Parallelism in algebraic geometry Examples with Singular and GPI-Space

Anne Frühbis-Krüger joint work with Janko Böhm SFB/TRR 195 and with Mirko Rahn, Fraunhofer ITWM, Kaiserslautern (and many others from the SINGULAR and GPI-Space Teams)

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parallel algorithms

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Parallel Computing n brief

GPI-Space

Sample application: Smoothness Test

Why parallel?

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Why parallel?

state of the art hardware:

- multicore computers
- high performance clusters

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success stories:

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numerical analysis

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practical drawback:

management of distribution of resources and data

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ideal speed-up:

linear in the number of cores

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ideal speed-up: linear in the number of cores

limiting factors in reality:

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ideal speed-up: linear in the number of cores

limiting factors in reality:

longest non-parallelizable part (critical chain)

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ideal speed-up: linear in the number of cores

limiting factors in reality:

- Iongest non-parallelizable part (critical chain)
- communication overhead

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 fine grained (synchronize/communicate data in short intervalls) parallel algorithms

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- coarse grained

(occasionally synchronize/communicate data)

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kinds of parallelism:

- fine grained (synchronize/communicate data in short intervalls)
- coarse grained (occasionally synchronize/communicate data)
- embarrassing (nearly no communication between tasks)

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Sample application: Smoothness Test

Traditionally 3 main approaches:

- 1. Parallelization on the level of arithmetic
 - \longrightarrow fine-grained/shared memory,
 - \longrightarrow limited to one machine

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Traditionally 3 main approaches:

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- 2. Embarassing parallelism of zero-dimensional objects → scales up to number of instances

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 \longrightarrow basically borrowed idea from number theory

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More recently: inherent natural parallelism of a setting

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More recently: inherent natural parallelism of a setting e.g.:

- gfan
- talk of Lars Kastner using polymake and MPTOPCOM

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Tasks in parallel setting (classically):

- $1. \ {\rm design} \ {\rm a} \ {\rm mathematical} \ {\rm algorithm}$
- 2. implement mathematical algorithm

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Is each of us an expert in all of these tasks?

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Using a workflow management system:

concentrate on 1 and 2

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Success stories along these lines

 ${\sf Fan}/{\sf Graph}{\text -}{\sf Traversals}{:}$

- ▶ GIT-fan (Böhm, FK, Rahn, Reinbold):
 - Mori chamber decomposition of cone of movable divisors of M_{0.6}
 - 12,5 minutes on 640 cores

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Coverings:

- smoothness test (Böhm, Decker FK, Rahn, Ristau, Pfreundt) – see below
- ▶ desing. of 2-dim. schemes/ℤ (FK, Gaube, Schober, Ristau)
- order zeta functions (FK, Maglione, Schober, Voll)

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Sample application: Smoothness Test

GPI-Space (Fraunhofer ITWM)

- originally designed with applications in finite element methods in mind
- separation of coordination and computation layers

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biggest advantage:

Parallelisation without modification to the backend

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Sample application: Smoothness Test

Petri nets

Petri net:



directed graph

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Sample application: Smoothness Test

Petri nets

Petri net:



- directed graph
- 2 kinds of vertices: places (circle) and transitions (box)
- places hold marked tokens
- transitions contain functional units

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Sample application: Smoothness Test
Petri net (running on a single core):



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Sample application: Smoothness Test

First for plane curves:



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Sample application: Smoothness Test

First for plane curves:



$$V(f)$$
 singular at $p \in \mathbb{C}^2 \iff$ not a unique tangent direction at p

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$$\Leftrightarrow \quad \tfrac{\partial f}{\partial x_1}(p) = 0 = \tfrac{\partial f}{\partial x_2}(p)$$

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 $\label{eq:constraint} \Leftrightarrow \quad \mbox{Jacobian matrix } J \mbox{ of } f \\ \mbox{ at } p \mbox{ of rank } < 1 \\ \end{tabular}$

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Sample application: Smoothness Test

Jacobian Criterion

Let all components of $V(f_1, \ldots, f_m)$ be of dimension d

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Sample application: Smoothness Test

