Blocker  $\mathfrak{B}(P(q, f)) = \left\{ \pi \in \mathbb{R}_+^{q-1} \mid \pi \cdot \mathbf{z} \geq 1 \forall \mathbf{z} \in P(q, f) \right\}$
- $P(q, f) \subseteq \mathbb{R}_+^{q-1}$  is full-dimensional, and has  $\mathbb{R}_+^{q-1}$  as recession cone.

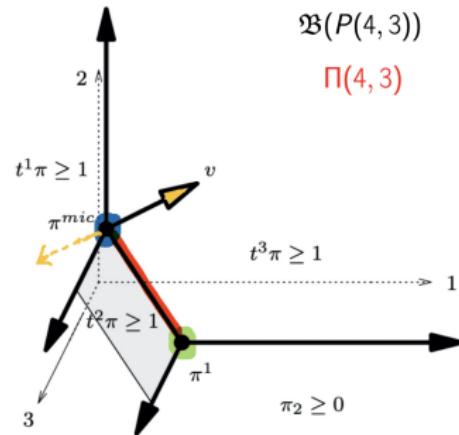
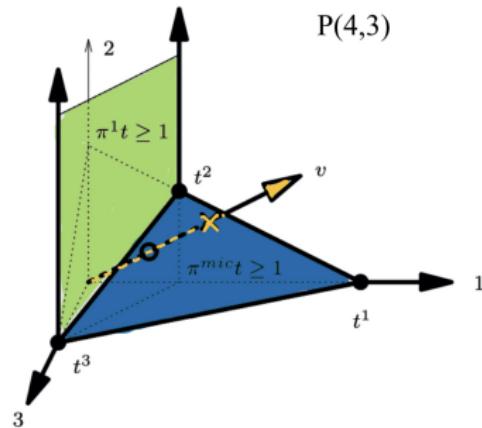
$$\implies \mathfrak{B}(P(q, f)) = \Pi(q, f) + \mathbb{R}_+^{q-1}$$

- **Group-facet polytope**  $\Pi(q, f)$  consists of  $\pi = (\pi_1, \dots, \pi_{q-1})$  with  $\pi_0 = 0, \pi_f = 1$  and satisfies
  - ▶ (nonnegativity)  $\pi_i \geq 0$  for  $i = 1, \dots, q-1$
  - ▶ (symmetry)  $\pi_i + \pi_j = 1, i+j \equiv f \pmod{q}$
  - ▶ (subadditivity)  $\pi_i + \pi_j \geq \pi_k, i+j \equiv k \pmod{q}$
- Non-trivial facet of  $P(q, f) \Leftrightarrow$  vertex of  $\Pi(q, f)$
- Number of facets / vertices  $\pi$  grows exponentially with  $q$ .
- Which  $\pi$ 's are more important?

# Relative sizes of facets — Shooting experiment

[Kuhn, 1991], [Evans, 2002], [Gomory–Johnson–Evans, 2003], [Hunsaker, 2003],  
[Dash–Günlük, 2006], [Shim, 2009], [Shim–Johnson, 2013], [Chopra–Shim–Steffy, 2015]

- Choose random direction  $\mathbf{v} \in \mathbb{R}_+^{q-1}$ .
- Move from the origin along the ray  $\lambda\mathbf{v}$  ( $\lambda > 0$ ) until hitting  $P(q, f)$ .
- Record which facet  $\pi^*$  is hit:  $\pi^* = \arg \min_{\pi} \{\pi \cdot \mathbf{v} \mid \pi \in \Pi(q, f)\}$ .
- Facets that receive more hits are deemed more important.



## Relative sizes of facets — Shooting experiment

Proportion of hits received by facets of  $P(7, 6)$  according to  
[Hunsaker, 2003] (out of 1000 shots) and [Shim, 2009] (geometry)

Facets of $P(7, 6)$						Hunsaker	Shim
1	2	3	4	5	6	0.332	0.3238
9	4	6	8	3	12	0.253	0.2500
4	8	5	2	6	10	0.245	0.2500
6	5	4	3	2	8	0.170	0.1762

Discrepancies?

# Relative sizes of facets — Shooting experiment

Proportion of hits received by facets of  $P(11, 10)$  according to  
[Hunsaker, 2003] (out of 1000 shots) and [Shim, 2009] (out of 10000 shots)

Facets of $P(11, 10)$											Hunsaker	Shim
1	2	3	4	5	6	7	8	9	10	11	0.134	0.1354
4	8	12	16	9	2	6	10	14	18	19	0.140	0.1291
9	18	16	3	12	21	8	6	15	24	25	0.089	0.0935
10	9	8	7	6	5	4	3	2	12	13	0.092	0.0872
16	21	4	20	14	8	24	7	12	28	29	0.080	0.0816
25	6	20	12	15	18	10	24	5	30	31	0.083	0.0813
8	5	2	10	7	4	12	9	6	14	15	0.070	0.0579
6	12	7	2	8	14	9	4	10	16	17	0.069	0.0646
20	7	16	14	12	10	8	17	4	24	25	0.033	0.0403
15	8	12	5	9	13	6	10	3	18	19	0.030	0.0404
13	4	6	8	10	12	14	16	7	20	21	0.037	0.0402
6	12	7	13	8	3	9	4	10	16	17	0.038	0.0297
4	8	12	5	9	13	6	10	14	18	19	0.022	0.0276
9	18	5	14	12	10	19	6	15	24	25	0.026	0.0250
14	6	20	12	15	18	10	24	16	30	31	0.013	0.0187
18	14	10	6	13	20	16	12	8	26	27	0.015	0.0173
13	15	6	8	10	12	14	5	7	20	21	0.012	0.0162
9	18	16	14	12	10	8	6	15	24	25	0.017	0.0140

# Shooting experiment size estimates solid angle

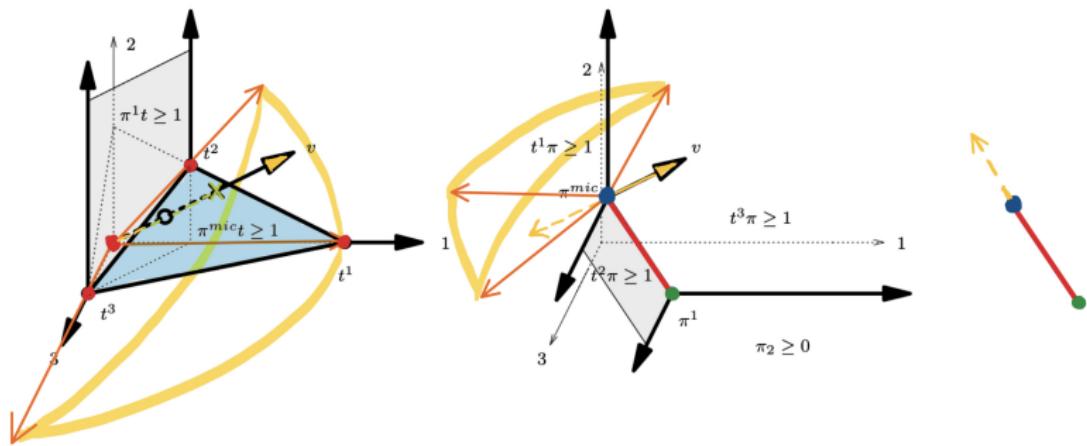
## Proposition

Shooting experiment size of a facet  $\pi \cdot z \geq 1$  of  $P(q, f)$

$\simeq$  solid angle subtended by the facet of  $P(q, f)$  at the origin

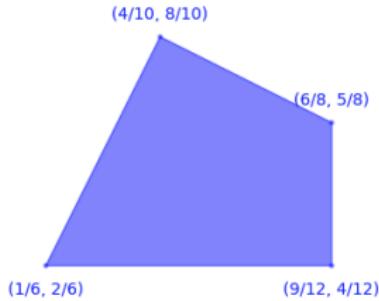
$=$  solid angle of the normal cone at the vertex  $\pi$  of  $\mathfrak{B}(P(q, f))$

$=$  (normalized) solid angle of the normal cone at the vertex  $\pi$  of  $\Pi(q, f)$



## Relative sizes of facets — Solid angle

Facets of $P(7, 6)$						Solid angle	Hunsaker	Shim
1	2	3	4	5	6	0.3238	0.332	0.3238
9	4	6	8	3	12	0.2500	0.253	0.2500
4	8	5	2	6	10	0.2500	0.245	0.2500
6	5	4	3	2	8	0.1762	0.170	0.1762