Jacobian Criterion

Let all components of $V(f_1, \ldots, f_m)$ be of dimension d

Then: $V(f_1, \ldots, f_m)$ sing. in $p \in \mathbb{C}^n \iff \dim_{\mathbb{C}} T_p(X) > d$ parallel algorithms

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 $\Leftrightarrow \quad \text{rank of Jacobian matrix} \\ J \text{ of } (f_1 \dots, f_m) \text{ at } p \\ < n - d$

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singular locus:

 $Sing(X) := \{ p \in X \mid X \text{ singular at } p \}$

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singular locus:

$$\begin{aligned} \mathsf{Sing}(X) &:= \{ p \in X \mid X \text{ singular at } p \} \\ &= V(f_1, \dots, f_m \text{ and } (n - \mathsf{dim}(X)) - \\ & \text{minors of Jacobian matrix } J \end{aligned}$$

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Sample application: Smoothness Test

A real-life example – the problem

numerical Godeaux-Surface (from current research/ surface with prescribed properties):

13 variables, dimension 2, 22 polynomials \implies approx. 55 Mio. minors

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Jacobian Criterion tests : $Sing(X) == \emptyset$?

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Jacobian Criterion tests : $Sing(X) == \emptyset$?

- that is: $1 \in I + \langle (n-d) \text{ minors von } J \rangle$?
- Groebner Basis computations: all minors as input (size of pairset!)
- certificate of smoothness or singularity after all computations

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Sample application: Smoothness Test

$\ensuremath{\mathbb{K}}$ algebraically closed field

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Sample application: Smoothness Test

 $\ensuremath{\mathbb{K}}$ algebraically closed field

$$f_1, \ldots, f_r \in \mathbb{K}[x_1, \ldots, x_n]$$
 and $X = V(f_1, \ldots, f_r)$

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Sample application: Smoothness Test

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 and $X = V(f_1, \ldots, f_r)$
 $I_X = I(X) \subset \mathbb{K}[x_1, \ldots, x_n]$ vanishing ideal

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Sample application: Smoothness Test

 $\ensuremath{\mathbb{K}}$ algebraically closed field

$$egin{aligned} f_1,\ldots,f_r \in \mathbb{K}[x_1,\ldots,x_n] ext{ and } X &= V(f_1,\ldots,f_r) \ I_X &= I(X) \subset \mathbb{K}[x_1,\ldots,x_n] ext{ vanishing ideal} \end{aligned}$$

Goal:

Test whether X is singular without computation of singular locus!

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Sample application: Smoothness Test

Hironaka(1964):

resolution of singularities in characteristic zero

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Sample application: Smoothness Test

Hironaka(1964):

resolution of singularities in characteristic zero

- finitely many blow-ups in 'good' centers
- termination criterion without Jacobian criterion

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Sample application: Smoothness Test

Hironaka(1964):

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Hironaka's measure for distance to smoothness at *p*:

$$\nu^*(X,p) := (\operatorname{ord}_p(g_1), \ldots, \operatorname{ord}_p(g_s))$$

where

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▶ g₁,..., g_s minimal standard basis von I_XO_{Aⁿ_K,p} w.r.t. local degree ordering, sorted by increasing order. parallel algorithms

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•
$$\operatorname{ord}_{p}(g_{i}) = \max\{k \in \mathbb{Z} \mid g_{i} \in \mathfrak{m}_{\mathbb{A}_{K}^{n},p}^{k}\}$$

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Sample application: Smoothness Test

defined a moment ago: $\nu^*(X, p) := (\operatorname{ord}_p(g_1), \dots, \operatorname{ord}_p(g_s))$

Lemma (Hironaka)

X singular at p

$$\iff \nu^*(X,p) >_{lex} \underbrace{(1,\ldots,1)}_{n-\dim(X)}$$

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practical problem:

standard basis locally at each point impossible

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Sample application: Smoothness Test

First entry of ν^* : order of ideal at p

 $\operatorname{ord}_p(I) := \min \{ \operatorname{ord}_p(h) \mid h \in I \}$

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First entry of ν^* : order of ideal at p

$$\operatorname{ord}_p(I) := \min \{ \operatorname{ord}_p(h) \mid h \in I \}$$

We know:

 $\operatorname{ord}_p(I) = 1 \implies \exists h \in I : \operatorname{ord}_p(h) = 1$



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We know:

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$$\implies$$
 • first entry of $\nu^*(X, p)$ is 1

• V(h) smooth hypersurface locally at p $X \subset V(h)$ parallel algorithms

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First entry of ν^* : order of ideal at p

$$\operatorname{ord}_{p}(I) := \min \{ \operatorname{ord}_{p}(h) \mid h \in I \}$$

We know:

$$\operatorname{ord}_p(I) = 1 \implies \exists h \in I : \operatorname{ord}_p(h) = 1$$

$$\implies \quad \bullet \text{ first entry of } \nu^*(X, p) \text{ is } 1$$
$$\bullet V(h) \text{ smooth hypersurface locally at } p$$
$$X \subset V(h)$$

locus of order ≥ 2 of X:

$$\Delta(I_x) = V(\langle f_1, \ldots, f_s, \frac{\partial f_i}{\partial x_j} \mid 1 \le i \le s, 1 \le j \le n \rangle)$$

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Sample application: Smoothness Test

Local System of Parameters

we have seen:

 $\operatorname{ord}_p(I) = 1 \Longrightarrow \exists h \in I : V(h) \text{ smooth and } X \subset V(h) \text{ near } p$

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Choose V(h) locally at p as new ambient space

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Technical Side Timings links

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Choose V(h) locally at p as new ambient space \implies no longer working in $\mathbb{K}[\underline{x}]$, parallel algorithms

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Parallel Computing n brief

GPI-Space

Sample application: Smoothness Test
Local System of Parameters

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Transfer to $(\mathbb{K}[x_1,\ldots,x_n]/\langle h \rangle)_g$ possible

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Sample application: Smoothness Test

Subsequent Entry of ν^*

Sketch of approach:

- Choose appropriate V(h) und D(g) covering X (g suitably chosen derivative of h)
- on each D(g) consider: $X \cap D(g) \subset V(h) \cap D(g)$
- repeat previous construction (slightly modified):
 - dim(V(h)) = n 1, drop in codimension
 - derivatives w.r.t. local systems of parameters in V(h) ∩ D(g)
 - ▶ provides covering of $X \cap D(g)$ by new $V(h, h_{neu}) \cap D(g_{neu})$

iterate

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Hironaka's ν* Technical Side Timings links

Observation:

number of charts increases, while codimension drops

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Sample application: Smoothness Test

Observation:

- number of charts increases, while codimension drops
- sufficiently small codimension makes Jacobian criterion feasable

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Sample application: Smoothness Test

Observation:

- number of charts increases, while codimension drops
- sufficiently small codimension makes Jacobian criterion feasable
- in practice: hybrid approach using descent in ambient space and Jacobian criterion

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Sample application: Smoothness Test

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- number of charts increases, while codimension drops
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- in practice: hybrid approach using descent in ambient space and Jacobian criterion

Challenges:

- choose large neighbourhoods for new ambient space
- keep number of charts low/use easily computable charts
- consistent choice of local system of parameters
- derivatives w.r.t. a system of parameters

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Sample application: Smoothness Test

Challenges call for parallel approach:

choose large neighbourhoods for new ambient space
 ⇒ check whether everything is covered

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Sample application: Smoothness Test

The problem Hironaka's ν^*

Challenges call for parallel approach:

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Sample application: Smoothness Test

The problem Hironaka's ν^*

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 potentially expensive computations

We really need a powerful parallelization environment:

- with good scheduling
- with good resource management

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Sample application: Smoothness Test

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The problem Hironaka's ν^*

Timings links

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We really need a powerful parallelization environment:

- with good scheduling
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- without too much technical overhead
- robust against huge variations in computing time and size

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Sample application: Smoothness Test

The problem Hironaka's u^*

The Algorithm as a Petri-Net



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A screenshot

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Campedelli-Fläche – Timings



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The problem Hironaka's ν^* Technical Side

Timings links

Campedelli-Fläche – Speed-Up versus cores



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Links and References

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Thank you!