## Relative sizes of facets — Solid angle

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1	2	3	4	5	6	7	8	9	10	0.1331	0.134	0.1354
4	8	12	16	9	2	6	10	14	18	0.1272	0.140	0.1291
9	18	16	3	12	21	8	6	15	24	0.0908	0.089	0.0935
10	9	8	7	6	5	4	3	2	12	0.0895	0.092	0.0872
16	21	4	20	14	8	24	7	12	28	0.0831	0.080	0.0816
25	6	20	12	15	18	10	24	5	30	0.0809	0.083	0.0813
8	5	2	10	7	4	12	9	6	14	0.0627	0.070	0.0579
6	12	7	2	8	14	9	4	10	16	0.0605	0.069	0.0646
20	7	16	14	12	10	8	17	4	24	0.0411	0.033	0.0403
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6	12	7	13	8	3	9	4	10	16	0.0353	0.038	0.0297
4	8	12	5	9	13	6	10	14	18	0.0286	0.022	0.0276
9	18	5	14	12	10	19	6	15	24	0.0236	0.026	0.0250
14	6	20	12	15	18	10	24	16	30	0.0190	0.013	0.0187
18	14	10	6	13	20	16	12	8	26	0.0175	0.015	0.0173
13	15	6	8	10	12	14	5	7	20	0.0158	0.012	0.0162
9	18	16	14	12	10	8	6	15	24	0.0130	0.017	0.0140

# Motivations for studying solid angles

- Draw more accurate conclusions regarding the importance of facets of master cyclic group polyhedra
- Estimate the number of simplices in a triangulation of an  $n$ -cube
- Solid angle sum over rational polytope:  
Ehrhart polynomial and lattice counting
- Approximate the relative volume in many applications:
  - ▶ pixel purity index (PPI) scores
  - ▶ feasibility domain of an ecological community
  - ▶ .....

# Normalized solid angle measure

## Definition (Property)

The **normalized solid angle measure** of a cone  $C \subseteq \mathbb{R}^n$  with respect to  $\mathbb{R}^n$  is defined as

$$\tilde{\Omega}_n(C) = \frac{\text{vol}_{n-1}(C \cap S_{n-1})}{\text{vol}_{n-1}(S_{n-1})} \left( = \frac{\text{vol}_n(C \cap B_n)}{\text{vol}_n(B_n)} = \frac{\int_C f(\mathbf{x}) d\mathbf{x}}{\int_{\mathbb{R}^n} f(\mathbf{x}) d\mathbf{x}} \right),$$

where

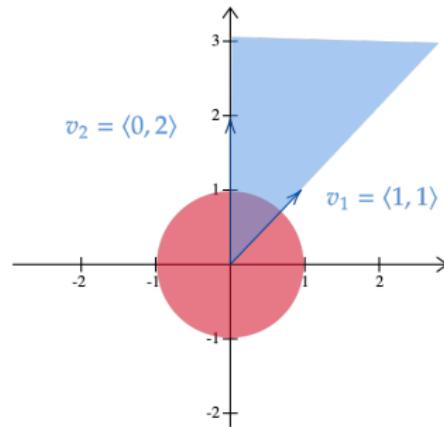
- $\text{vol}_n$  is the usual volume form in  $\mathbb{R}^n$ ,
- $S_{n-1}$  is the unit  $(n-1)$ -sphere (residing in  $\mathbb{R}^n$ ) centered at  $\mathbf{0}$ ,
- $B_n$  is the unit ball in  $\mathbb{R}^n$  centered at  $\mathbf{0}$
- $f: \mathbb{R}^n \rightarrow \mathbb{R}$  is any function that is invariant under rotations around  $\mathbf{0}$ ,  
e.g.  $f = e^{-\|\mathbf{x}\|^2}$

In the following, we consider **simplicial** cones  $C = \mathfrak{c}(\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n)$ .

## Solid angles in $\mathbb{R}^2$

In  $\mathbb{R}^2$ , the normalized solid (or plane) angle measure can be computed via the standard inner product.

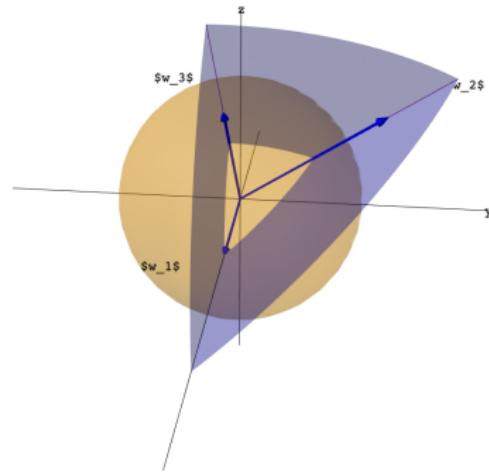
$$\tilde{\Omega}_2(\mathbf{c}(v_1, v_2)) = \frac{1}{2\pi} \cos^{-1} \left( \frac{v_1 \cdot v_2}{\|v_1\| \|v_2\|} \right)$$



$$\tilde{\Omega}_2(\mathbf{c}(v_1, v_2)) = \frac{1}{2\pi} \cos^{-1} \left( \frac{\sqrt{2}}{2} \right) = \frac{1}{8}$$

## Solid angles in $\mathbb{R}^3$

The normalized solid angle measure is the ratio of the area of the spherical triangle formed by the unit vectors to the surface area of the unit sphere.



$$\tilde{\Omega}_3(\mathfrak{c}(\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3)) = \frac{1}{4\pi} \left( 2 \tan^{-1} \left( \frac{|\mathbf{v}_1 \cdot (\mathbf{v}_2 \times \mathbf{v}_3)|}{1 + \mathbf{v}_2 \cdot \mathbf{v}_3 + \mathbf{v}_2 \cdot \mathbf{v}_1 + \mathbf{v}_1 \cdot \mathbf{v}_3} \right) \right).$$

# Solid angles in $\mathbb{R}^n$

$$\tilde{\Omega}_n(C) = \frac{\text{vol}_{n-1}(C \cap S_{n-1})}{\text{vol}_{n-1}(S_{n-1})} = \frac{\text{vol}_n(C \cap B_n)}{\text{vol}_n(B_n)} = \frac{\int_C f(\mathbf{x}) d\mathbf{x}}{\int_{\mathbb{R}^n} f(\mathbf{x}) d\mathbf{x}}$$

- Computing  $\tilde{\Omega}_n(\mathfrak{c}(\mathbf{v}_1, \dots, \mathbf{v}_n))$  amounts to computing the volume of a “spherically faced simplex”
- Closed formula not known
- Probabilistic methods — require large samples
- Numerical integration methods — high in computational cost
- We consider the multivariate power series method independently discovered by [Aomoto, 1977] and [Ribando, 2006]

# Solid angle formula — Ribando's hypergeometric series

## Theorem (Ribando, 2006)

Let  $C \subseteq \mathbb{R}^n$  be the simplicial cone generated by the unit vectors  $\mathbf{v}_1, \dots, \mathbf{v}_n$ . Let  $V \in \mathbb{R}^{n \times n}$  be the matrix whose  $i^{\text{th}}$  column is  $\mathbf{v}_i$ . Let  $\alpha_{ij} = \mathbf{v}_i \cdot \mathbf{v}_j$  for  $1 \leq i, j \leq n$ . Define

$$T_\alpha = \frac{|\det V|}{(4\pi)^{\frac{n}{2}}} \sum_{\mathbf{a} \in \mathbb{N}^{\binom{n}{2}}} \left[ \frac{(-2)^{\sum_{i < j} a_{ij}}}{\prod_{i < j} a_{ij}!} \prod_{i=1}^n \Gamma\left(\frac{1 + \sum_{m \neq i} a_{im}}{2}\right) \right] \alpha^{\mathbf{a}}.$$

Then,  $T_\alpha$  converges absolutely to  $\tilde{\Omega}_n(C)$ , if and only if its associated matrix  $M_n(C)$  is positive definite.

$$M_n(C) = \begin{bmatrix} 1 & -|\mathbf{v}_1 \cdot \mathbf{v}_2| & \cdots & -|\mathbf{v}_1 \cdot \mathbf{v}_n| \\ -|\mathbf{v}_2 \cdot \mathbf{v}_1| & 1 & \cdots & -|\mathbf{v}_2 \cdot \mathbf{v}_n| \\ \vdots & \vdots & \ddots & \vdots \\ -|\mathbf{v}_n \cdot \mathbf{v}_1| & -|\mathbf{v}_n \cdot \mathbf{v}_2| & \cdots & 1 \end{bmatrix}$$

## Ribando's hypergeometric series

$$T_\alpha = \frac{|\det V|}{(4\pi)^{\frac{n}{2}}} \sum_{\mathbf{a} \in \mathbb{N}^{\binom{n}{2}}} \left[ \frac{(-2)^{\sum_{i < j} a_{ij}}}{\prod_{i < j} a_{ij}!} \prod_{i=1}^n \Gamma\left(\frac{1 + \sum_{m \neq i} a_{im}}{2}\right) \right] \alpha^\mathbf{a}.$$

- $\alpha = (\alpha_{12}, \alpha_{13}, \dots, \alpha_{n-1,n})$  is a multivariable in  $\binom{n}{2}$  variables;
- $\mathbf{a} = (a_{12}, a_{13}, \dots, a_{n-1,n})$  is a multiexponent;
- $\alpha^\mathbf{a} := \prod_{i < j} \alpha_{ij}^{a_{ij}}$ ;
- $\sum_{m \neq i} a_{im} = \sum_{j < i} a_{ji} + \sum_{j > i} a_{ij}$ ;
- $\Gamma$  is the Euler-Gamma function.
- $T_\alpha$  is a hypergeometric series as the ratio of the neighboring coefficients is a rational function of the index.

## Issue with $T_\alpha$ : convergence condition not met

Let  $v_1 = [1, 1, 0]$ ,  $v_2 = [1, 0, 1]$ ,  $v_3 = [1, 0, 0]$ , and  $C = \mathfrak{c}(v_1, v_2, v_3)$ .

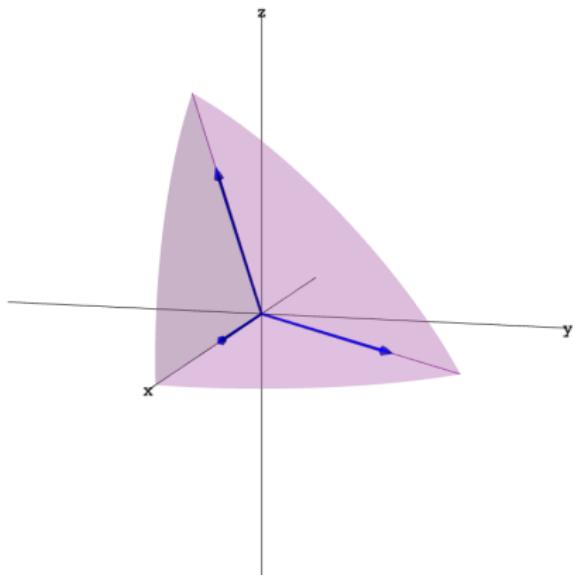
- Scale to unit vectors;

$$\bullet V = \begin{bmatrix} | & | & | \\ v_1 & v_2 & v_3 \\ | & | & | \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 1 \\ \frac{1}{\sqrt{2}} & 0 & 0 \\ 0 & \frac{1}{\sqrt{2}} & 0 \end{bmatrix}$$

$$\bullet \Rightarrow V^t V = \begin{bmatrix} 1 & \frac{1}{2} & \frac{\sqrt{2}}{2} \\ \frac{1}{2} & 1 & \frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & \frac{\sqrt{2}}{2} & 1 \end{bmatrix}$$

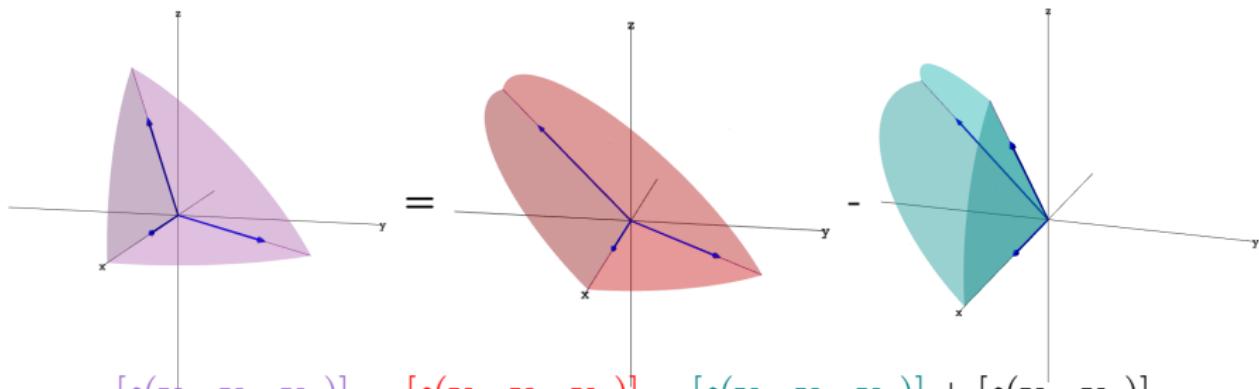
$$\bullet M_3(C) = \begin{bmatrix} 1 & -\frac{1}{2} & -\frac{\sqrt{2}}{2} \\ -\frac{1}{2} & 1 & -\frac{\sqrt{2}}{2} \\ -\frac{\sqrt{2}}{2} & -\frac{\sqrt{2}}{2} & 1 \end{bmatrix}$$

is NOT positive-definite



## Remedy: Cone decomposition

Let  $\mathbf{v}_1 = [1, 1, 0]$ ,  $\mathbf{v}_2 = [1, 0, 1]$ ,  $\mathbf{v}_3 = [1, 0, 0]$ ,  $\mathbf{v}_4 = [0, -1, 1]$ .



$$[\mathfrak{c}(\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3)] = [\mathfrak{c}(\mathbf{v}_1, \mathbf{v}_3, \mathbf{v}_4)] - [\mathfrak{c}(\mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4)] + [\mathfrak{c}(\mathbf{v}_3, \mathbf{v}_4)]$$

$$\tilde{\Omega}_3(\mathfrak{c}(\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3)) = \tilde{\Omega}_3(\mathfrak{c}(\mathbf{v}_1, \mathbf{v}_3, \mathbf{v}_4)) - \tilde{\Omega}_3(\mathfrak{c}(\mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4)) + 0$$

where  $[C]$  denotes the indicator function of the cone  $C$ ,  
and  $\mathfrak{c}(\mathbf{v}_1, \mathbf{v}_3, \mathbf{v}_4)$ ,  $\mathfrak{c}(\mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4)$  have positive-definite associated matrices.

# Decomposition Theorem

## Theorem (Fitisone–Zhou, 2023)

Given linearly independent unit vectors  $\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_n \in \mathbb{R}^n$ , the cone  $\mathfrak{c}(\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_n)$  can be decomposed into a finite family of cones, each of which is either:

- ① a cone of affine dimension less than  $n$ , or
- ② a full-dimensional cone  $\mathfrak{c}(\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n)$  such that

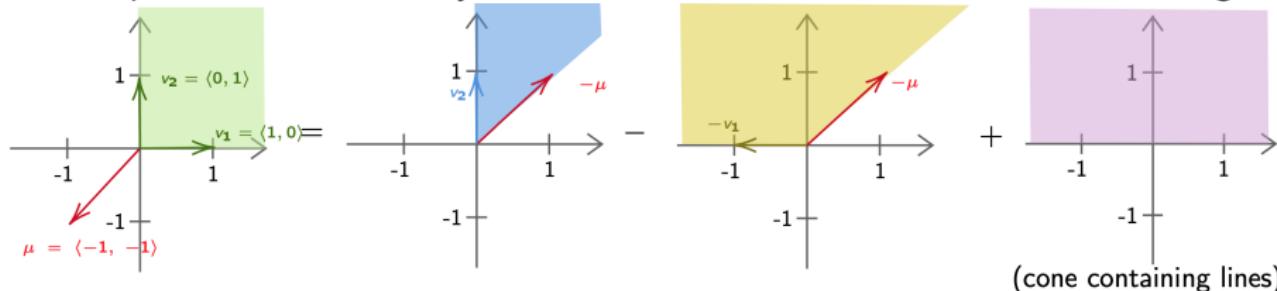
- ③
  - a)  $\|\mathbf{v}_i\| = 1$  for  $i = 1, 2, \dots, n$
  - b)  $\mathbf{v}_n = \mathbf{w}_n$
  - c)  $\langle \mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_{n-1} \rangle = \langle \mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_{n-1} \rangle$
  - d)  $\mathbf{v}_i \cdot \mathbf{v}_j = 0$  for all  $1 \leq i, j \leq n$  such that  $j \neq i, j \neq i \pm 1$ .

### Remarks:

- A cone in ① has solid angle 0.
- Properties ③b and ③c ensure induction works.
- Property ③d ensures  $V^T V$  is tridiagonal, so  $M_n(\mathfrak{c})$  is positive-definite.

# Decomposition Theorem

**Proof idea.** Use induction on dimension. Apply **Brion–Vergne decomposition** with respect to a line carefully chosen, to the dual cone. Then take the dual again.



## Corollary (Fitisone–Zhou, 2023)

The decomposition theorem gives explicitly  $N \leq (n-1)!$  cones  $C_i$  whose  $\tilde{\Omega}_n(C_i)$  can be computed via the power series formula  $T_\alpha$  and the signs  $s_i \in \{\pm 1\}$ , such that

$$\tilde{\Omega}_n(C) = \sum_{i=1}^N s_i \tilde{\Omega}_n(C_i).$$

We can make the cones  $C_i$  to have tridiagonal associated matrices.

Issue with  $T_\alpha$ : too many terms  $\mathbf{a} \in \mathbb{N}^{\binom{n}{2}}$

$$T_\alpha = \frac{|\det V|}{(4\pi)^{\frac{n}{2}}} \sum_{\mathbf{a} \in \mathbb{N}^{\binom{n}{2}}} \left[ \frac{(-2)^{\sum_{i < j} a_{ij}}}{\prod_{i < j} a_{ij}!} \prod_{i=1}^n \Gamma\left(\frac{1 + \sum_{m \neq i} a_{im}}{2}\right) \right] \alpha^\mathbf{a}.$$

Recall property ④ from the theorem: tridiagonal  $V^T V$ !

$$V^T V = \begin{bmatrix} 1 & \beta_1 & 0 & \cdots & 0 \\ \beta_1 & 1 & \beta_2 & \ddots & \vdots \\ 0 & \ddots & \ddots & \ddots & 0 \\ \vdots & & \beta_{n-2} & 1 & \beta_{n-1} \\ 0 & \dots & 0 & \beta_{n-1} & 1 \end{bmatrix}$$

Remedy: series  $T_\alpha$  in  $\binom{n}{2}$  variables simplifies to series in  $(n-1)$  variables

$$T_\beta = \frac{|\det V|}{(4\pi)^{\frac{n}{2}}} \sum_{\mathbf{b} \in \mathbb{N}^{n-1}} A_{\mathbf{b}} \beta^{\mathbf{b}},$$

where for any multiexponent  $\mathbf{b} = (b_1, \dots, b_{n-1})$  in  $\mathbb{N}^{n-1}$ ,

$$A_{\mathbf{b}} := \frac{(-2)^{\sum b_i}}{\prod_{i=1}^{n-1} b_i!} \Gamma\left(\frac{1+b_1}{2}\right) \Gamma\left(\frac{1+b_1+b_2}{2}\right) \cdots \Gamma\left(\frac{1+b_{n-2}+b_{n-1}}{2}\right) \Gamma\left(\frac{1+b_{n-1}}{2}\right).$$

## Eigenvalue and domain of convergence

Suppose  $V^T V$  is tridiagonal.

Suppose the  $\mathbf{v}_i$ 's are **not** all pairwise orthogonal (otherwise  $\tilde{\Omega}_n(C) = \frac{1}{2^n}$ ).

### Proposition

- $M_n(C)$  has the same eigenvalues as  $V^T V$ .
- The smallest eigenvalue  $\lambda_{\min}$  satisfies  $0 < \lambda_{\min} < 1$ .

When does the hypergeometric series converge / diverge?

$$T(\mathbf{x}) = \sum_{\mathbf{b} \in \mathbb{N}^{n-1}} A_{\mathbf{b}} x_1^{b_1} x_2^{b_2} \cdots x_{n-1}^{b_{n-1}}$$

### Proposition

- $(\beta_1, \dots, \beta_{n-1})$  lies in the domain of convergence of  $T(\mathbf{x})$ .
- $\left( \frac{\beta_1}{1-\lambda_{\min}}, \dots, \frac{\beta_{n-1}}{1-\lambda_{\min}} \right)$  lies on the boundary of convergence domain.

## Asymptotic truncation error of the series

Truncating the series in partial degrees  $(N_1, \dots, N_{n-1})$ ,  
the error term is bounded by

$$E(N_1, \dots, N_{n-1}) = \sum_{\mathbf{b} \in B} |A_{\mathbf{b}} \beta^{\mathbf{b}}|,$$

where  $B = \{\mathbf{b} \in \mathbb{N}^{n-1} \mid b_i \geq N_i \text{ for at least one } i\}$ .

We show the asymptotic decay of  $E(N_1, \dots, N_{n-1})$  in relation to  $1 - \lambda_{\min}$ .

### Theorem (Fitisone–Zhou, 2023)

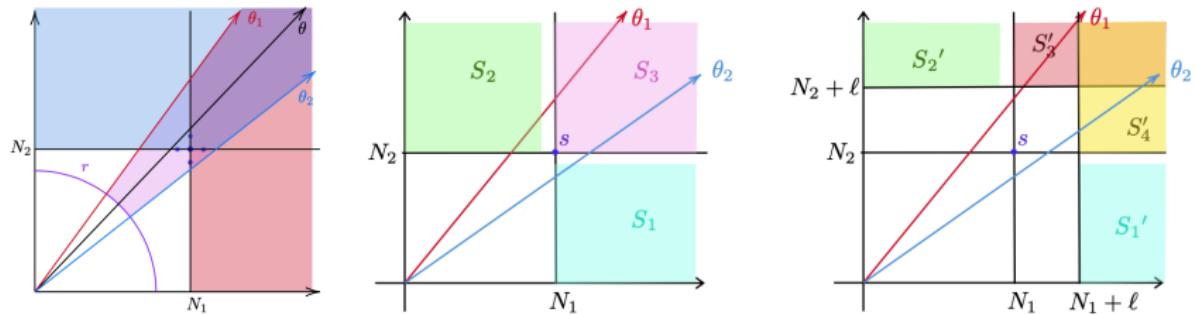
For any  $\rho$  such that  $1 - \lambda_{\min} < \rho < 1$ , there exist partial degrees  $N_1, \dots, N_{n-1}$  such that for any integer  $\ell \geq 1$ , we have

$$E(N_1 + \ell, \dots, N_{n-1} + \ell) \leq \rho^\ell E(N_1, \dots, N_{n-1}).$$

# Asymptotic truncation error proof

Proof idea (for case  $n = 3$ ).

- Since  $\left(\frac{\beta_1}{1-\lambda_{\min}}, \frac{\beta_2}{1-\lambda_{\min}}\right)$  lies on the boundary of convergence domain, there exist  $x_1, x_2 \in \mathbb{R}_+$  such that  $\frac{|\beta_i|}{1-\lambda_{\min}} = \frac{1}{|\Psi_i(x_1, x_2)|}$  for  $i = 1, 2$ ,  
 $\Psi_i(\mathbf{b}) = \lim_{t \rightarrow \infty} \frac{A_{t\mathbf{b}+\mathbf{e}_i}}{A_{t\mathbf{b}}}$  rational and homogeneous of degree zero.
- $\frac{|A_{b_1+1, b_2} \beta_1^{b_1+1} \beta_2^{b_2}|}{|A_{b_1, b_2} \beta_1^{b_1} \beta_2^{b_2}|}, \frac{|A_{b_1, b_2+1} \beta_1^{b_1} \beta_2^{b_2+1}|}{|A_{b_1, b_2} \beta_1^{b_1} \beta_2^{b_2}|} \leq (1 - \lambda_{\min})(1 + \epsilon) =: \mu$
- $E(N_1 + \ell, N_2 + \ell) \leq S'_1 + \cdots + S'_4 \leq \mu^\ell (1 + \epsilon)^\ell (S_1 + S_2 + S_3) \leq \rho^\ell E(N_1, N_2)$



# Thank you!

- **Manuscript:**

A. Fitison and Y. Zhou.

Solid angle measure of polyhedral cones

eprint arXiv:2304.11102 [math.MG], 2023

- **SageMath code:**

<https://github.com/yuan-zhou/solid-angle-code>